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7/25/68

A GPSS II SIMULATION MODEL OF A  
BRIGADE RIVER CROSSING OPERATION

A THESIS

Presented to

The Faculty of the Graduate Division

by

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BRIGADE RIVER CROSSING OPERATION

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## TABLE OF CONTENTS

	Page
ACKNOWLEDGMENTS. . . . .	ii
LIST OF TABLES . . . . .	v
LIST OF ILLUSTRATIONS. . . . .	vi
GLOSSARY . . . . .	viii
SUMMARY. . . . .	x
Chapter	
I. INTRODUCTION. . . . .	1
Statement of the Problem and Objectives	
Background	
Current Limitations	
Purpose of Research	
Methodology, Scope, and Limitations	
Literature Survey	
II. A TYPE SUBMODEL . . . . .	16
General	
Tactical Unit Generator Section	
Nonamphibious Vehicle Section	
Amphibious Vehicle Section	
Inherent Quantitative Data Availability	
III. THE BASE MODEL. . . . .	36
General	
Tactical Unit Generator Section	
Main Movement Section	
Southern Amphibious Vehicle Flow	
Southern Nonamphibious Vehicle Flow	
Far Bank Nonamphibious Vehicle Flow	
IV. EXPERIMENTATION . . . . .	57
General	
Initial Validation Runs	

## TABLE OF CONTENTS (Concluded)

Chapter	Page
Initial Discussion of Results	
Experimental Runs	
River Crossing Time	
Crossing Area Vehicle Density	
Mean Crossing Area Transit Time	
Near Bank Dispersal Area Delays	
Discussion of Results	
V. CONCLUSIONS AND RECOMMENDATIONS . . . . .	66
General Comments	
Conclusions	
Recommendations	
APPENDICES . . . . .	69
A. RIVER CROSSING EQUIPMENT CHARACTERISTICS. . . . .	70
B. BASE MODEL BRIGADE TASK ORGANIZATION. . . . .	72
C. BASE MODEL COMPUTER LISTING . . . . .	74
D. BASE MODEL REPRESENTATIVE GPSS II FLOW DIAGRAM. . . . .	92
E. GPSS II SIMULATION LANGUAGE . . . . .	104
F. REPRESENTATIVE MILITARY SYMBOLS . . . . .	107
BIBLIOGRAPHY . . . . .	109

## LIST OF TABLES

Table		Page
1.	Mechanized Division River Crossing Equipment Options . . . . .	4
2.	Typical Vehicle Crossing Option Chart . . . . .	5
3.	Simulation Model Vehicle Types. . . . .	18
4.	Tactical Unit Identification Codes. . . . .	40
5.	Southern River Crossing Equipment Opening Times . . . . .	51
6.	Comparison of Means . . . . .	58
7.	Ninety-five Percent Confidence Intervals for Selected Sample Means . . . . .	58
8.	Experimental Runs . . . . .	60
9.	River Crossing Time . . . . .	61
10.	Crossing Area Vehicle Density . . . . .	62
11.	Mean Crossing Area Transit Times. . . . .	63
12.	Nonamphibious Vehicle Mean Time Delay in Dispersal Areas Near Bank. . . . .	64
13.	Brigade Task Organization and Vehicle Types . . . . .	72
14.	Base Model Task Organization. . . . .	73
15.	GPSS II System Representations. . . . .	105

## LIST OF ILLUSTRATIONS

Figure		Page
1.	System Model Boundaries (Brigade Zone of Action) . . . . .	7
2.	Submodel General Flow Diagram . . . . .	17
3.	Battalion Axis of Advance . . . . .	19
4.	Battalion Type Deployment Configuration . . . . .	19
5.	GPSS II Battalion Generator Flow Diagram. . . . .	21
6.	Nonamphibious Vehicle Flow Diagram. . . . .	23
7.	GPSS II Nonamphibious Vehicle Flow Diagram. . . . .	25
8.	GPSS II CANB Time Function. . . . .	26
9.	GPSS II River Crossing Transit Time Function. . . . .	26
10.	Superimposition of Figures 6 and 7. . . . .	28
11.	GPSS II Amphibious Vehicle Flow Diagram . . . . .	30
12.	Amphibious Vehicle Flow Diagram . . . . .	31
13.	GPSS II Crossing Site Alignment Function. . . . .	33
14.	GPSS II River Transit Time Functions. . . . .	33
15.	Base Model Tactical Unit Deployment Configuration . . . . .	37
16.	Base Model General Flow Diagram . . . . .	38
17.	Main Movement Section General Flow Diagram. . . . .	42
18.	Southern Amphibious Vehicle Flow. . . . .	44
19.	GPSS II Phase Line Transit Time Function. . . . .	47
20.	Southern Nonamphibious Vehicle Flow . . . . .	49



## LIST OF ILLUSTRATIONS (Concluded)

Figure	Page
21. Southern Nonamphibious Vehicle Flow, CAFB . . . . .	53
22. TF 1-78 Infantry Generator. . . . .	93
24. GPSS II Southern Nonamphibious Vehicle Flow, CANB. . . . .	96
25. GPSS II Southern Amphibious Vehicle Flow, CAFB. . . . .	100
26. GPSS II Southern Nonamphibious Vehicle Flow, CAFB. . . . .	102
27. Representative Military Symbols . . . . .	108

## GLOSSARY

**BATTALION:** A unit composed of a headquarters element and two or more companies (Infantry) or batteries (Artillery) (6).

**BRIGADE:** A unit which is smaller than a division and to which battalions and smaller units are attached as required for operations (6).

**COMPANY:** The basic tactical and administrative unit in most arms and services of the Army. A company is on a command level below battalion and is equivalent to a battery of artillery (6).

**CROSSING AREAS:** Crossing areas are designated to facilitate the flow of troops and equipment across the river obstacle by surface means. The crossing area includes the crossing area near bank (CANB), the crossing area far bank (CAFB), the crossing sites, the space required for bridge and raft construction and operation, and the area required for convoy dispersal (9).

**DISPERSAL AREAS:** Dispersal areas are designated within the crossing area along roads to the bridge and raft sites. They provide space where vehicles can be halted and dispersed to avoid congestion on access roads to the sites when the vehicle flow has been disrupted or when there is a reduction in the capacity of the bridges, rafts, or ferries (9).

**DIVISION:** The division is a tactical unit or formation which combines in itself the necessary arms and services required for sustained combat. The division is larger than a brigade and smaller than a corps (9).

**ENGINEER EQUIPMENT PARKS:** Engineer Equipment Parks are areas reserved near bridge and raft sites for the assembly of engineer equipment required for the construction of the crossing equipment (9).

**LINE OF DEPARTURE:** The Line of Departure (LD) is a line ordinarily located on or behind the last available terrain mask which can be reached without exposure to hostile observation and small arms fire. It is designated to coordinate the departure of an attack (6).

**PHASE LINE:** The Phase Line (PL) is a line normally located on or near a terrain feature extending across the zone of action. The Phase Line is used to control and coordinate military operations (6).

**ZONE OF ACTION:** The Zone of Action is a subdivision of a larger area. Responsibility for the Zone of Action is assigned to a specific unit for offensive operations (6).

## SUMMARY

The brigade tactical river crossing is a complex flow problem involving the movement of troops, equipment, and vehicles from one side of a river obstacle to the other. Present planning methodologies base the rate of vehicle flow on the capabilities of the river crossing equipment allocated to the brigade. This GPSS II simulation model, programmed for the UNIVAC 1108 computer, simulates a specific brigade river crossing operation which reflects current unclassified U. S. Army planning doctrine.

The model structure and computer simulation run output indicate that simulation methodology provides considerably more parameter availability and quantitative data for analysis than does current methodology.

The GPSS II flow diagram of the base model is very analogous to the traditional military symbology which is used by staff officers to depict the operation.

Experimental results indicate the importance of the Mobile Assault Bridge ferries as compared to the M4T6 rafts and Light Tactical Rafts. The results also suggest further experimentation should be conducted to determine the tactical formation required to achieve acceptable vehicle densities in the crossing areas.

## CHAPTER I

### INTRODUCTION

#### Statement of the Problem and Objectives

This thesis concerns the formulation of a realistically structured GPSS II simulation model of a tactical military operation -- a Mechanized Infantry Brigade river crossing. The basic model is a synthesis of various unit sub-models, each depicting a sub-organization of the brigade. The primary objective, therefore, is the model formulation and validation. Ancillary objectives are to determine the adequacy of current U. S. Army river crossing doctrine and to demonstrate, by the model structure and simulation language, how this specific model might be used in U. S. Army service schools as an educational device to promote a better understanding of simulation. Specifically, it will demonstrate how a unit staff officer can, through simulation, clarify and depict courses of action prior to making a staff recommendation.

#### Background

Despite recent technological advances in helicopter design and capabilities, the majority of a military organization's surface vehicles are still used on the ground during tactical movements. The primary combat vehicles of the mechanized division and brigade are the main battle tank and the armored personnel carrier. Both possess loaded tactical weights (105,000 and 22,495 lbs, respectively) exceeding the lift capa-

bilities of the largest helicopters, the CH-47A and CH54A (18,900 and 18,565 lbs, respectively), in the Army inventory (32). Although the helicopter has significantly freed the infantryman from his traditional two-dimensional battlefield, it has not yet provided a means to transport a mechanized unit's primary fighting vehicles about the battlefield. Thus, the military operation, the tactical river crossing, still exists as a perplexing tactical problem; a complicated maneuver which is, by its nature, very dangerous when executed in the face of a determined defender and potentially vulnerable under any circumstance.

Current U. S. Army doctrine divides river crossing into two types, hasty and deliberate. A hasty crossing is one which can be implemented as an extension or continuation of an attack. It is characterized by speed, surprise, and a minimum concentration of personnel and equipment. A deliberate crossing entails a detailed concentration of supplies, equipment, and personnel, and the extensive use of specialized river crossing equipment. It is conducted when forces must resume the attack after securing the near bank of a river, or whenever a hasty crossing fails. All crossings involve detailed planning to ensure troop dispersion in the crossing area, rapid crossing operations, and the maximum utilization of all crossing systems. The river crossing plan, when applicable to the nuclear environment, should provide for multiple crossing on a wide front with minimum delay and buildup of supplies and equipment (8). The purpose of all river crossing operations is to move an attacking force across the river obstacle in such a manner that the force may continue its attack or seize objectives which will protect subsequent crossings.

The movement across the obstacle should be conducted as rapidly and as efficiently as possible (9).

Planning a river crossing is complicated and time consuming. The division is the smallest tactical organization possessing organic bridging and rafting equipment. Even so, this equipment is generally insufficient and additional river crossing equipment must be made available to the division from higher organizations such as the corps (7). Planning a river crossing implies selecting the best combination of crossing equipment such that the momentum of the advance, the tactical disposition, and the tactical integrity of the force will be maintained. In addition to the organic equipment in the division, the additional equipment furnished by corps and army engineer groups can also be used in many configurations. The staff officer's task is to recommend the most efficient way in which this equipment should be used. In other words, he must determine what portion should be used for rafts, bridges, or a combination of the two. The mechanized division is equipped with river crossing equipment listed in Table 1 (31).

Based on the commander's policies and the knowledge of the staff regarding the tactical situation, the staff must formulate crossing plan options which are within the capabilities of the available equipment and then compare these options against the available crossing equipment (9) to determine how each option provides for crossing a given number of vehicles. Some of the factors considered during this evaluation are:

1. Adequate crossing volume to insure mission accomplishment.
2. Vulnerability of crossing equipment to enemy attack.

Table 1. Mechanized Division River Crossing Equipment Options

Equipment	Options	Weight Class
Mobile Assault Bridge (MAB)	1-144m bridge or 2-80m bridges or 4-48m ferries	Class 60
M4T6 Bridging	1-170m bridge or 8-rafts	Class 50
Class 60 Bridging	1-165m bridge or 4-5 rafts	Class 60
Light Tactical Rafts (LTR)	2-LTR's or 1-31m bridge	Class 12

---

Note: Divisional engineers are equipped with either MAB's or a combination of M4T6 and class 60 bridging. The weight class number represents the loading effect of the vehicle. The effect depends on the vehicle weight, axles, and the rate of movement of the vehicle.

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3. Congestion in the crossing area which presents the enemy a lucrative target.

4. Efficient utilization of crossing equipment.

A method used to compare crossing plan options is to list, by equipment type, various crossing capabilities and then to express the crossing capability rate in vehicles per unit time. The total number of vehicles is then divided by this rate to get the total crossing time. An example of a typical crossing option is listed in Table 2.

Table 2. Typical Vehicle Crossing Option Chart

Option	Equipment	Rate	Class	Cumulative Vehicles Crossed			
				H+1	H+2	H+3	...
A	8-LTR	7v/r/hr	12	0	56	112	
	10-M4T6 rafts	7	55	0	70	140	
	4-MAB ferries	14	60	0	56	112	
	0-M4T6 bridges						
Total Vehicles Crossed				0	182	364	...
B	8-LTR	7	12	0	56	112	
	5-M4T6 rafts	7	55	0	35	70	
	4-MAB ferries	14	60	0	56	112	
	1-M4T6 bridge	400	60	0	0	0	(Opens H+7)
Total Vehicles Crossed				0	147	295	...

Note: MAB ferries and M4T6 rafts may carry two and one Class 55 vehicles, respectively, or four and two Class 12 vehicles per raft per trip. All crossing equipment opens at H+1 hours.

This crossing option chart does not depict all options, but does represent an initial step in a staff officer's river crossing plan formulation methodology. Subsequent development and analysis of various options eventually enable the staff officer to recommend a specific option to the commander.

#### Current Limitations

This "traditional" methodology, used in the field and service schools, is essentially a simple mathematical solution to a rather complicated queueing flow problem. One can visualize a tactical unit river crossing operation as a bounded physical system as represented in Figure 1. Unit transactions, which represent vehicles, flow through the system in a manner prescribed by the tactical deployment of units and their rate of movement. This flow is either interrupted or modified by the facilities, in this instance river crossing equipment available to permit the transactions to flow across the river obstacle. Although the "traditional" methodology appears to provide a solution to this problem, as demonstrated historically by actual operations, it does not provide the formulator an analogue of the system. The system performance, measured by such quantitative factors as vehicle density in the crossing area, queue sizes at crossing sites and dispersal areas, and river crossing equipment utilization, cannot be demonstrated by the present methodology in sufficient detail such that a quantitative analysis of each river crossing option is permissible. At best, it would appear that a staff officer can merely state which option may provide an optimum rate of flow.

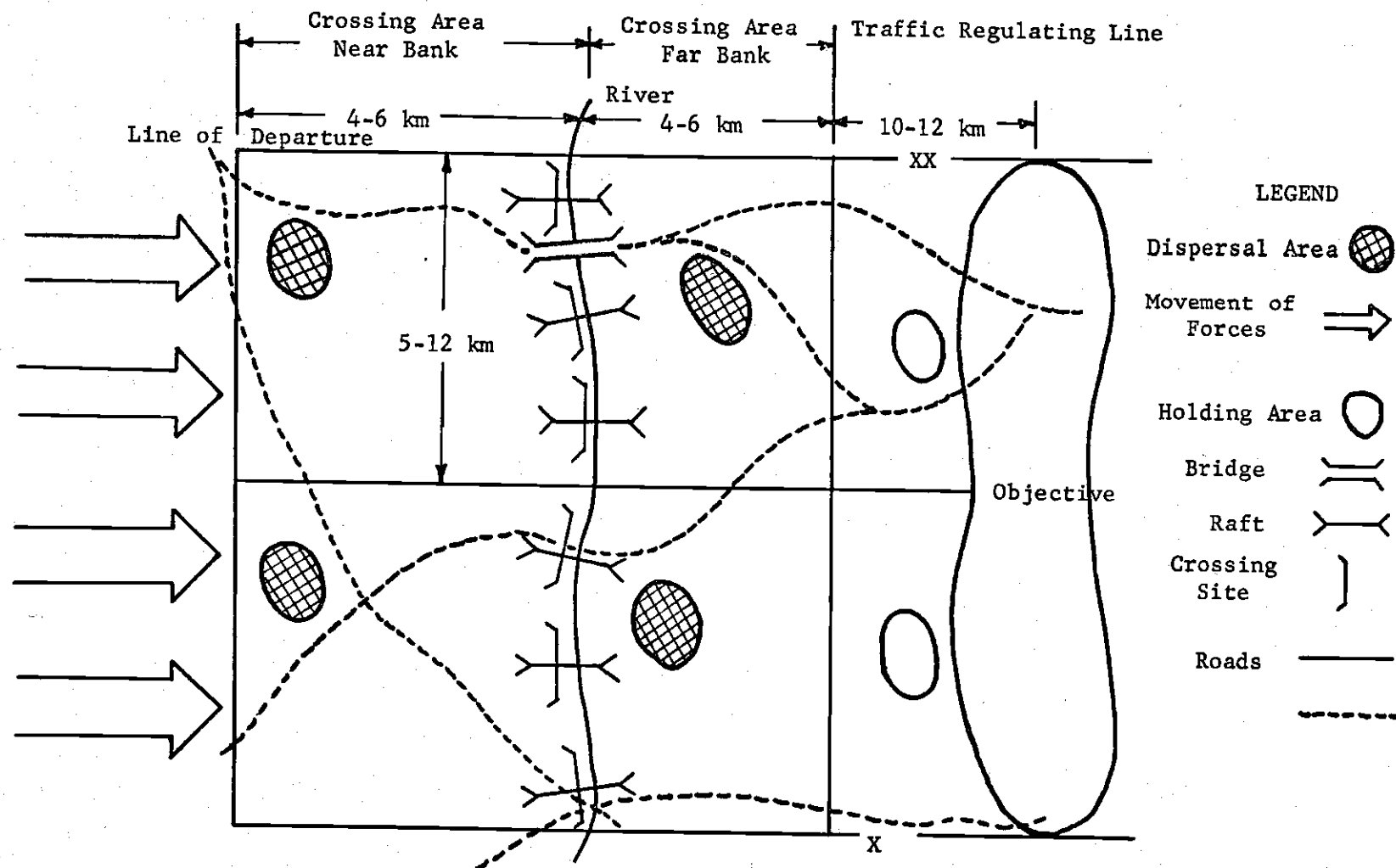


Figure 1. System Model Boundaries (Brigade Zone of Action)

### Purpose of Research

The limitations of the current river crossing planning methodology can be lessened, at least in the service school environment, by a new methodological approach to the problem. It is the purpose of this research to demonstrate how a simulation model of a mechanized brigade river crossing operation can provide the staff officer a tool by which he can quantitatively analyze a crossing option. The simulation model, written in GPSS II, will realistically depict the flow within the brigade zone of action and will provide the user considerably more information than is presently available by "traditional" methodology. It is felt that the model will also enable potential users to gain an appreciation of simulation and will provide an incentive for increased demand at lower echelons within the Army for this Operations Research tool.

### Methodology, Scope, and Limitations

One of the initial obstacles this research intends to overcome is the general tendency of managers to dismiss the fact that simulation is a valuable planning tool. As mentioned in (27), several reasons exist for this difficulty.

1. Managers (Chiefs of Staff and Commanders) do not understand the simulation.
2. A manager might perceive the simulation as a threat to his job security.
3. Simulation results are not applicable to the problem at hand.
4. A manager does not have time to listen to the simulation analyst's story.

5. The simulation may not represent the problem in a recognizable way to the manager.

One possible way to alleviate these difficulties is the formulation of a simulation model which is analogous to the real world system. Another way to eliminate such difficulties is the formulation and programming of the model by the user. This technique solves the user-programmer interface communications gap, but it also assumes that the user can program (23). The use of a simulation programming language such as GPSS greatly enhances this approach. Simulation programming languages such as GPSS have contributed to the success of simulation techniques by their programming convenience, concept articulation, and their ability to be understood by managers (17).

Schmidt and Taylor (24) state that the problem of constructing a simulation model of a real world system in FORTRAN, or any general purpose language, requires a great deal of effort and can become an arduous task. Special purpose languages were therefore developed to eliminate a major portion of this problem. GPSS, a transaction flow language, is especially appropriate for a simulation model representing a river crossing operation. It was written for users with little or no programming experience (15) and the flow charts used to formulate the program are, with little explanation, very understandable to uninitiated or skeptical managers.

The system to be modeled is based on the 1968-69 U. S. Army Command and General Staff College (CGSC) instructional problem M6440, Deliberate and Hasty River Crossings, and the U. S. Army Infantry School (USAIS) problem BQC 74/1, River Crossing Operations, 1970-71. Both problems discuss

and demonstrate the "traditional" methodology in formulating the river crossing plans. As the most detailed data are contained in the CGSC problem, it was used in this work as the model base for validation. Specific subunit employment for all units below brigade in size, such as battalions, is based on doctrine used by the USAIS problem. The model boundaries, represented in Figure 1, depict one of the two committed brigades discussed in the CGSC division problem. The base model, a synthesis of the unit submodels, represents one of the two committed brigades discussed in the CGSC problem and is depicted in Figure 1. Each submodel represents a specific unit as deployed in the CGSC problem and as it reflects U. S. Army river crossing doctrine. The following assumptions have been made:

1. The brigade is committed in a conventional, general war environment and is conducting a hasty river crossing.
2. Enemy contact is light and intermittent.
3. Rates of movement are based on day movement through open terrain.
4. Battalion-sized units occupy and are uniformly distributed throughout a square kilometer area.
5. River crossing equipment capabilities are based on those used in the CGSC reference instructional problem (29). The following general assumption has been made.

Vehicle and river crossing equipment technical data, tactical unit speeds, and deployment configurations are realistic insofar as they are portrayed in U. S. Army training and war game publications (30,10,33,31, 29,9,32).

The general method of procedure in this research was accomplished in the following stages.

1. An analysis of the system, an establishment of boundaries, and a detailed assignment of type vehicles to specific units was accomplished.

2. A general schematic of the flow, similar to Figure 1, was constructed and a representative subunit's flow was formulated in terms of a GPSS flow chart. This subunit flow was then simulated on the computer and results validated by data contained in the CGSC base problem.

3. The base model, structured in a manner analogous to the real world system, was formulated, translated into a GPSS flow diagram, and subsequently validated.

4. An analysis of results determined the useful data obtained from the base model. These data were then compared to the data presently available from the traditional analytical procedures. The analysis of these data was oriented towards the stated research objectives.

Two limitations concomitant with this procedure should be stated. The most significant scientific limitation is the lack of real world empirical data. System parameters such as interarrival times and unit vehicular distributions are based on data contained in U. S. Army training and war game publications and can be used only with a note of caution. The cost of conducting a brigade river crossing maneuver is, of course, a significant constraint which precludes sampling experiments. Thus, the system parameters chosen are the most reliable of those unclassified parameters available and are assumed to be realistic. A second limitation relating to the validation problem is that the size of the computer program

resulted in a long run time, approximately seven minutes on a UNIVAC 1108. The number of runs required for statistical validation was judged excessive and resulted in financial limitations being placed on subsequent experimental runs. However, as Naylor stated in (21), "The problem of verifying simulation models remains today perhaps the most elusive of all the unresolved problems associated with comparable simulation techniques." In that the objectives of this research are to demonstrate the potential of simulation and its applicability more than to conduct a specific scientific experiment, it is believed that these two limitations do not significantly detract from the stated research objectives.

#### Literature Survey

As Dalkey (3) stated in 1967, several hundred major military simulation projects had been carried out in the United States since 1964. Subsequently, many refinements to these projects and new, more extensive projects have been initiated. An extensive literature search of all military problems being investigated by simulation techniques was beyond the scope of this research. This survey was, therefore, limited to recent pertinent literature of simulation in general and simulation studies or projects associated with land combat.

Simulation as defined by McLeod (19), "The art of representing some aspects of the real world by numbers or symbols which may be easily manipulated to facilitate their study," agrees with the military definition and usage contained in (30). However, the term war game does not, technically, imply simulation. A war game, which can be a simulation, implies manipulation of two or more opposing forces (30). Hence, all



military simulation models involving maneuver forces are not necessarily war games. The base model developed in this research is such a model and was developed to represent a real world system.

A great deal of military simulation has been accomplished by The Rand Corporation. Kiviat (18) discussed simulation rationale, model construction and uncertainties, and provides a comprehensive list of definitions applicable to the simulation field. In a more recent article (17), he discusses and compares the attributes of general scientific programming languages and special purpose simulation languages. Ginsberg (14), Gordon (15), Haverty (16), and Smith (25) also analyze the pros and cons of using special purpose languages. An extension of this topic, the general problem of simulation acceptance by managers, is investigated and recommendations are offered in (27). In addition to these topics, works by McLeod (19), Gordon (15), Naylor (21), Smith (25), and Schmidt and Taylor (24) offer the simulation practitioner a wealth of information covering the statistical, validation, and general programming methodologies used in simulation.

The U. S. Army agencies primarily concerned with war gaming and computer simulation activities in the land combat field are the Office of the Deputy Chief of Staff for Operations (DCSOPS) and the U. S. Army Combat Developments Command (USACDC). Catalogs from these offices (5,28) and a literature search conducted by the Defense Documentation Center and the Defense Logistics Studies Information Exchange indicate that current simulation studies are quite extensive and numerous. DIVTAG II, a war game being developed by USACDC, is a computer simulation designed to provide

a responsive means for evaluating doctrine and organizations in low, mid, and high intensity war. Virtually all aspects of ground combat are simulated for divisional through army group - sized units (28). MAFIA V, the Maneuver and Fire Analyzer, is a closed, time-step simulation which assists force planners in analyzing various factors that affect the capabilities of combat units. MACE, Model for Assessment of Combat Effectiveness, was developed to determine the feasibility of computer simulations as a tool for evaluating division combat effectiveness (28).

Research Analysis Corporation (RAC), although not a part of the Army, is a Federal Contract Research Center and has contributed significantly to simulations of land combat (5). ATLAS, A Tactical, Logistical, and Air Simulation, was developed in 1969 to assist the military planner to evaluate the requirements for military forces. The Theater Battle Model, TBM-68, is a very large scale computer simulation war game designed to simulate a tactical environment realistic enough to serve as a basis for testing military contingency plans.

It is interesting to note in (5) that approximately one percent of the operational games and simulations are written in a special purpose simulation language, whereas approximately sixteen percent of the models under development are being programmed in either GPSS or SIMSCRIPT.

Special purpose simulation languages have, however, been used for military simulations rather extensively by military graduate students at civilian institutions. Works by Davis (4), Faulkender (11), Meyer (20), and Abele (1) demonstrate the applicability of DYNAMO as a simulation tool for the military practitioner. Davis approaches the division tactical

river crossing problem with an extensive DYNAMO model which is very detailed and comprehensive. However, unlike GPSS, DYNAMO requires considerable more effort from the novice to understand. The typical DYNAMO flow chart is not as analogous to military symbology as are similar GPSS flow charts. Yet, the potential of DYNAMO or the use of the Industrial Dynamics philosophy as a research tool for the military problem is unquestioned. Several other theses by Boles (2), Gibson (13), and Steine (26) demonstrate the applicability and ease of GPSS as a programming language to simulate air defense, logistics, and aircraft maintenance problems.

## CHAPTER II

### A TYPE SUBMODEL

#### General

The purpose of this chapter is to demonstrate to the computer simulation novice--a manager or staff officer whom a practitioner must convince--the analogy between the military symbology used to represent flows in a river crossing operation and the GPSS II flow diagram used to construct the computer simulation model. Quantitative factors and parameters available for analysis in the simulation model which are not normally considered in the traditional methodology will also be identified. It is assumed that the novice possesses a rudimentary understanding of the GPSS II logic, blocks, and system variables contained in (12).

The system depicted in Figure 1 consists of unit submodels which represent specific tactical units of the brigade. One such submodel, a mechanized infantry battalion, is illustrated by the flow diagram in Figure 2. The battalion's vehicles are created in a manner to simulate their actual ground deployment and rate of movement. These parameters are based on data contained in (9), and enter the system at the line of departure. Amphibious vehicles move to the crossing sites, cross the river obstacle, and proceed to their objectives on the far bank. Non-amphibious vehicles move to the dispersal area and to specific crossing

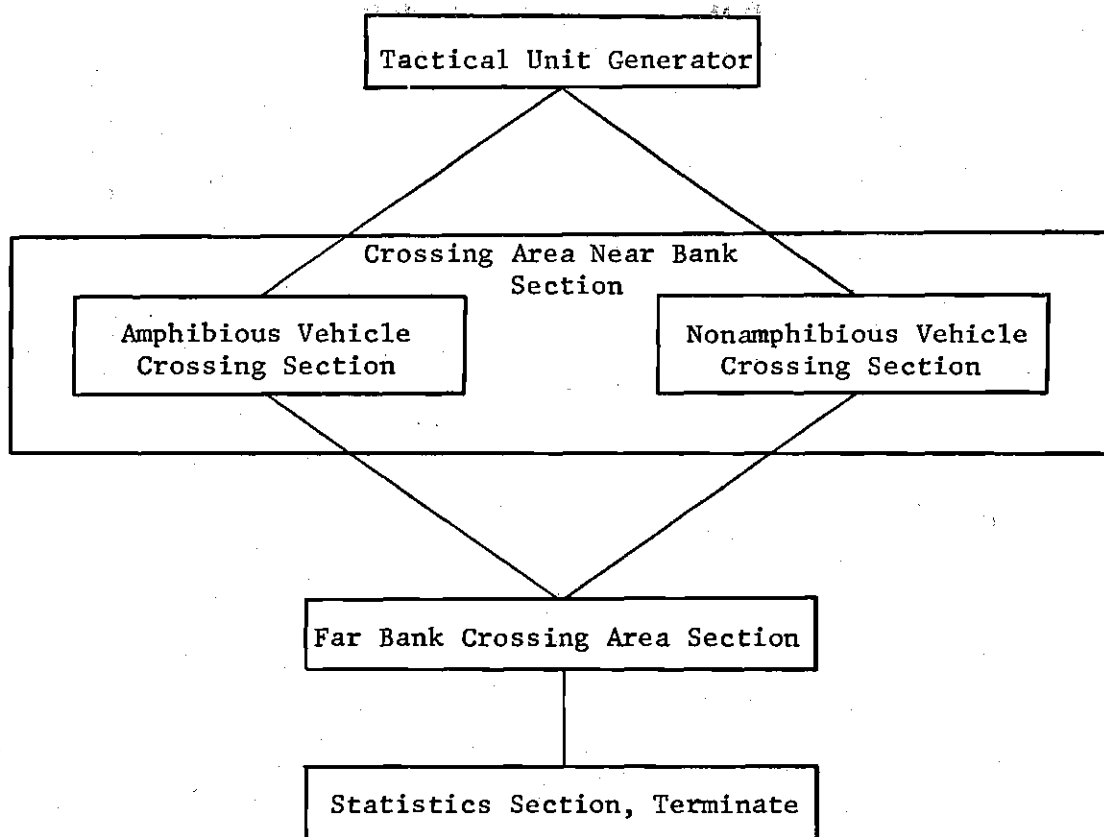


Figure 2. Submodel General Flow Diagram

equipment sites. Class 12 vehicles may use either LTR, M4T6, or MAB rafts; larger vehicles may use either the M4T6 or MAB's. The equipment descriptions are contained in Appendix A.

### Tactical Unit Generator Section

The tactical unit generator initiates a unit's vehicles and introduces them as transactions into the model. Each transaction represents one of four vehicle types.

Table 3. Simulation Model Vehicle Types

Vehicle Code	Weight Class	Type Vehicle
C1		Amphibious
C2	$C1 \ 12 < C2 \cong C1 \ 60$	Heavy tracked
C3	$C1 \ 12 < C3 \cong C1 \ 60$	Heavy wheeled
C4	$C4 \cong C1 \ 12$	Light and medium

The vehicles are generated in a desired sequence and are assigned a desired rate of movement and interarrival time. The transactions, with these parameter assignments, are initiated in a manner analogous to the actual ground deployment. Figures 3 and 4 depict a battalion advance in military symbology familiar to all operations staff officers. As indicated in (9), the battalion vehicles are assumed to be uniformly distributed throughout a square kilometer. Figure 4 represents a possible deployment formation. Elements of the combat support company and the three rifle

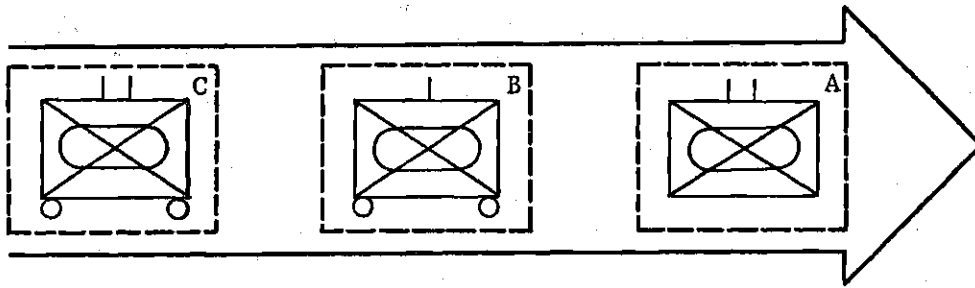


Figure 3. Battalion Axis of Advance

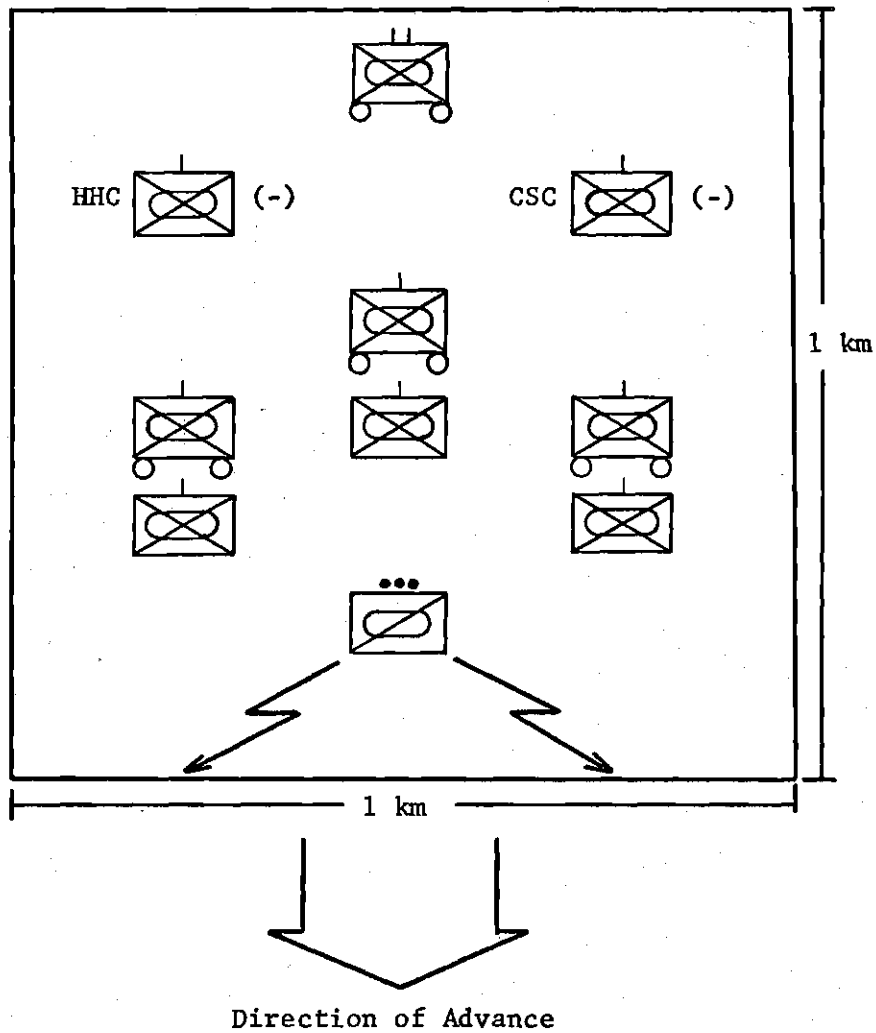


Figure 4. Battalion Type Deployment Configuration

companies comprise the assault echelon. The assault echelon is followed by the company trains and battalion combat trains. The GPSS II flow diagram analogous to Figures 3 and 4 is illustrated by Figure 5. Section D, ORIGINATE and ASSIGN blocks 1 and 2, create 162 transactions every  $3 \pm 1$  seconds, beginning at clock time 0 seconds. The interarrival time of  $3 \pm 1$  seconds was computed by noting that the 162 vehicles--uniformly distributed throughout a square kilometer as illustrated in Figure 4 must traverse one kilometer in:

$$\text{Travel time 1 km} = \frac{(3600 \text{ s/hr})(1 \text{ km})}{(7 \text{ km/hr})} = 514+ \text{ seconds; giving an}$$

$$\text{Arrival rate (AR)} = \frac{162}{514} \text{ vehicles per second; or an}$$

$$\text{Interarrival rate (IAR)} = \frac{1}{\text{AR}} = 3.14 \text{ seconds per vehicle.}$$

Given that the simulation time increment is in one second intervals, a uniformly distributed IAR of 2-4 seconds was chosen. The ASSIGN block identifies each vehicle as a 1-76 Infantry vehicle by assigning the 1-76 identification number, the constant 1 (K1), to each transaction's parameter 6. After K1 is placed in parameter 6, the ALL selection mode sends each transaction to blocks 3-5, in that order. COMPARE block 3 allows the first 82 transactions to enter and sends them to ASSIGN block 6, where each is assigned an identification number, K1, to the vehicle code parameter. K1 identifies each of these transactions as C1 amphibious vehicles. Section A, Figure 5, therefore, represents the vehicles con-



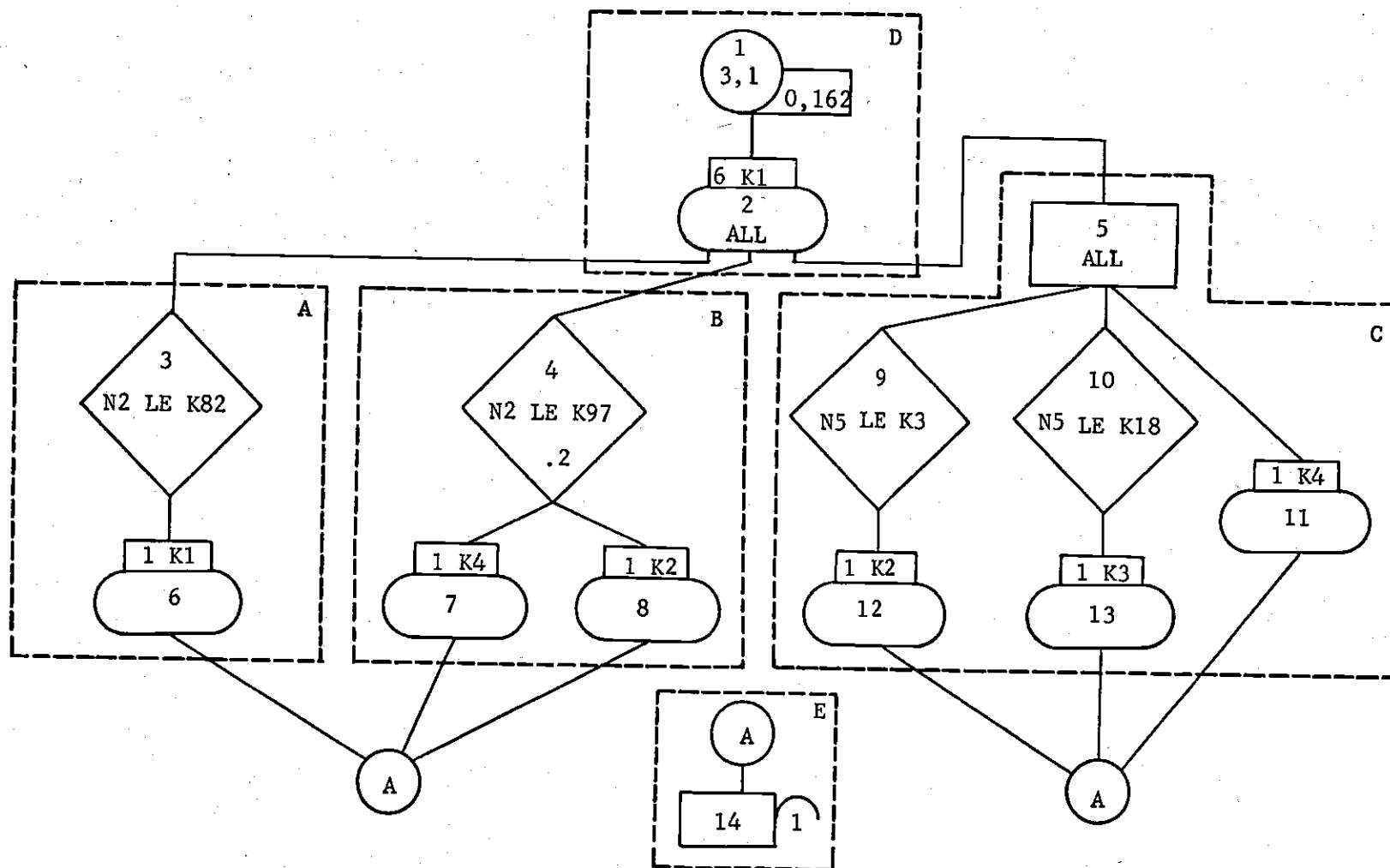


Figure 5. GPSS II Battalion Generator Flow Diagram

tained in Section A, Figure 3. Similarly, Section B, Figure 5 identifies and designates the 15 C2 and C3 vehicles in the company trains (Section B, Figure 3). The battalion combat trains, consisting of three C2 vehicles, 15 C3 vehicles, and 47 C4 vehicles, is depicted by Section C, Figure 3. These vehicles are identified in the corresponding section of the GPSS flow diagram (Figure 5). All transactions, after having been coded according to vehicle type, move to ENTER block 14, storage 1. This storage represents the crossing area near bank (CANB).

#### Nonamphibious Vehicle Section

Transactions leaving the tactical unit generator section (Figure 2) are separated into two major categories, amphibious and nonamphibious vehicles. A COMPARE block allows all transactions with the C1 identifier in parameter 1 to enter the amphibious vehicle crossing section. All other vehicles, the C2, C3, and C4 vehicles, enter the nonamphibious section.

Figure 6 illustrates the nonamphibious section in military symbology. Vehicles (transactions) enter this section at the line of departure (LD) and move to the dispersal area near bank (DANB). Vehicles are then assigned to one of two subareas within the DANB. One subarea contains all C4 vehicles and the other all C2 and C3 vehicles. The C4 vehicles may use all crossing equipment available, whereas the larger vehicles may use either the M4T6 or MAB rafts. Vehicles are dispatched to the raft sites so that no more than five are enroute to each site. This parameter is selected to represent the control exercised by the Traffic Control Post located at the dispersal area. Vehicles are dis-

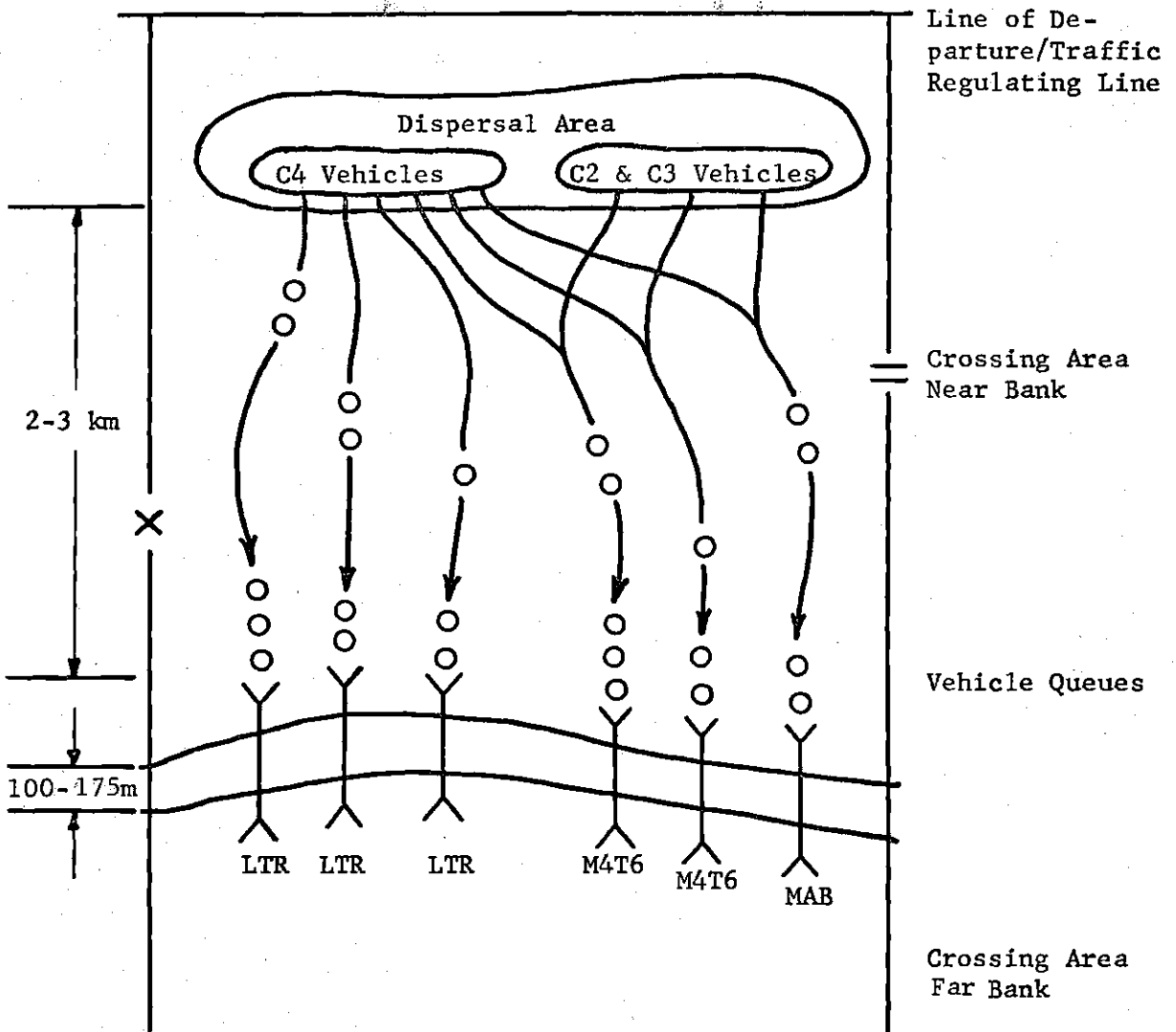


Figure 6. Nonamphibious Vehicle Flow Diagram

patched to control the raft site queues and to preclude unnecessary congestion in the area between the dispersal area and the raft sites. The vehicles move onto the rafts, cross the river, and enter the crossing area far bank (CAFB). If the raft is occupied, the vehicles queue in front of each raft site.

The analogous GPSS II flow diagram establishes the simulation logic and transaction flow and is shown by Figure 7. The LD, or entrance to the CANB, is represented by ENTER block 17's storage 13. Each transaction's parameter 5 is assigned a value of variable 1 by ASSIGN block 18. This value represents the transit time from the DANB to the raft sites and is determined by the following GPSS variable statement:

1 VARIABLE FN1\*K3600/P4/K10

This is equivalent to the mathematical expression:

Transit time = Distance/Vehicle Rate of Movement

(See Figure 8)

The random number generator selects a uniformly distributed number between zero and one as the function's argument and computes a functional value between 20 and 30. Assuming this value is 28 and that the value in parameter 4 is 7, the assigned rate of movement, the variable statement becomes:

$$\text{Transit Time} = \left(\frac{28}{10} \text{ km}\right) \left(3600 \frac{\text{sec}}{\text{hr}}\right) \left(\frac{1 \text{ hr}}{7 \text{ km}}\right) = 1440 \text{ seconds.}$$

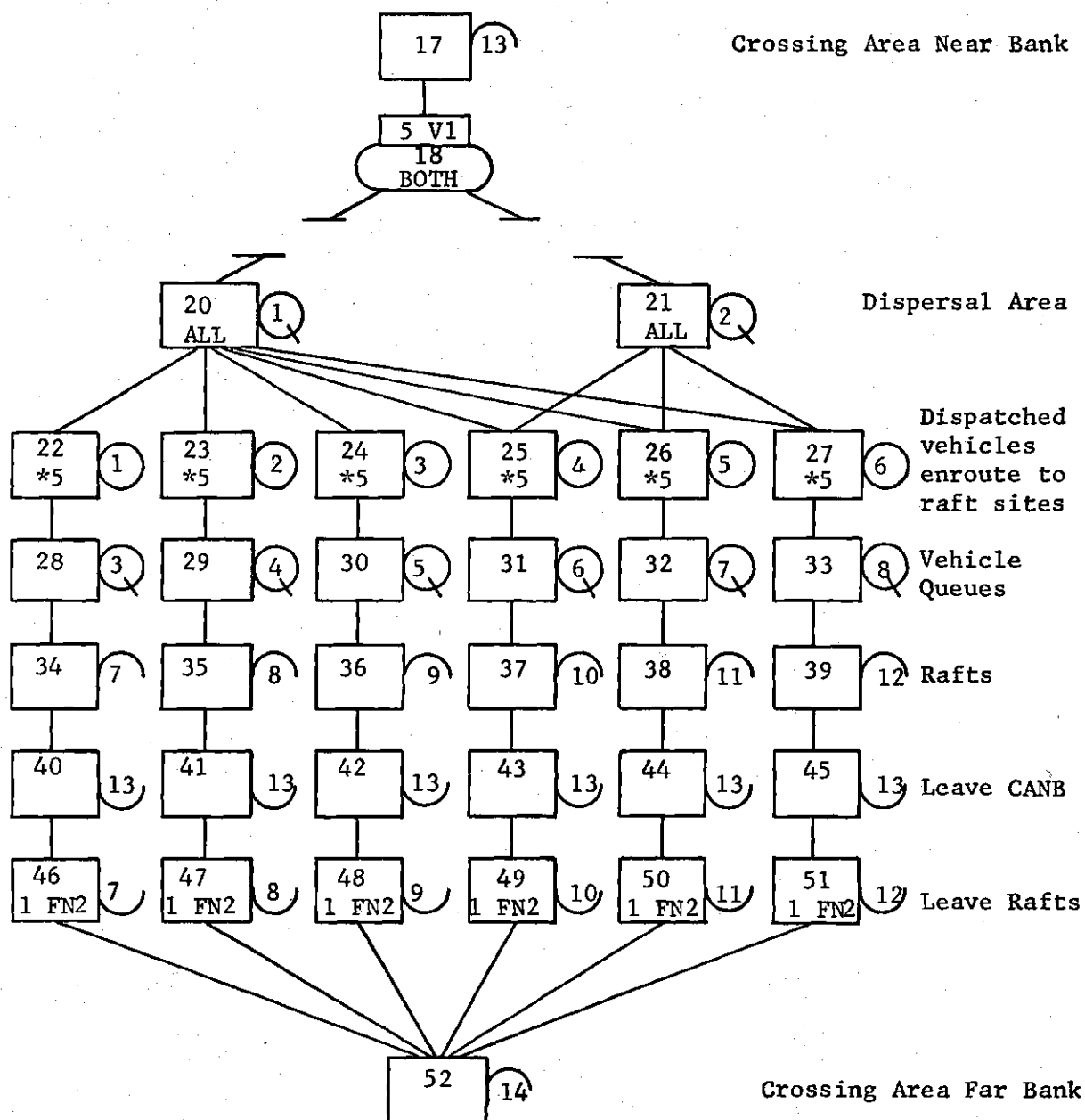


Figure 7. GPSS II Nonamphibious Vehicle Flow Diagram

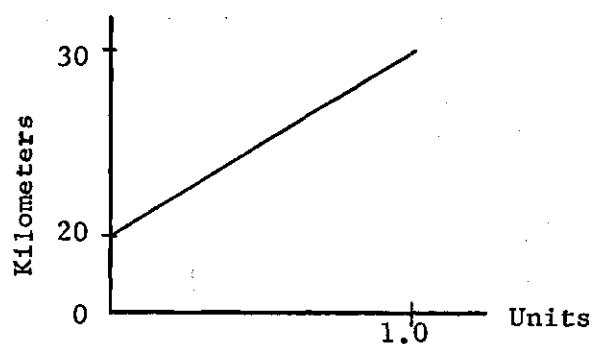


Figure 8. GPSS II CANB Transit Time Function

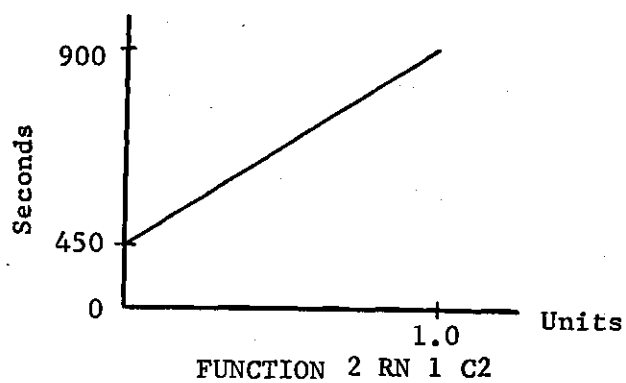


Figure 9. GPSS II River Crossing Transit Time Function

The BOTH selection mode sends the transactions, in turn, to QUEUE 1 and 2, blocks 20 and 21. All C4 vehicles are identified and are permitted to enter QUEUE 1, the C4 subarea. All other vehicles enter QUEUE 2, the C2-C3 subarea. Block 20's ALL selection mode sends the transactions to STORE 1 through STORE 6. These storages represent the terrain between the subarea and raft sites. Similarly, block 21's ALL selection mode sends the vehicles to STORE 4 through STORE 6. Each STORE is assigned a capacity of five to limit the vehicles enroute to the desired number. The transit time, computed by the variable statement previously discussed, is obtained by indirect specification to the value contained in parameter 5.

Transactions move to the raft queues, QUEUE 3 through QUEUE 8; from the queues to ENTER storage 7-12, blocks 34-39, which represent the rafts; and leave the CANB by entering LEAVE storage 13, blocks 40-45. The river crossing transit time is simulated by the product of the mean and the value of function 2 (see Figure 9). Function 2 delays each raft for 450-900 seconds. This delay simulates a 4-8 round trip per hour utilization rate.\* ENTER storage 14, block 52, represents the crossing area far bank (CAFB). The CAFB is entered by all transactions as they leave the rafts.

A more vivid analogy between the military and GPSS II symboloby (Figures 6 and 7) is illustrated by Figure 10, a superimposition of

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\*The CGSC problem assumes a six round trip per hour utilization rate. The 4-8 round trip per hour uniformly distributed utilization rate is used in the model to more realistically represent the range of this parameter as observed in actual operations.

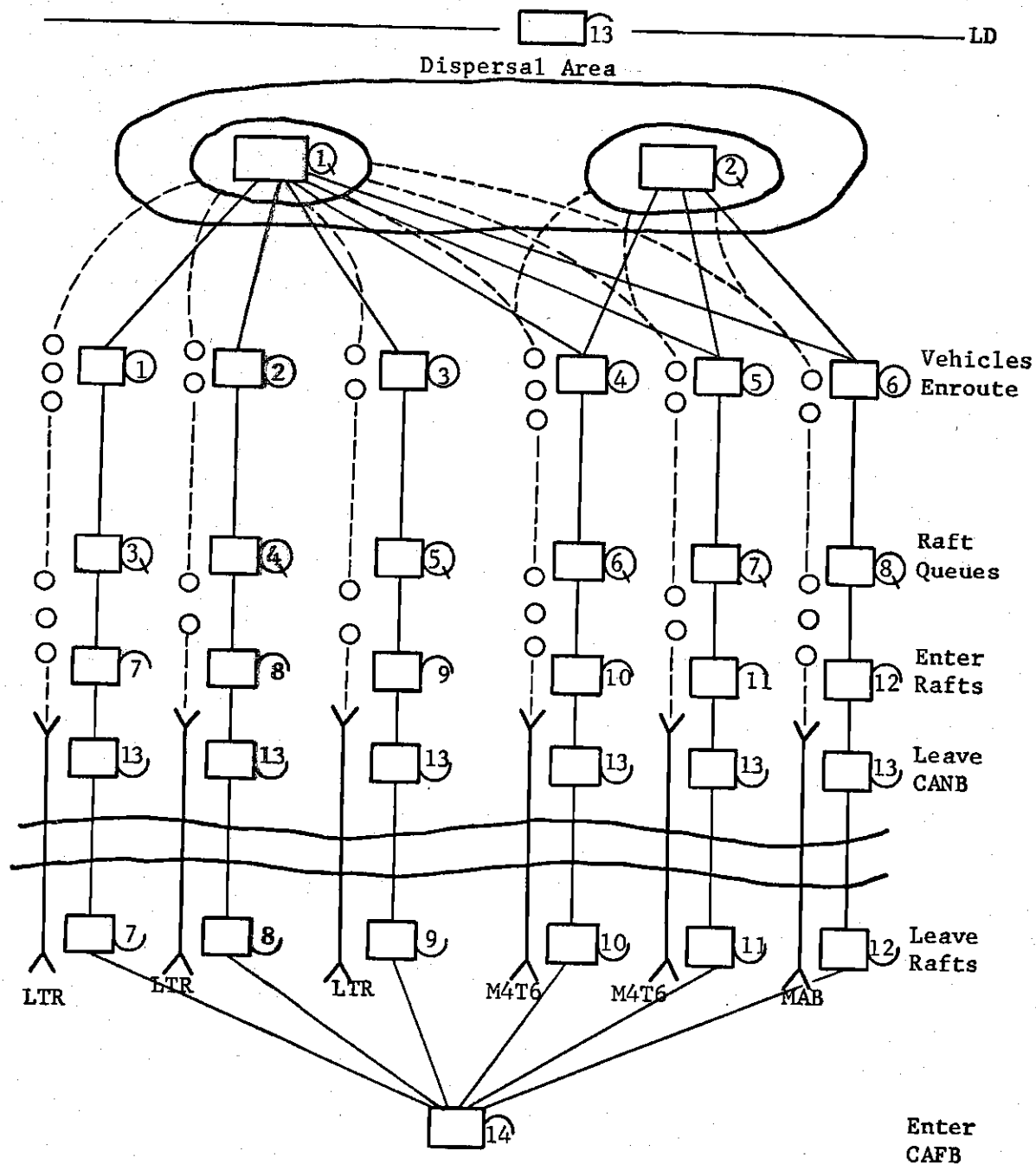


Figure 10. Superimposition of Figures 6 and 7



Figures 6 and 7.

#### Amphibious Vehicle Section

Figures 11 and 12 depict the Amphibious Vehicle Section of Figure 2. The flow similarities are obvious, but a more detailed inspection of Figure 11 reveals significantly more quantitative information and parameter potential than that available with military symbology. This information and parameter availability is very useful in model validation and enables the practitioner to realistically represent a real world situation with the simulation model.

STORE 20-22, blocks 69-71, depict the three crossing sites available to the crossing force. It is not realistic to assume that all amphibious vehicles enter these sites as they arrive. To do so would assume that ingress to the water is available all along the near bank. The selection of the crossing sites indicates that this is not so, but that ingress is limited to the areas delineated by the sites. This restriction reduces the ingress area width from, for example, a 3000 meter crossing width to the total width of the three crossing sites. This width determines how many vehicles may enter the river simultaneously. If the terrain along the near bank were very difficult, it is realistic to visualize situations where no more than ten vehicles could enter the river simultaneously from each site. The crossing site ingress capacity can be determined by reconnaissance of the river bank. However, once determined, this restriction can be simulated by setting the proper capacity limit for storages 20-22. These capacities limit the number of transactions entering each block. The delay of  $8 \pm 3$  seconds represents

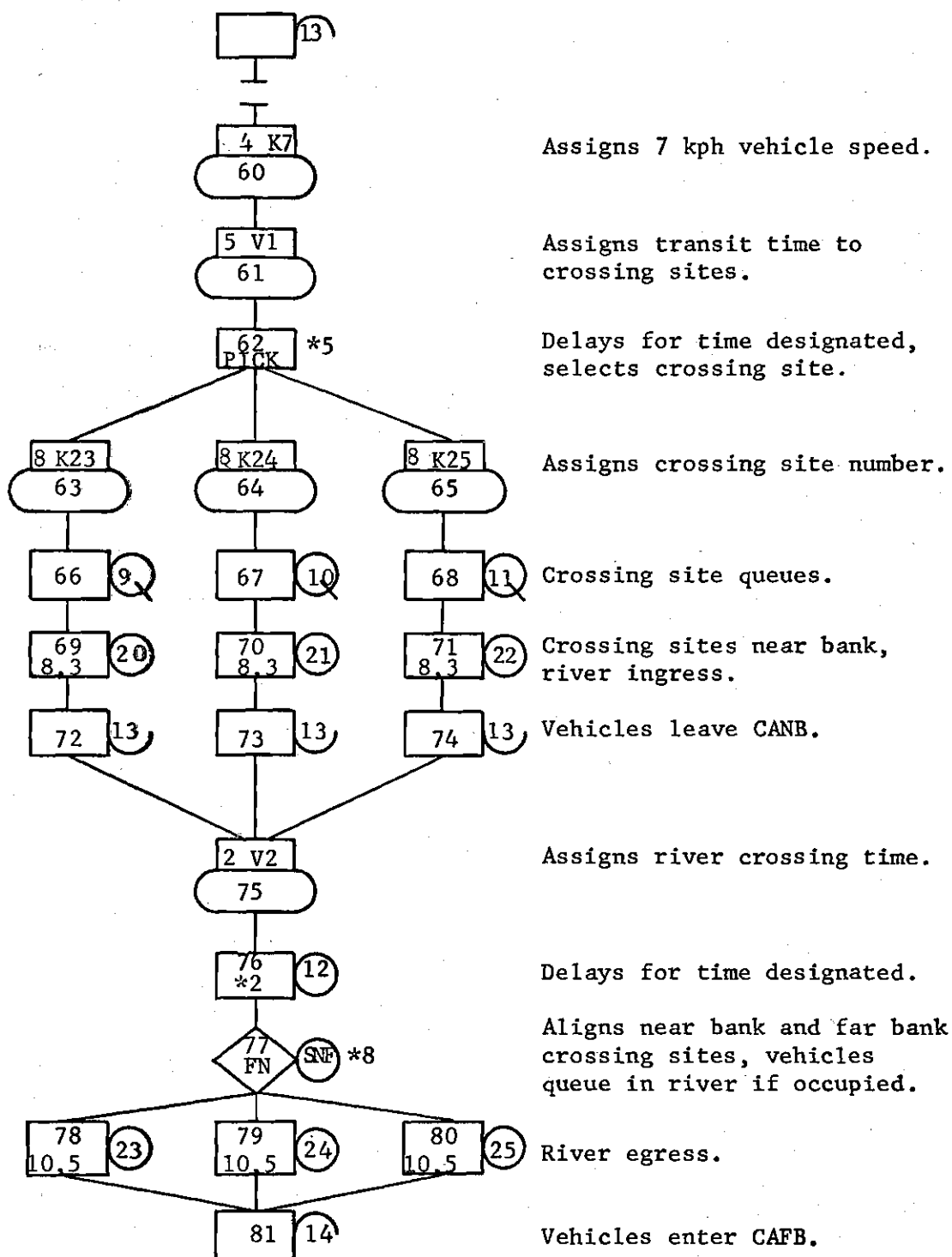


Figure 11. GPSS II Amphibious Vehicle Flow Diagram

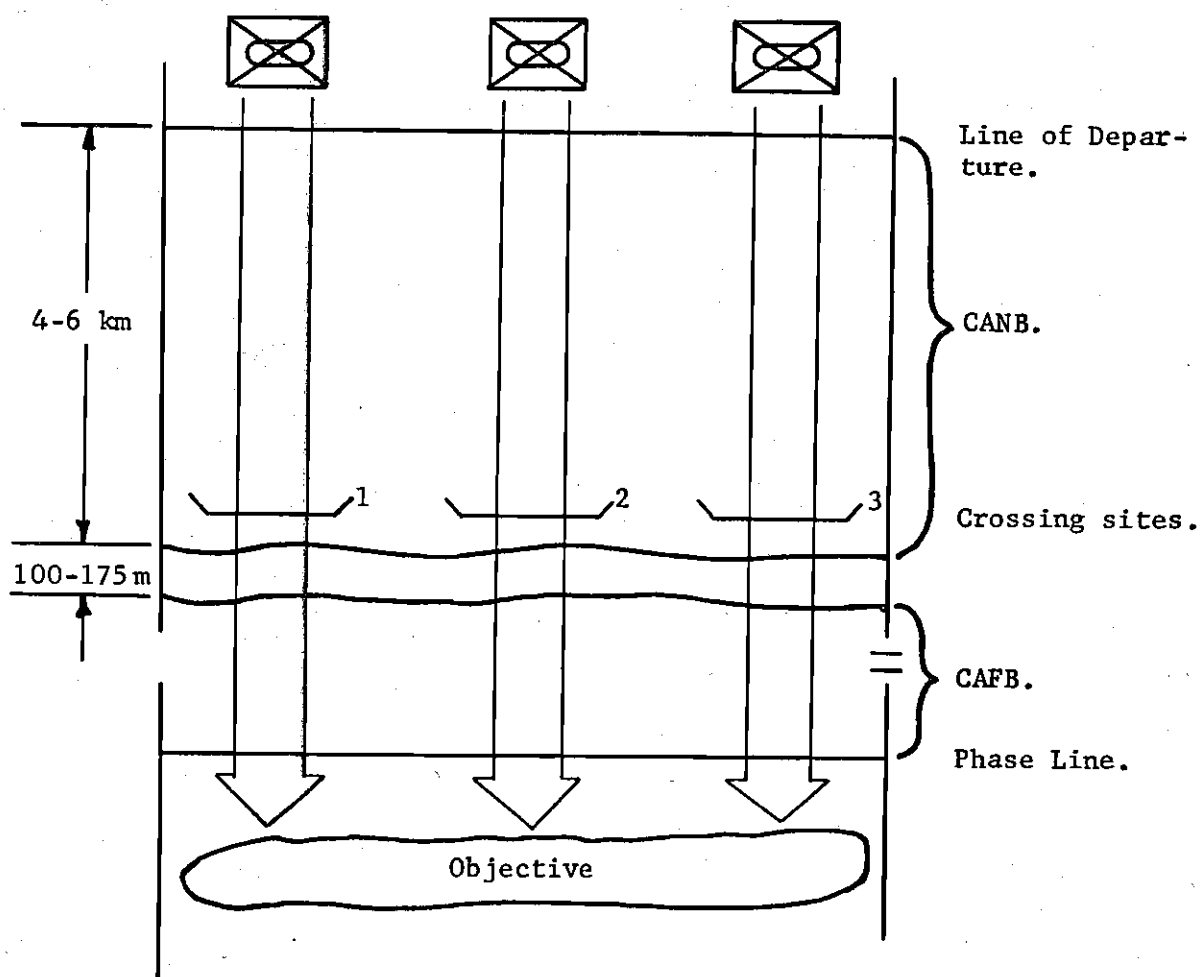


Figure 12. Amphibious Vehicle Flow Diagram

the amphibious vehicles' movement from the near bank edge into the river. The real world situation would also result in queues forming behind each crossing site. This is simulated by QUEUES 9-11, blocks 66-68.

Another problem in an actual river crossing is the annoying situation which does not allow as many vehicles to enter the far bank crossing sites as entered the near bank sites. This can be realistically portrayed in the GPSS II simulation model by adjusting the capacities of the storages which represent the egress sites (STORE 23-25, blocks 78-80). The delay time in these blocks,  $10 \pm 5$  seconds, allows a longer delay to simulate the uphill climb from the river to the far bank. The ingress and egress parameters represent values which affect a vehicle's river crossing time in actual operations. These parameters are not considered in the traditional methodology. The values selected are based on the author's experience and are included to demonstrate the detail which can be structured into the simulation model.

The near bank and far bank crossing site alignment is simulated by blocks 63-65, and block 77. Vehicles entering the river at crossing site 1 (STORE 20) are directed to the corresponding far bank crossing site (STORE 23) by assigning the storage number to parameter 8 of each transaction. As transactions attempt to enter the far bank sites (STORE 23-25), a selection mode FUNCTION, abbreviated FN in the block symbol, assigned to block 77 orients each transaction to the proper far bank site, Figure 13. The value of function 3 is the number corresponding to the block number assigned to parameter 8. This is used as the argument.

River transit time is simulated by blocks 75-77. The value of

variable 2 is the quotient of a uniformly distributed river width (100-175 meters) and the amphibious vehicle rate of movement (3-5 kph), Figure 14.

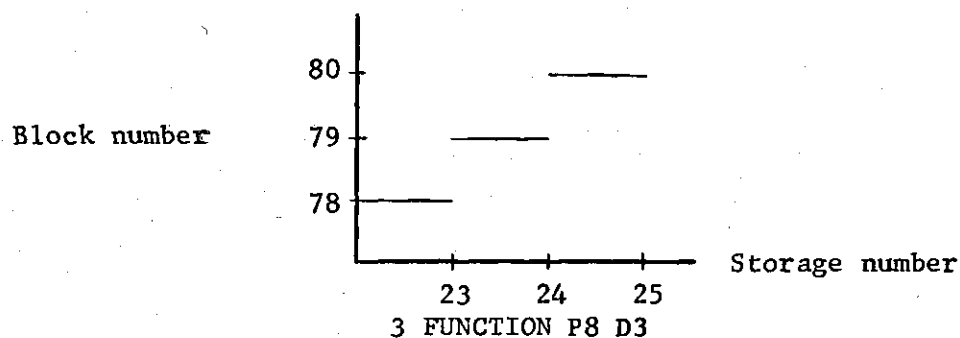


Figure 13. GPSS II Crossing Site Alignment Function

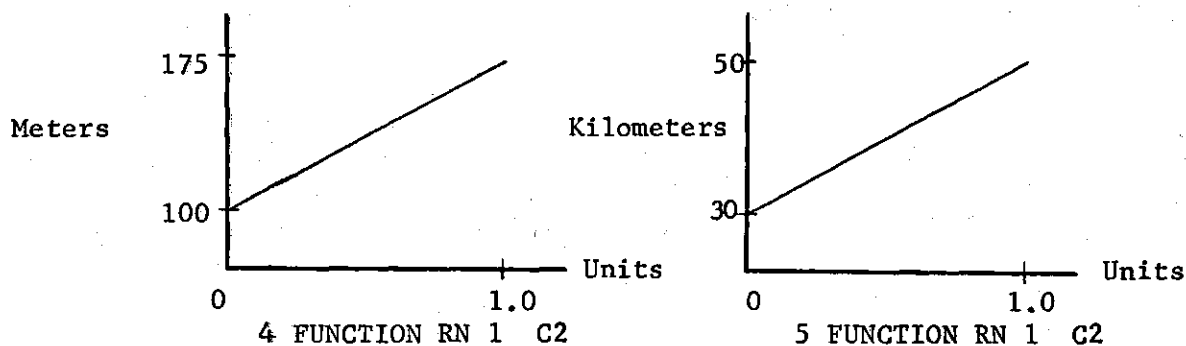


Figure 14. GPSS II River Transit Time Functions

The value of variable 2:

2 VARIABLE FN4\*K3600/FN5\*K100

is assigned to parameter 2 of each transaction and the delay is effected

by indirect specification in block 76. If, after this delay, a crossing site is not full, transactions enter blocks 78-80. However, if a site is full, the transactions queue in the river and enter the crossing sites when space is available.

This option is simulated by block 77, GATE SNF\*8. The system variable SNF\*8 allows a transaction to enter the block if the corresponding storage number contained in the transaction's parameter 8 (either K23, K24, or K25) is not full. If this test is satisfied, the transaction enters block 77 and is sent to the appropriate far bank crossing site. All transactions then proceed to the CAFB, which is represented in GPSS II symbology as ENTER storage 14, block 81.

#### Inherent Quantitative Data Availability

The GPSS II flow diagram enables the practitioner to collect, collate, and analyze a large amount of information not available in the traditional methodology. Traffic flow, effects of competition for river crossing equipment, and the simulated system logic may be studied. The computer output may provide information on:

1. the volume of vehicles moving through the system,
2. transit time distribution between selected points within the system,
3. average utilization of critical equipment, and
4. maximum and average queue lengths at selected queues.

Vehicle priorities may be established and the interdependence between selected variables such as queue lengths, vehicle density or rates of

vehicle flow, and the transit time for a selected crossing unit to effect a crossing may also be varied and studied (12).

## CHAPTER III

### THE BASE MODEL

#### General

The base model is a computer simulation model of the system illustrated in Figure 1. Input to this system are the vehicles of the 1st Brigade, 52nd Mechanized Division. The task organization of the brigade, Appendix B, and tactical configuration, Figure 15, are based on the CGSC instructional problem (29). The base model simulates one specific type of brigade task organization, that depicted in Appendix B; and one type tactical configuration, that illustrated by Figure 15. The CGSC problem served as the base from which all quantitative data were obtained. Time and distance parameters were obtained from topographical map measurements and from U. S. Army war game data (30). The tactical formation and task organization reflect the author's experience and perception of U. S. Army river crossing doctrine as contained in (9, 34, 29, and 8).

The base model is a synthesis of unit submodels similar to that discussed in Chapter II. The general flow diagram of the model is depicted by Figure 16. The Tactical Unit Generator Section (Section A) initiates the units and passes them as transactions to the Main Movement Section (Section B) or the Special Unit Processing Section (Section D). The routing depends on the type unit. Unit vehicle flows are simulated



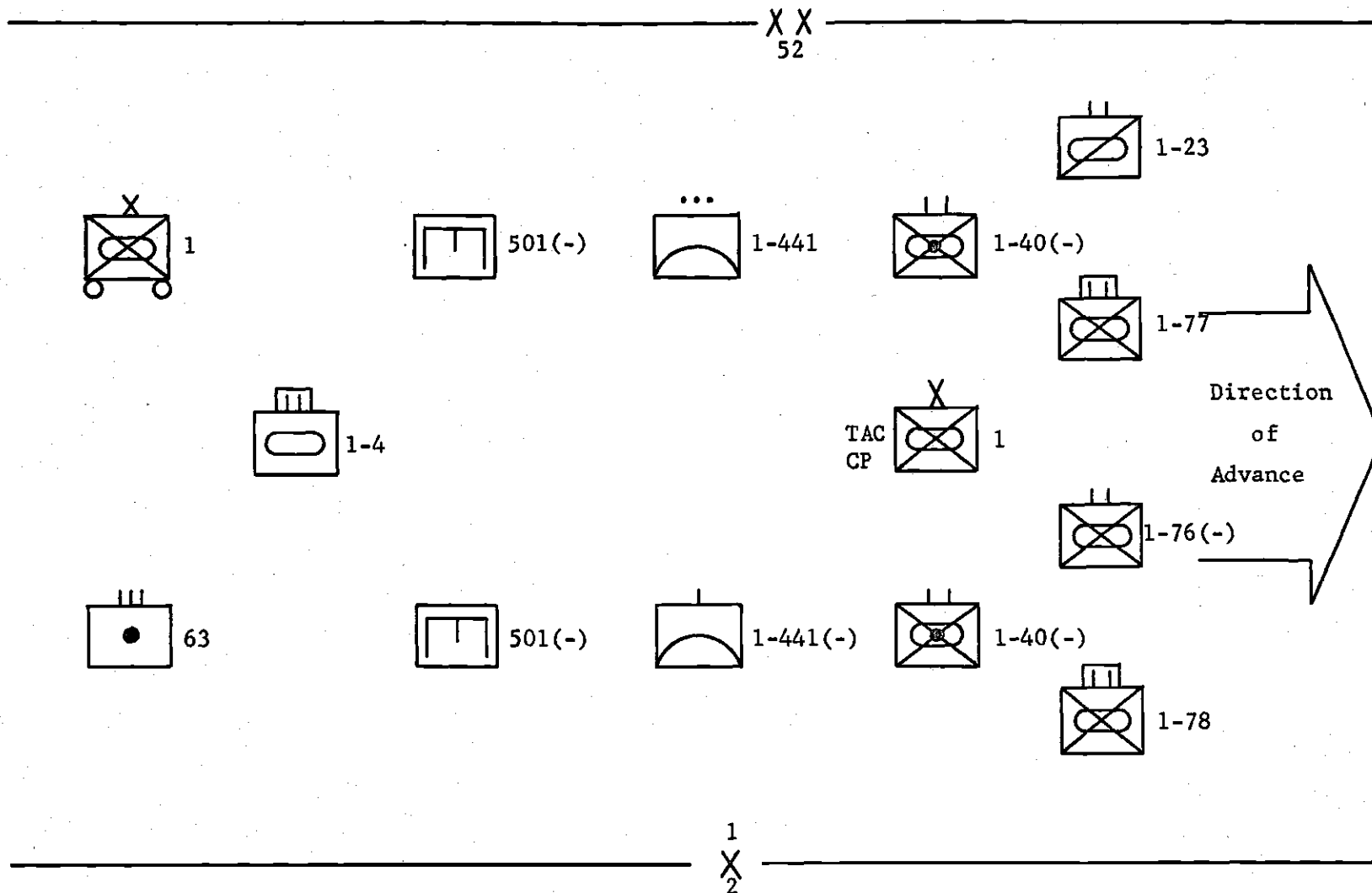


Figure 15. Base Model Tactical Unit Deployment Configuration

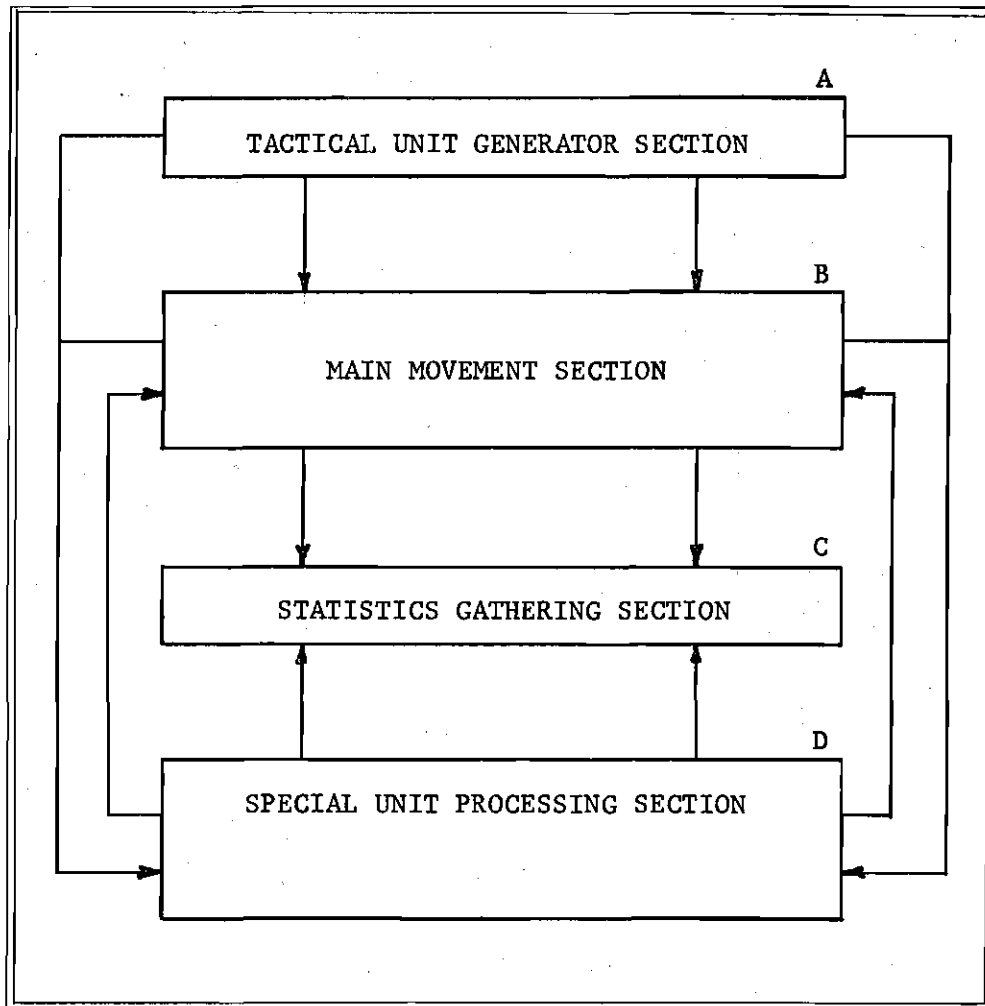


Figure 16. Base Model General Flow Diagram

by these sections through the Crossing Area Near Bank (CANB), across the river, through the Crossing Area Far Bank (CAFB), and onto the objective. After passing through the objective area, unit vehicles are terminated and appropriate statistics are gathered by the Statistics Gathering Section (Section C).

As indicated by the computer program of the GPSS II base model simulation, Appendix C, the model is structured in a manner analogous to the military units it simulates. Achieving this similarity has required a large number of GPSS II blocks. The model contains over 790 blocks and is capable of processing up to 2500 transactions simultaneously. The size of the model precludes listing a complete GPSS II flow diagram. However, a representative flow diagram is contained in Appendix D. Portions of this GPSS II diagram, depicted as superimpositions of the military and GPSS II symbology, will be discussed in detail.

#### Tactical Unit Generator Section

Each tactical unit's vehicles are initiated by an ORIGINATE or GENERATE block, depending on the time of initiation, and assigned an identification number in parameter 6, the unit identification parameter. Units are referred to in the computer program as U1, U2, and so on. When the code is followed by S or N, such as U4S or U4N, the unit is further identified as to its location in the brigade zone of action. Vehicle identification codes are assigned to each transaction's parameter 1, as was done in the submodel, to designate and identify a unit's C1, C2, C3, and C4 vehicles.

Table 4. Tactical Unit Identification Codes

Unit	Identification Code Assigned Parameter 6
TF 1-78 Inf (U1)	K1
1-76 Inf (U2)	K2
TF 1-77 Inf (U3)	K3
TF 1-4 Armor (U4)	K4
1-23 Cav (U5)	K5
Bde Tac CP (U6)	K6
1-441 Arty (U7)	K7
Engineers (U8)	K8
Trains (U9)	K9
1-40 Arty (U10)	K10
1-651 Arty (U11)	K11
1-652 Arty (U12)	K12

The tactical unit generator blocks are similar to the TF 1-78 Inf ORIGINATE block previously discussed with the exception that the number of transactions initiated differs according to the number of vehicles in each unit. The time of entry of the transactions into the model varies according to the tactical formation. All units crossing the line of departure (entering the system) at clock time zero are initiated by ORIGINATE blocks. Subsequent arrivals are initiated by GENERATE blocks with the proper delay controlled by COMPARE blocks. Subsequent variations in the base model tactical formation are made in the experimental runs, Chapter IV, by manipulating the subunit generator ORIGINATE and GENERATE block parameters. A representative GPSS II flow chart of

one unit generator is included in Appendix D.

### Main Movement Section

The general flow of the Main Movement Section (Section B, Fig. 16) is illustrated in detail by Figure 17. The section is divided into two major subsections, northern and southern, which receive unit vehicles according to their relative location in the system. Approximately half of the vehicles move through each of these subsections. Transactions enter the Main Movement Section from Section A or D, and are sent to either the northern or southern portions. A unit's vehicles are identified as either amphibious or nonamphibious and are routed to the appropriate simulation model subsection. After effecting the river crossing, vehicles are directed to the CAFB subsection and are either transferred to the Special Unit Processing Section for subsequent movement to the objective area, or to the Main Movement Section for similar routing. As the transactions (vehicles) pass through the objective area, they are terminated from the system and enter the Statistics Gathering Section for statistical compilations. Subsequent discussion will be restricted to the southern portion of the system. This portion is representative of the total system transaction flow and GPSS II logic.

### Southern Amphibious Vehicle Flow

The southern amphibious vehicle flow is divided into two main subsections: the flow initiated as the vehicles enter the CANB and cross the river, and the subsequent flow initiated as the vehicles enter the CAFB. The GPSS II flow diagram, Appendix D, illustrates the base

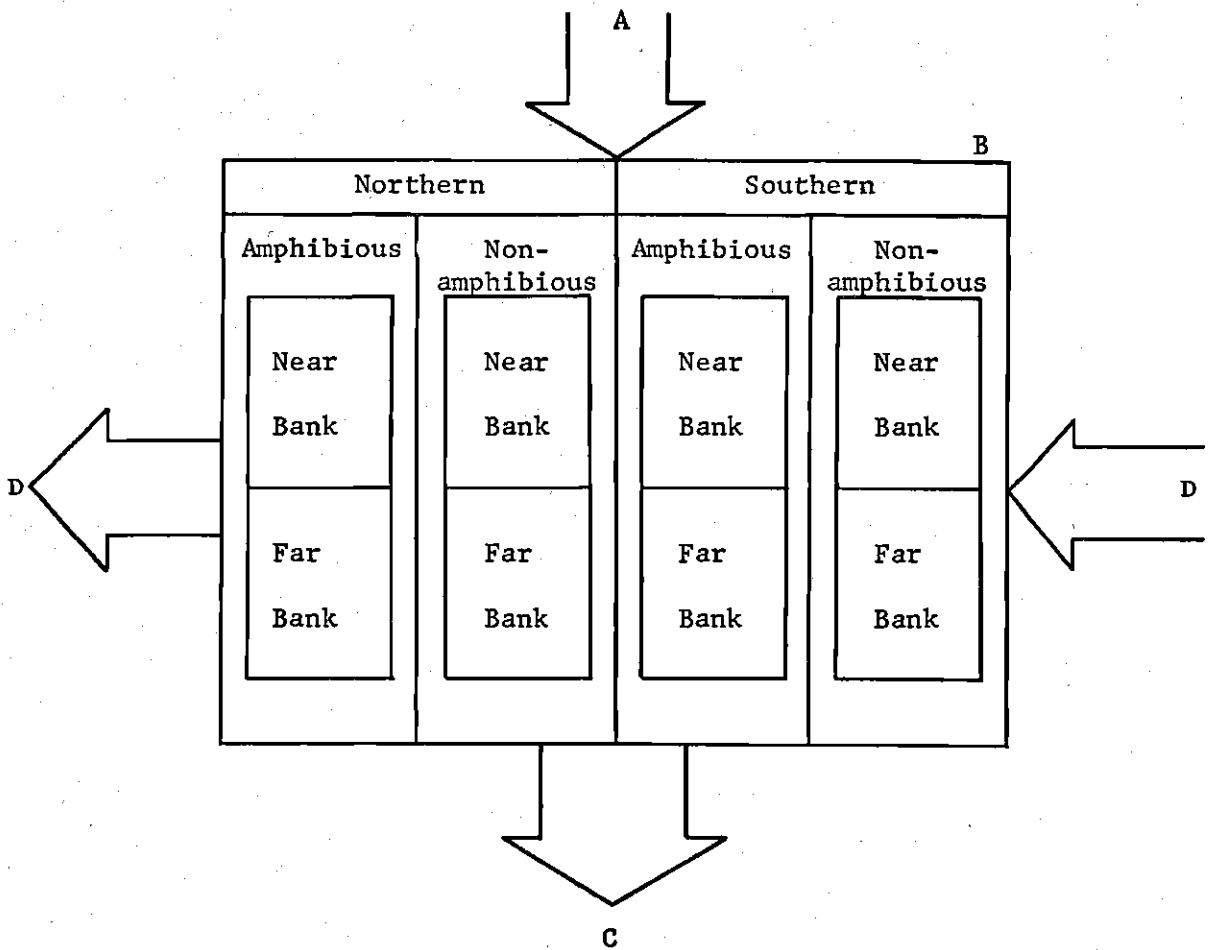


Figure 17. Main Movement Section General Flow Diagram

model simulation logic. The base model CANB flow is identical to the submodel flow, Figure 11, with the exception of the system variable and block number digits.

The CAFB southern amphibious vehicle flow, Figure 18, begins as vehicles enter the far bank and are routed to specific unit flow sections: TF 1-78 Inf (U1) to block 450, and 1-76 Inf (U2) to block 460. These COMPARE blocks allow the C1 amphibious vehicles to enter and the time each transaction enters is placed in SAVEX locations 25 and 26. The SAVEX storage cell values are maintained by the program and are automatically printed in the computer printout at the termination of the simulation run. The vehicles move to the alignment areas (ENTER storage 29 and 30, blocks 452 and 462) and are delayed by GATE blocks 453 and 463 until all vehicles have closed. This realistically represents the tactical unit's reorganization after crossing the river and insures that the unit moves from the alignment area in a proper tactical formation. The formation is reinitiated by GENERATE blocks 456 and 466. The COMPARE blocks following the GENERATE blocks insure that no transaction enters until the alignment areas are full.

Having satisfied the COMPARE statements, transactions leave the alignment area and are assigned a transit time to simulate the delay from the alignment area to the phase line. The value of variable 1:

1 VARIABLE FN1\*K3600/P4/K10

is placed in each transaction's parameter 2 by ASSIGN block 470. The time is computed by dividing the vehicle rate of movement (7 kph and contained

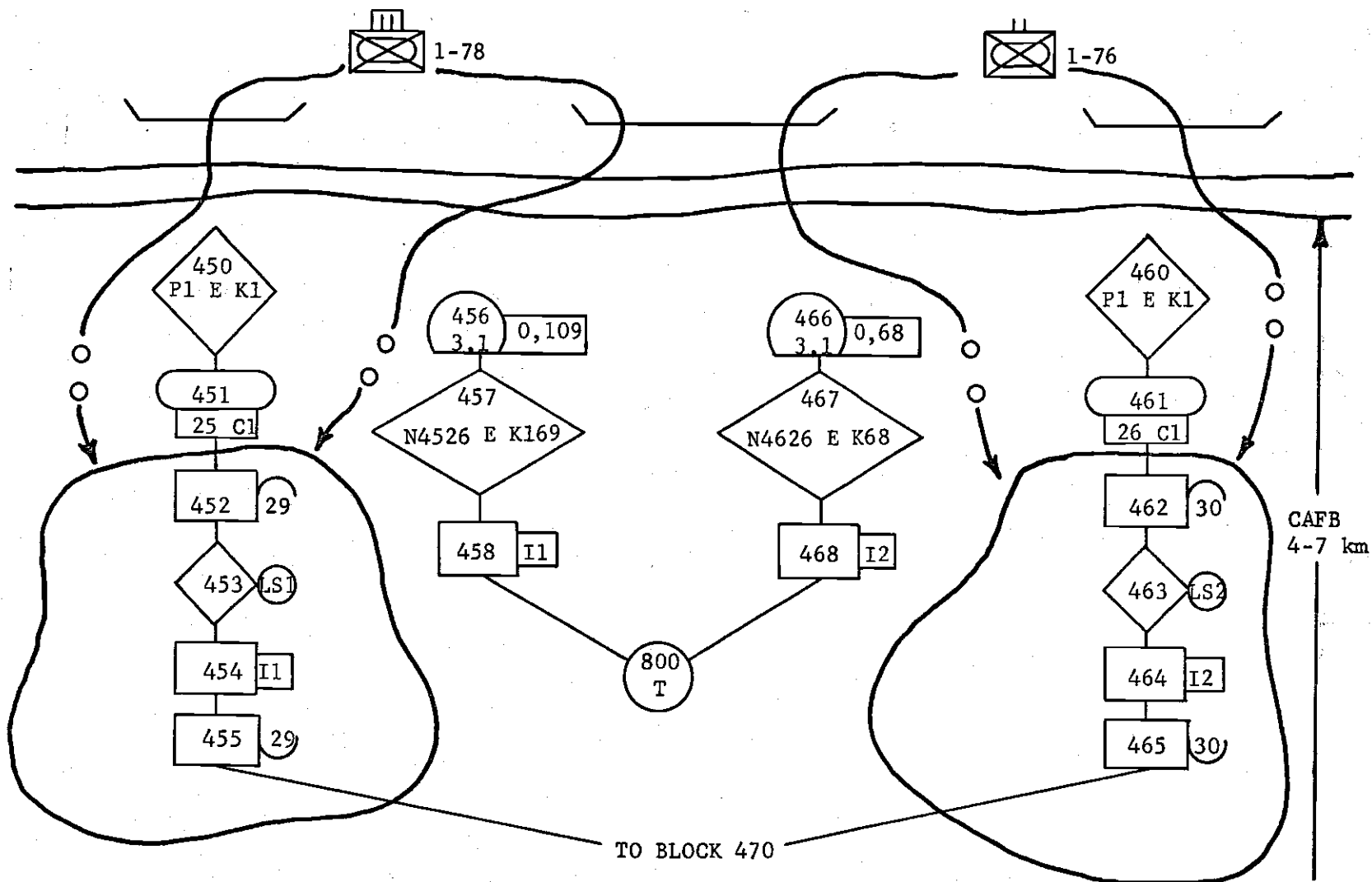


Figure 18. Southern Amphibious Vehicle Flow



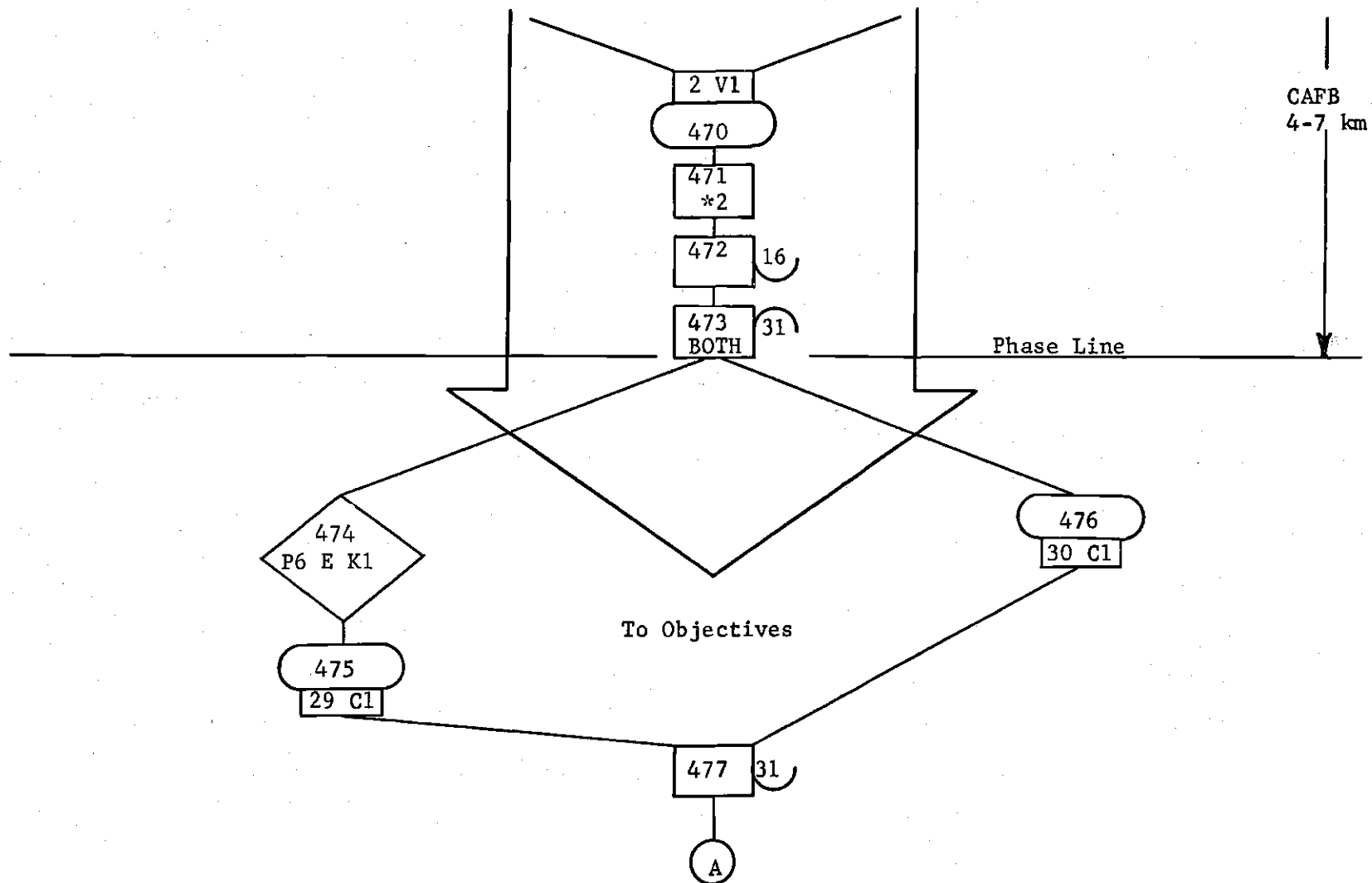


Figure 18. Continued

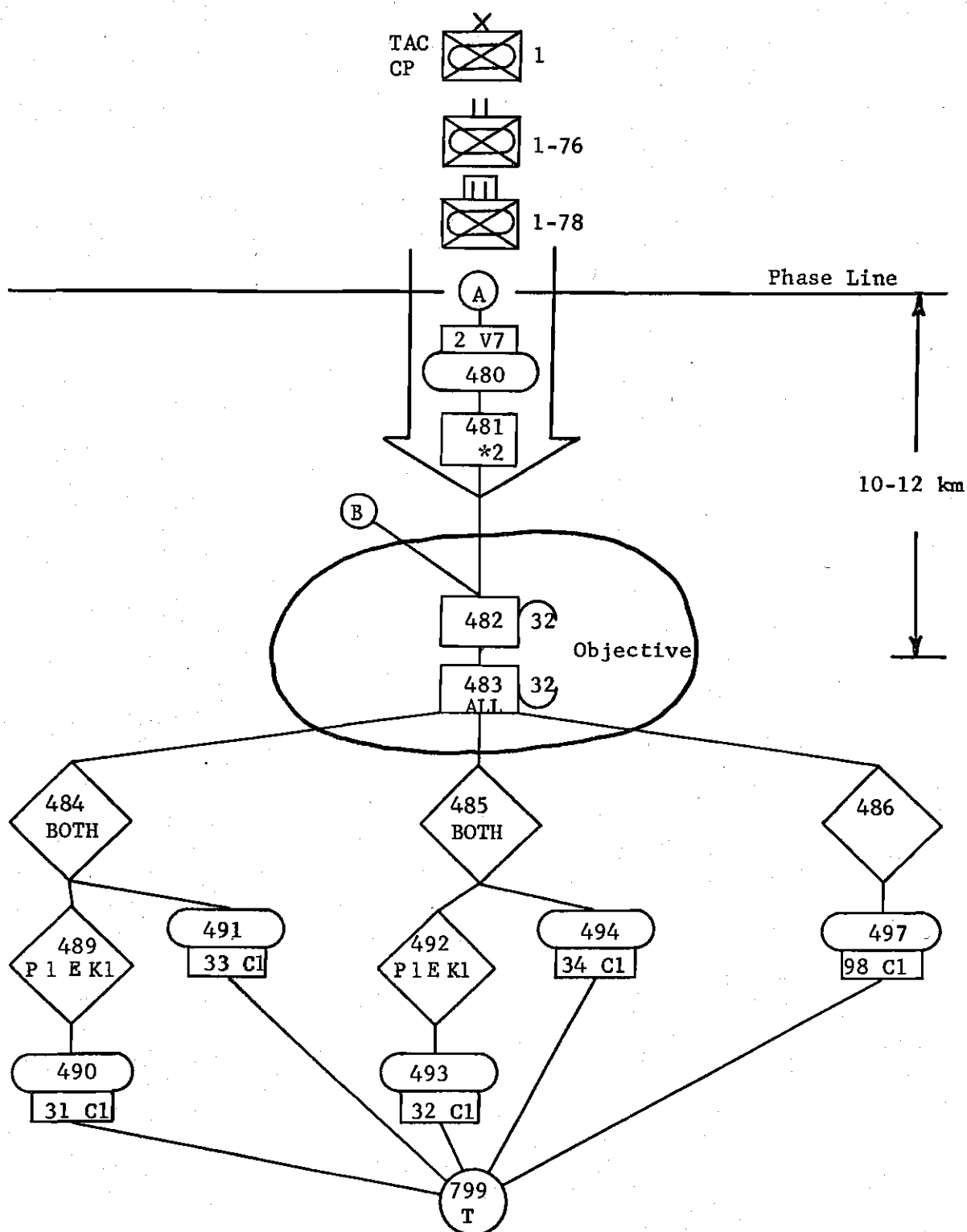


Figure 18. Concluded

in parameter 4) into a uniformly distributed distance of 4-7 km. The value of this distance is determined by function 1 (Figure 19).

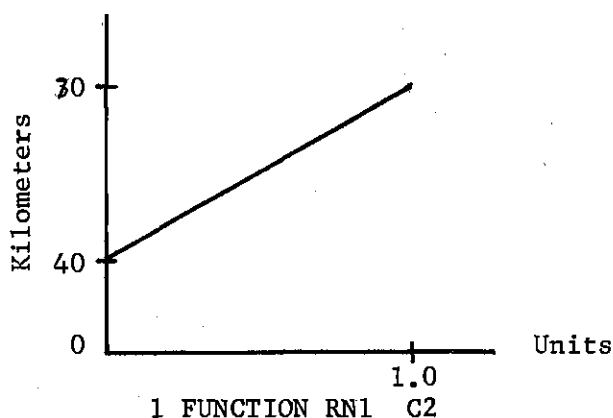


Figure 19. GPSS II Phase Line Transit Time Function

Transactions are delayed by ADVANCE block 471 for the appropriate transit time and leave the CAFB upon entering block 472, LEAVE storage 16, the CAFB. As vehicles enter the phase line, simulated by ENTER storage 31, block 473, the BOTH selection mode directs the transactions to their respective SAVEX cell locations. Transactions leave the phase line as they enter block 477, LEAVE storage 31.

Vehicle flow from the phase line to the objective area is similarly simulated by blocks 480-483. The closure times for each unit's amphibious and nonamphibious vehicles are placed in the SAVEX blocks. All transactions are terminated as they pass through the objective area and enter the TERMINATE block 799.

### Southern Nonamphibious Vehicle Flow

The southern nonamphibious vehicle flow (Figure 20) is similar to that of the submodel. However, two significant differences exist. The base model simulates more than one tactical unit and the QUEUE blocks representing the C4 and C2-C3 vehicle dispersal areas have been replaced by LINK blocks 282 and 317.

As vehicles enter the DANB (Fig. 20) they are identified as either C4 or C2-C3 and are routed to their respective subareas within the dispersal area. C4 vehicles are sent to block 292, LINK chain 9. C2 and C3 vehicles are sent to LINK chain 13, block 317. The LINK blocks increase the efficiency of the computer simulation by deactivating the transactions on the user chains. As transactions enter the LINK block, they either pass through the block onto a subsequent block, determined by the ALL selection mode; or, if delayed, enter user chain 9 or 13. The system variable PR1 establishes the transaction priorities on a first come within priority group basis on each chain.

Vehicles enter the area between the DANB and the river crossing equipment sites via blocks 283-288, ENTER storages 43-48. The number of vehicles permitted in this area is controlled by the capacity limit of each storage. The first vehicles to arrive at the DANB move directly to these blocks until the capacity limits have been filled. Once full, subsequent vehicles are refused entry into the area and must wait in the DANB. This is simulated by the user chains. Blocks 252, 297, and 298 act as traffic control posts which prohibit premature vehicle entry into the crossing sites. Transactions are delayed until they can move directly to a crossing site.

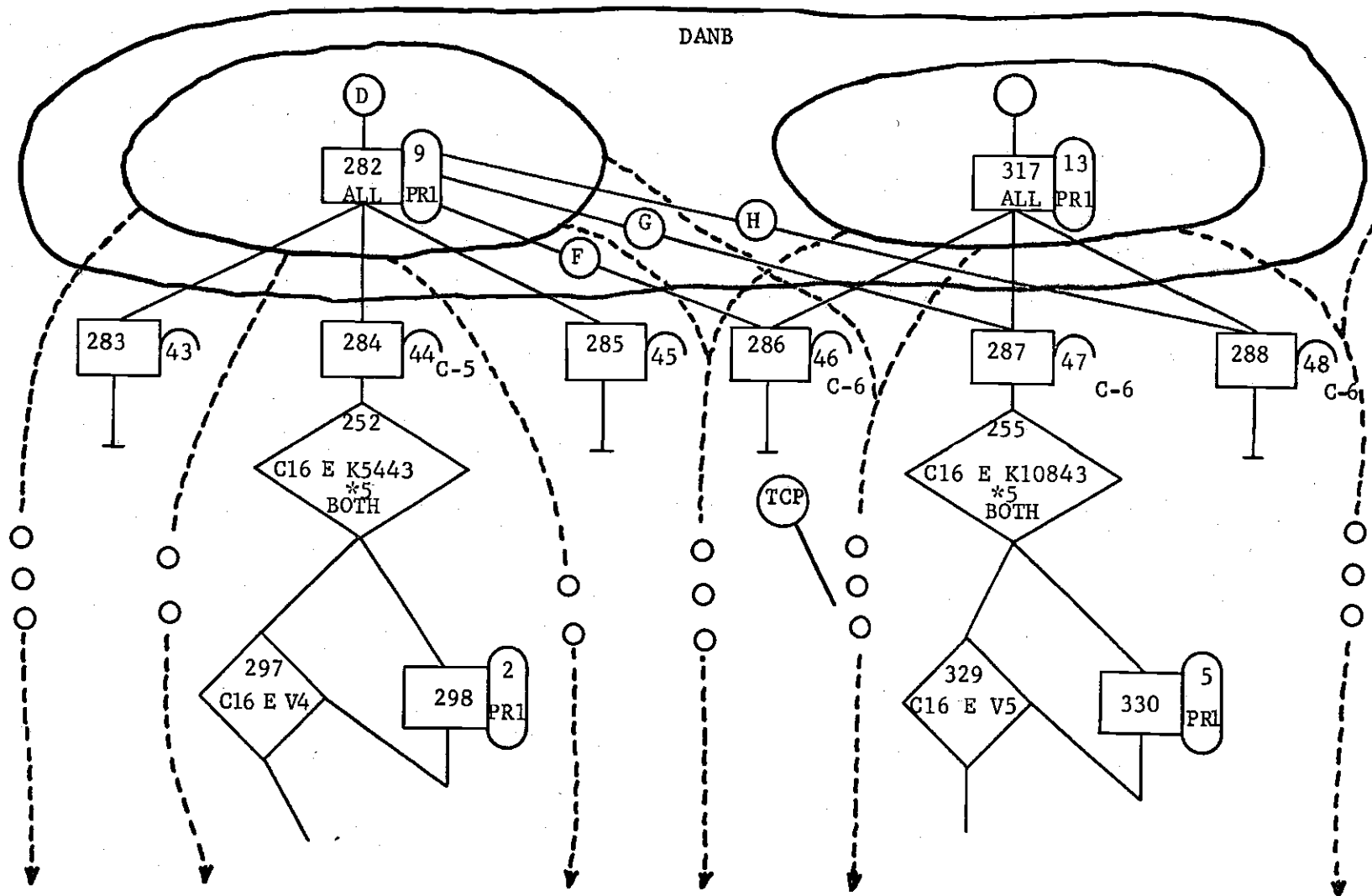


Figure 20. Southern Nonamphibious Vehicle Flow

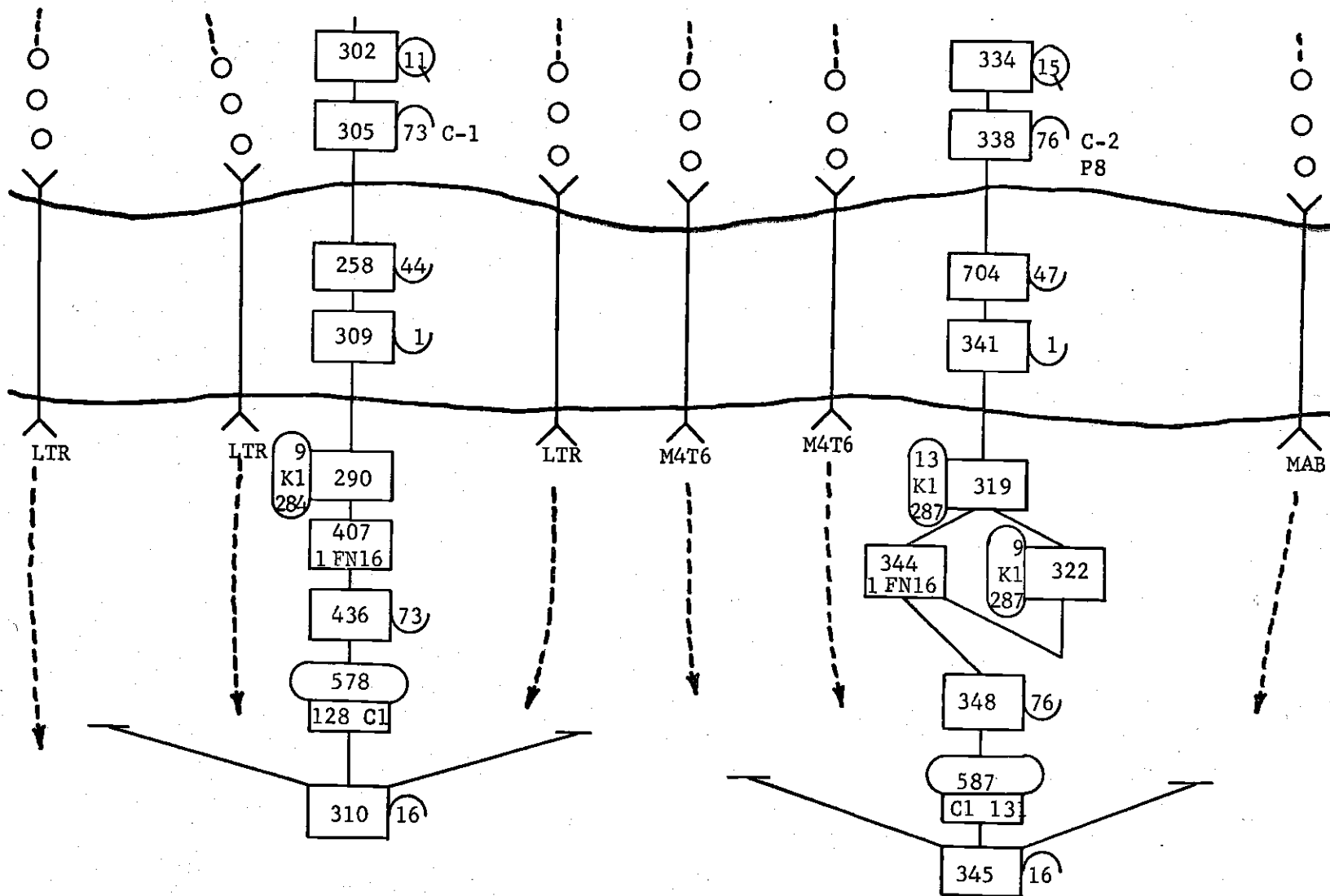


Figure 20. Concluded

The opening times for the LTR's, M4T6's, and MAB's are simulated by variables 4, 5, and 6, respectively.

Table 5. Southern River Crossing Equipment Opening Times

Equipment	Opening Time	Equivalent Computer Statement (Variable Statement)
LTR	K+1.0 hr	4 Variable X9+K3600
M4T6	K+2.5 hrs	5 Variable X9+K9000
MAB	K+1.2 hrs	6 Variable X9+K4320

K is the time the northern and southern engineers complete their river bank reconnaissance. The reconnaissance is simulated by the engineer portion of the Special Unit Processing Section (Appendix D). The opening times are stored in SAVEX cell 9 for the southern section and 11 for the northern section of the base model.

The flow of vehicles from the river crossing equipment queues to the far bank is also similar to the submodel flow. As a transaction enters an UNLINK block, for example block 290, the specification in the block indicates that one transaction is to be released from user chain 9, block 292, and sent to block 284. However, because all vehicles use the M4T6's and MAB's, an additional UNLINK block is required for this section. As a transaction leaves the CANB, block 341, it enters block 319, UNLINK 13. If transactions are waiting on this chain (the C2-C3 vehicle dispersal subarea), one transaction is sent to block 287 from the chain and the original transaction is directed to block 344. Block 344 simulates the

river crossing delay. If no transactions are on user chain 13, the original transaction is sent to block 322, UNLINK 9. Thus, having no transactions available on chain 13, the original transaction attempts to release a transaction from user chain 9 (the C4 vehicle dispersal subarea). After accomplishing this, the original transaction moves to block 344. This sequence insures that the heavier vehicles, the C2 and C3 vehicles, receive priority for the M4T6 and MAB river crossing equipment.

The only difference between the M4T6 and MAB flows is the capacity value of the ENTER blocks which represent the M4T6's and MAB. The M4T6 capacity is two; the MAB capacity is four. The capacities are placed in each transaction's parameter 8 by ASSIGN blocks as the transactions are identified as either C2, C3, or C4 vehicles.

After crossing the river, all transactions flow through SAVEX blocks which store their time of entry, and then enter either block 310 or 345, ENTER 16, the CAFB. River crossing equipment usage times are computed by the Statistics Gathering Section by variable statements which subtract the equipment opening time from last transaction entry time contained in the appropriate SAVEX cell. For example, the total usage time of the LTR simulated by ENTER storage 73 is obtained by subtracting the opening time of the LTR (the value of variable 4) from the time the last vehicle clears the LTR (the value in SAVEX cell 128, block 578).

#### Far Bank Nonamphibious Vehicle Flow

As the nonamphibious vehicles depart the rafts and enter the CAFB (Figure 21), they move directly to the Departure Area South Far Bank (DASFB); to the Holding Area South Far Bank (HASFB); and finally, to the objective area.



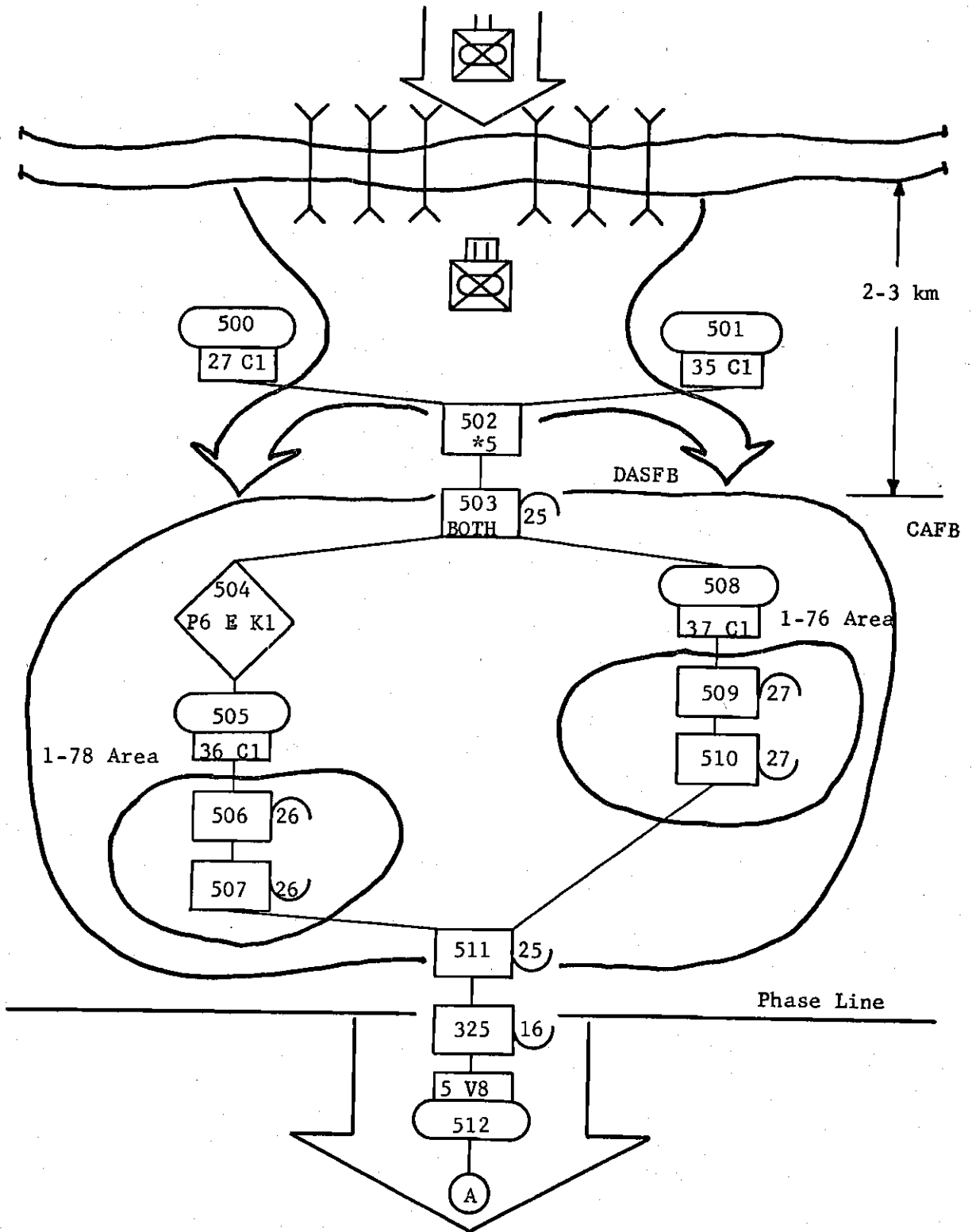


Figure 21. Southern Nonamphibious Vehicle Flow, CAFB

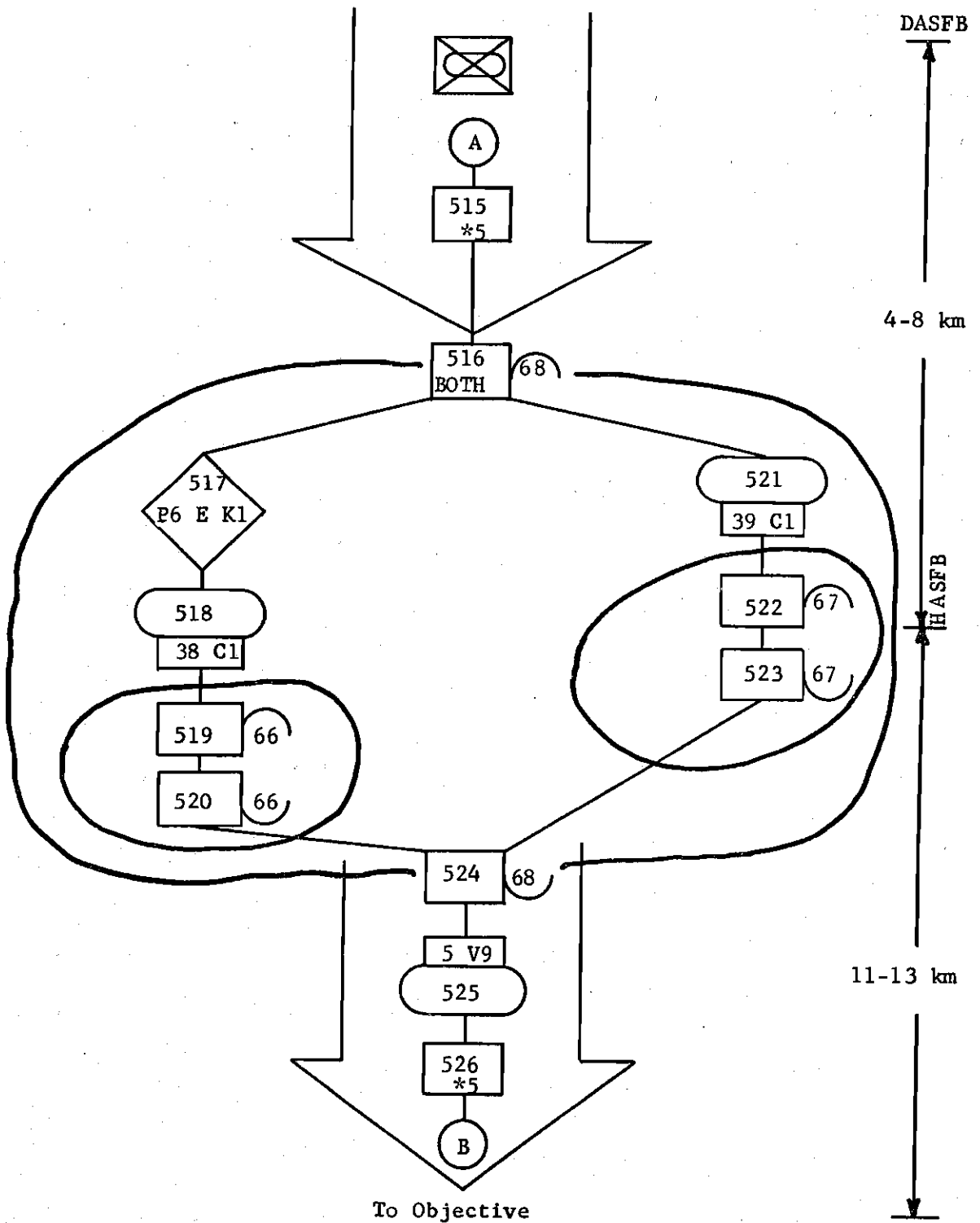


Figure 21. Concluded

SAVEX blocks 500 and 501 store the closing times of U1 and U2 in the CAFB and direct these units' transactions to ADVANCE block 502. This block delays each transaction for a simulated transit time equivalent to traveling 2-3 km at a 7 kph rate of movement. The transit time is effected by indirect specification to the value of each transaction's parameter 5, a value previously computed and placed in this location by ASSIGN blocks.

Upon entering the DASFB, simulated by ENTER storage 25, block 503, transactions proceed to their respective unit subareas. U1 transactions move to ENTER storage 26; U2's move to block 509, ENTER storage 27. SAVEX blocks 505 and 508 maintain the closing times of each unit. Both units depart the DASFB via block 511, LEAVE storage 25. Leaving the CAFB is simulated as transactions enter LEAVE storage 16, the CAFB. The value of variable 8, which represents the DASFB-HASFB transit time, is assigned to each transaction's parameter 5. This delay is also simulated by indirect specification to the value contained in parameter 5. The variable statement from which the delay is computed represents a uniformly distributed distance (4-8 km) divided by the rate of movement (7 kph). The distance range, as all others, is the minimum and maximum limit as measured from the CGSC problem topographical map.

After the transit time delay, vehicles enter the HASFB, ENTER storage 68, and are routed by the BOTH selection mode to their respective unit subareas, ENTER storage 66 and 67. As in the DASFB, the closing times of the units are stored in appropriate SAVEX cells. Transactions leave the HASFB as they enter block 524, LEAVE storage 68. Transit times are

assigned by ASSIGN block 525 to simulate the 11-13 km distance from the HASFB to the objective. The delay is simulated by ADVANCE block 526, from which the transactions enter block 482, ENTER storage 32, the objective (Fig. 18).

## CHAPTER IV

### EXPERIMENTATION

#### General

The experimental phase of this research was conducted in two stages. Initially, a series of computer runs was conducted to verify the base model logic and to compare the results to the data contained in the CGSC problem. Subsequent runs were made for seven base model configurations to examine the effect of the tactical formation and river crossing equipment availability on selected variables.

#### Initial Validation Runs

Approximately 100 computer runs were conducted during the verification and validation stage. The base model was structured in a manner analogous to the military symbology which can be used to visually portray a river crossing operation. Many parameters are available for manipulation; however, it is believed that the values selected are realistic and reflect the most accurate data available to the author from U. S. Army publications (30, 10, 9, 29, and 32). It is noted, moreover, that these data do not purport to imply a level of accuracy which could be obtained from empirical data gathered from actual river crossing field exercises.

Table 6 contains the base model results as they compare to selected critical variables from the CGSC problem.

Table 6. Comparison of Means (Hours)

River Crossing Equipment Type	Mean Equipment Usage		Percent Difference
	Base Model	CGSC Problem	
LTR	7.830	6.660	+ 17.5
M4T6	6.312	6.250	+ 0.19
MAB	7.239	5.300	+ 36.5
Bridge	1.180	1.200	- 1.66

Ten runs, using different random number seeds, of the base model were conducted and the 95 percent confidence intervals for the means were computed.

Table 7. Ninety-five Percent Confidence Intervals for Selected Sample Means

Variable	Mean (Hours)
LTR	7.88 $\pm$ 0.064
M4T6	6.37 $\pm$ 0.025
MAB	7.31 $\pm$ 0.073

### Initial Discussion of Results

The results contained in Table 6 indicate the model's results as compared to the CGSC problem. The 36.5 percent difference in the MAB usage means is believed to be caused by an underlying assumption used to compute the CGSC usage mean. This assumption is that the MAB ferries

operate at 100 percent capacity. The base model structure is such that the resulting MAB simulation indicates an 87-94 percent operating capacity, which appears to be more realistic when one considers that the capacity of the MAB permits all nonamphibious vehicles entry. The random nature of type vehicle arrivals indicates that all crossings will not be made at maximum capacity. Another factor causing these differences is the assumed routing of vehicles to each river crossing site. The base model simulates a routing such that vehicles use the crossing sites in their respective unit zone of action. The bridge was used by units which could logically arrive in the CANB at a time equal to or greater than the opening time.

A final significant factor which has probably affected the verification results is the parameter values assigned to the base model. Numerous parameters such as queue limitations, river ingress and egress times, uniformly distributed transit times, etc., have been incorporated into the simulation model to provide the user a realistic, flexible analytical tool. The methodology demonstrated by the CGSC problem does not consider these parameters.

#### Experimental Runs

Seven tactical formation and river crossing equipment combinations were simulated to examine their effects on selected variables. Each experiment is identified by a letter-digit code. The letter designates the type of tactical formation; the digit, the river crossing equipment availability (see Table 8).

Table 8. Experimental Runs

Formation	River Crossing Equipment Capability			
	Equipment Status			
	1	2	3	4
A	7 LTR	5 LTR	7 LTR	7 LTR
	4 M4T6	4 M4T6	2 M4T6	4 M4T6
	2 MAB	2 MAB	2 MAB	1 MAB
	1 Bridge	1 Bridge	1 Bridge	1 Bridge
B	7 LTR	5 LTR	7 LTR	
	4 M4T6	4 M4T6	2 M4T6	
	2 MAB	2 MAB	2 MAB	
	1 Bridge	1 Bridge	1 Bridge	

Formation A is the base model tactical configuration, Fig. 15.

Formation B is a variation of this configuration which decreases the Formation frontage. Instead of advancing on a wide front with four battalions of the assault echelon on line, Formation B is a narrower formation which uses a two-up, two-back formation. The assault battalions are deployed in a box-like shape; two forward, followed by two in the rear. Formation B, therefore, narrows the brigade front and increases the brigade depth.

#### River Crossing Time

The river crossing time is determined by the maximum river crossing equipment usage mean. In all experiments, the LTR's realized this value. This is predictable when one considers that approximately 73 percent of the nonamphibious vehicles in the brigade task organization are C4 type



vehicles. The crossing time is determined by subtracting the time the last vehicle clears a particular raft or ferry from the time that equipment opened. It does not include the Line of Departure to crossing site transit time or the time required for engineer reconnaissance.

Table 9. River Crossing Time (Hours)

Formation	Equipment Status			
	1	2	3	4
A	7.830	8.753 (+ 12%)	8.910 (+ 14%)	8.607 (+ 10%)
B	7.982 (+ 2%)	8.700 ( 11%)	8.997 (+ 15%)	

The most significant increase in river crossing time was caused by the loss of two, M4T6 rafts. These rafts accommodate all nonamphibious vehicles and are distributed equally between the two main crossing areas within the brigade zone. The type of formation did not appear to influence the crossing time in any equipment allocation.

#### Crossing Area Vehicle Density

The crossing area, the total area bounded by the CANB and CAFB, is an area especially critical to successful river crossing operations. The area contains all river crossing equipment and, therefore, offers the enemy a very lucrative nuclear target. Disregarding the critical nature of the equipment, one must still consider that the nature of the area is

such that vehicles tend to cluster and accumulate in it. The vehicle density, therefore, must be minimized in order to avoid offering the enemy a lucrative nuclear target.

Table 10. Crossing Area Vehicle Density

Formation	Equipment Status							
	1		2		3		4	
	CANB	CAFB	CANB	CAFB	CANB	CAFB	CANB	CAFB
A	660	180	693 (+ 5%)	186 (+ 3%)	691 (+ 5%)	187 (+ 4%)	776 (+ 17%)	228 (+ 27%)
B	659 (< 1%)	181 (< 1%)	684 (+ 4%)	186 (+ 3%)	684 (+ 4%)	185 (+ 3%)	--	--

As expected, the CANB density is far greater than the CAFB density. The formation did not appear to influence the density. However, the loss of the MAB did significantly increase both the CANB and CAFB vehicle density.

#### Mean Crossing Area Transit Time

The transit time through the CANB is the time required for a vehicle, either amphibious or nonamphibious, to move from the Line of Departure to the river. The CAFB transit time is the time required for a vehicle to move from the far bank to the Phase Line or Traffic Regulating Line used to delineate the CAFB boundary. This transit time is an indicator of a force's potential nuclear vulnerability.

Table 11. Mean Crossing Area Transit Times (Hours)

Formation	Equipment Status							
	1		2		3		4	
	CANB	CAFB	CANB	CAFB	CANB	CAFB	CANB	CAFB
A	4.080	1.300	4.293	1.345	4.278	1.356	4.806	1.652
			(+ 5%)	(+ 3%)	(+ 5%)	(+ 4%)	(+ 18%)	(+ 27%)
B	4.050	1.290	4.236	1.344	4.240	1.345	--	--
	(< 1%)	(< 1%)	(+ 4%)	(+ 3%)	(+ 4%)	(+ 3%)		

As found in the previous results, the time required to cross the CANB is significantly greater than that required to move through the CAFB. The formation, again, did not appear to influence this variable. However, the loss of the MAB did result in a significant increase in CANB and CAFB transit times.

#### Near Bank Dispersal Area Delays

Ideally, a crossing force moves without delay across the Line of Departure, through the CANB, across the river, and onto the objective area. Holding areas and dispersal areas are designated, however, to provide temporary assembly areas for vehicles outside of and within the crossing area as previously indicated in Fig. 1. The base model is structured so that it simulates a force which utilizes these areas. All combat, combat support, and combat service support vehicles move with their respective tactical units and, if delayed in transit, queue in either the C4, or C2-C3 subareas within the DANB. Vehicles are assigned

a movement priority and are directed onto the rafts and ferries as they become available. Thus, another variable related to a force's potential nuclear vulnerability is the delay time in the DANB.

Table 12. Nonamphibious Vehicle Mean Time Delay  
in Dispersal Areas Near Bank (Hours)

Formation	Equipment Status							
	1		2		3		4	
	C4	C2-C3	C4	C2-C3	C4	C2-C3	C4	C2-C3
A	5.060	3.940	6.032 (+ 19%)	3.958 (< 1%)	5.481 (+ 8%)	4.570 (+ 16%)	5.235 (+ 3%)	5.450 (+ 38%)
B	5.050 (< 1%)	3.810 (- 3%)	5.320 (+ 5%)	3.790 (- 4%)	5.380 (+ 6%)	4.421 (+ 12%)	--	--

Formations A and B do not differ significantly in their influence on the mean nonamphibious vehicle delay in the DANB. C2-C3 vehicles are delayed less than C4 vehicles in all experiments except A4, the loss of the MAB. This loss significantly increased the C2-C3 delay. The loss of two LTR's, experiment A2, indicated the most significant increase in the C4 vehicle subarea. The minimum time in the DANB was achieved by the equipment status 1, the maximum allocation.

#### Discussion of Results

The variation in tactical formation produced no significant change in the variables studied. Prior to conducting the final experimental

runs, a test run was made which simulated the B1 experimental configuration. The formation was changed to reflect the data contained in (30) and the resulting four battalion assault echelon force was structured to occupy an area two kilometers wide by two kilometers deep. Each battalion occupied one square kilometer and its vehicles were assumed to be uniformly distributed throughout the area. This configuration produced very little change in the data resulting from the A1 run. In an effort to determine whether or not the model was responsive to a formation variation, the depth of the four battalion assault echelon formation was increased by delaying rear battalions so that a 500 meter separation existed between them and the two lead battalions. This formation did yield results which indicated that the model was responsive to the change and the run was designated the B1 experiment. It would appear that increased depths will yield valid results. However, the direct relationship between the formation depth and the variables of interest requires further experimentation.

The variations of equipment allocations indicate that the MAB was the most critical piece of river crossing equipment. Although the loss of two M4T6's, experiment A2 and B2, did cause the longest mean crossing time, the potential nuclear vulnerability of the crossing force, as measured by the three variables, Figs. 10, 11, 12, was influenced most significantly by the loss of the MAB.

## CHAPTER V

### CONCLUSIONS AND RECOMMENDATIONS

#### General Comments

The base model is a GPSS II simulation model of one specific river crossing operation plan. All model parameters were determined from those applicable to the plan. The model may be adapted to simulate many different plans which involve varying terrain conditions, varying day and night movement conditions, varying crossing area depths and widths, and varying river crossing equipment allocations by assigning the proper values to the model parameters. As was previously pointed out, the results are predicated on the input data accuracy. It must be noted that the model interarrival times, distribution, and other parameter values are not based on empirical, observed data, but on data contained in the references previously cited which are taken from unclassified military sources.

#### Conclusions

1. The base model structure and logic, when expressed in a GPSS II flow diagram, afford a potential user an easily understandable symbology very analogous to the military symbology familiar to staff officers and service school students and instructors studying river crossing operations.
2. The base model provides the potential user an analytical tool

with which one may collect and evaluate quantitative data on selected critical variables and evaluate the interactions of these variables with regard to their effect on the river crossing plan options.

3. In addition to being an analytical aid to the military student and instructor, the base model provides a means by which current river crossing equipment operational capabilities, river crossing planning methodologies, and the data input used to determine the optimum equipment allocations may be quantitatively analyzed and validated by empirical data gathered from field tests and exercises.

4. The results obtained from the experimental runs indicate that the variable which most significantly influences a force's river crossing time and potential vulnerability to mass destruction weapons is the capability of the river crossing equipment allocated to the force.

5. Varying the four battalion assault echelon formation from a wide, on-line formation to one which is 50 percent narrower and 150 percent deeper does not significantly affect the crossing force vehicle density within the crossing area.

6. The loss of heavy river crossing equipment, either the M4T6 rafts or the MAB ferries, adversely affects a force's river crossing time more than the loss of light equipment such as LTR's, despite the fact that only approximately 27 percent of the nonamphibious vehicles require the heavy equipment. The loss of one MAB, moreover, appears to have the most adverse effect on the variables indicating potential nuclear vulnerability. Thus, of the three types of rafting and ferrying equipment allocated to the base model crossing force, the MAB seems to be the most critical.

### Recommendations

1. Further study of the model structure developed in this study should be conducted to determine modifications which will decrease the computer run time while maintaining the present number of variables and parameters available for analysis.
2. Should empirical data become available for input to the model, sufficient replications of experimental runs should be conducted to provide a statistical basis for more exhaustive analysis of the data currently used for determining river crossing plan options.
3. Further experiments should be conducted to determine the "optimum" tactical formation with regard to achieving desirable levels of vehicle densities and delays within the river crossing area. A critical question is whether or not this "optimum" formation would provide mutual support among subunits.
4. In that the division is the smallest unit possessing organic river crossing equipment, it is recommended that, concomitant with the above recommendations, the base model be enlarged to simulate this force size operation.
5. A simulation model is very inexpensive to use when compared to actual maneuvers involving river crossing operations. It is, therefore, an appealing research tool. Empirical data from various small unit river crossing operations could be gathered, synthesized, and used to validate the larger unit base model. This tactic recognizes the financial limitations which hinder the gathering of empirical data from large unit river crossing operations and would enhance the appealing nature of the simulation model by increasing the model validity and accuracy.



## APPENDICES

## APPENDIX A

### RIVER CROSSING EQUIPMENT CHARACTERISTICS

#### General

The division's organic river crossing equipment is contained in the division engineer battalion's bridge company. The bridge company consists of a headquarters, an armored vehicle launched bridge (AVLB) platoon, and either two heavy raft platoons equipped with Mobile Assault Bridges (MAB's) or two bridge platoons equipped with M4T6 or class 60 bridging. In addition to the MAB, M4T6, or class 60 bridging, the bridge company provides reconnaissance boats and Light Tactical Rafts (LTR's) to support river crossing operations.

#### Mobile Assault Bridge

The MAB consists of individual amphibious vehicles which, when joined together, form a class 60 bridge. Each vehicle can move on roads up to speeds of 55 kph and in the water at speeds up to 11 kph. The floor of the bridge is mounted on top of and parallel to the long axis of the vehicle. The floor is turned perpendicular to the long axis of the vehicle to form the bridge. When equipped with MAB's, the bridge company has the capability to construct one 144 meter bridge; two 80 meter bridges; or four 48 meter self-propelled ferries (30).

### M4T6 Bridging

The M4T6 bridging is a combination of M4 and class 60 equipment. The superstructure of the bridge is M4 equipment and the rubber pneumatic floats come from the class 60. Unlike the MAB, the M4T6 is not self propelled. The bridge must be carried in sections by prime movers to the crossing site, assembled, and placed into the water. When used as rafts, the M4T6 is propelled by power boats. The M4T6 can be used as one 170 meter class 50 float bridge, or eight class 50 rafts (30).

### Light Tactical Rafts

Two sets of LTR's are allocated to each divisional engineer battalion. Like the M4T6, the LTR must be transported by prime movers to the crossing sites and requires an external source of power when used as rafts. Each LTR set may be used as one 4-pontoon raft, or one 44 foot class 12 bridge (30).

### Armored Vehicle Launched Bridge

The AVLB is used to quickly span short gaps less than 60 feet in width. The bridge is hinged in the middle of its span and is mounted on top of a tank chassis. When employed, the bridge unfolds--sissors-like--onto the gap. The bridge can be launched in less than two minutes and can be retrieved from either end in less than ten minutes. The maximum crossing capacity is 75 tons (30).

## APPENDIX B

## BRIGADE AND BASE MODEL TASK ORGANIZATIONS

Table 13. Brigade Task Organization and Vehicle Types

Unit	Vehicle Types		
	C1	C4	C2-C3
Bde HQ	13	32	1
1-76 Mech Inf	83	68	20
1-77 Mech Inf	83	68	20
1-78 Mech Inf	83	68	20
1-4 Arm	33	67	83
1-23 Cav	117	77	28
63d Arty Gp HQ	0	41	0
1-40 Arty (155, SP)	46	92	33
1-651 Arty (155, towed)	0	86	41
1-652 Arty (155, towed)	0	86	41
A/1-441 Arty (Vulcan)	19	46	4
A/52d Engr	10	12	7
D/52d Engr	10	12	7
AVLB Sec	0	0	3
Hv Raft Plat	12	7	0
Fwd Comd Tml Tm	0	4	0
MP Plat	0	10	0
Fwd Spt Co	0	30	2
Med Co	0	27	0
Fwd Sup Sec	0	2	0
TOTAL	509	835	310 = 1634 Vehicles
Corps/Army Engineers*			<u>274 Vehicles</u>
GRAND TOTAL			1938 Vehicles

\*The Corps and Army Engineer vehicles remain in the near bank and far bank engineer parks and contribute to the cross-area vehicle densities.

Table 14. Base Model Task Organization

ASSAULT ECHELON			
NORTHERN AREA	TOTAL VEHICLES	SOUTHERN AREA	TOTAL VEHICLES
TF 1-77 Mech Inf*	266	TF 1-78 Mech Inf*	266
A/1-4 Arm		B/1-4 Arm	
Plat/A/52 Engr		Plat/A/52 Engr	
1-40 Arty (-)		1-40 Arty	
1-23 Cav*	212	1-76 Mech Inf (-)*	156
Plat/1-441 Arty*	7	Plat/A/52 Engr	
		A/1-441 Arty (-)*	58
		Bde TAC CP*	8
ENGINEER ECHELON			
NORTHERN AREA	TOTAL VEHICLES	SOUTHERN AREA	TOTAL VEHICLES
Nothern Engineers*	164	Southern Engineers*	156
61 Engr Gp		61 Engr Gp (-)	
D/52 Engr		D/52 Engr	
AVLB Sec		AVLB Sec	
Hvy Raft		Hvy Raft	
RESERVE			
UNIT			TOTAL VEHICLES
1-4 Arm*			135
FIRE SUPPORT ECHELON			
UNIT			TOTAL VEHICLES
1-651 Arty*			102
1-652 Arty*			102
FOLLOW-UP AND REAR ECHELONS			
UNIT			TOTAL VEHICLES
Unit trains and combat			
service support elements			306
from all units			
TOTAL VEHICLES ENTERING BRIGADE AREA			1938

\* Indicates unit generator for unit with asterisk and all immediately below.

## APPENDIX C

## BASE MODEL COMPUTER LISTING

	JOB	161507247501
1	CAPACITY	1938 TOT VEH EN CANB INCL 299 ENGR VEH AND 1639 VEH ATCH BOE
2	CAPACITY	15 CS7NB
3	CAPACITY	15 CS6NB
4	CAPACITY	15 CS5NB
5	CAPACITY	15 CS7FB
6	CAPACITY	15 CS6FB
7	CAPACITY	15 CS5FB
8	CAPACITY	15 CS4NB
9	CAPACITY	15 CS3NB
10	CAPACITY	15 CS2NB
11	CAPACITY	15 CS4FB
12	CAPACITY	15 CS3FB
13	CAPACITY	15 CS2FB
14	CAPACITY	7 AAA PLAT SECURITY POSN VIC CSS
15	CAPACITY	58 AAA BTRY(-) POSN VIC CSN
16	CAPACITY	1938 CAFB
17	CAPACITY	11 ENGR PK FBS
18	CAPACITY	145 ENGR PK NBS
19	CAPACITY	11 ENGR PK FBN
20	CAPACITY	153 ENGR PK NBN
21	CAPACITY	2 MAB 2
22	CAPACITY	2 MAB 2
23	CAPACITY	2 MAB 1
24	CAPACITY	2 MAB 1
25	CAPACITY	257 DASFB
26	CAPACITY	157 U1AREA DASFB
27	CAPACITY	88 U2AREA DASFB
29	CAPACITY	109 U1 ALIGN AREA
30	CAPACITY	68 U2 ALIGN AREA
31	CAPACITY	185 U1U2U6 C1 ARR PL
32	CAPACITY	450 U1U2U6 ARR OBJ
33	CAPACITY	109 U3 ALIGN AREA
34	CAPACITY	117 U5 ALIGN AREA
35	CAPACITY	226 U3U5 ARR PL
36	CAPACITY	478 U3U5 OBJ
37	CAPACITY	252 DANFB
38	CAPACITY	157 U3AREA DANFB
39	CAPACITY	95 U5AREA DANFB
40	CAPACITY	252 HANFB
41	CAPACITY	157 U3AREA HANFB
42	CAPACITY	95 U5AREA HANFB
43	CAPACITY	5
44	CAPACITY	5
45	CAPACITY	5
46	CAPACITY	6
47	CAPACITY	6
48	CAPACITY	6
49	CAPACITY	35 SFS AREA U4C1C2
50	CAPACITY	25 U4 ALIGN S
51	CAPACITY	135 U4 ASMBY AREA
53	CAPACITY	5 LTR4
54	CAPACITY	5 LTR 3

55	CAPACITY	5	LTR 2	
56	CAPACITY	5	LTR 1	
57	CAPACITY	6		
58	CAPACITY	6		
59	CAPACITY	6		
60	CAPACITY	8	U6 ALIGN	
61	CAPACITY	12	U6AREA DASFB	
62	CAPACITY	12	U6AREA HASFB	
63	CAPACITY	7	BRIDGE	
64	CAPACITY	204	U11U12 FPF8	
65	CAPACITY	102	U12 FP VIC LD	
66	CAPACITY	200		
67	CAPACITY	100		
68	CAPACITY	450		
70	CAPACITY	34	NFS AREA U4C1C2	
71	CAPACITY	24	U4 ALIGN N	
72	CAPACITY	1		
73	CAPACITY	1		
74	CAPACITY	1		
75	CAPACITY	2		
76	CAPACITY	2		
77	CAPACITY	4		
80	CAPACITY	1		
81	CAPACITY	1		
82	CAPACITY	1		
83	CAPACITY	1		
84	CAPACITY	2		
85	CAPACITY	2		
86	CAPACITY	4		
1	VARIABLE	FN1*K3600/P4/K10		TT LD-CSNB TT CSFB-PL 4-7KM
2	VARIABLE	FN2*K3600/FN3/K100		TT RIVER(100-175M)/(3-5KPH)
3	VARIABLE	FN5*K3600/P4/K10		TT LD-DA TT DA-CS 2-3KM
4	VARIABLE	X9+K3600		LTR OPEN K+1 S
5	VARIABLE	X9+K9000		M4T6 OPEN K+2.5 S
6	VARIABLE	X9+K4320		MAB OPEN K+1.2
7	VARIABLE	FN4*K3600/P4/K10		TT PL-OBJ N
8	VARIABLE	FN6*K3600/P4/K10		TT DASFB-HASFB 4-6KM
9	VARIABLE	FN7*K3600/P4/K10		TT HASFB-OBJ 11-13KM
10	VARIABLE	FN8*K3600/P4/K10		TT RIV-PL N 5.5-6.5KM
11	VARIABLE	FN9*K3600/P4/K10		TT PL-OBJ N 9-12KM
12	VARIABLE	FN12*K3600/P4/K10		TT 1-4ARM AA-OBJ 17-19KM
13	VARIABLE	X11+K3600		LTR N OPEN K+1
14	VARIABLE	X11+K9000		M4T6 N OPEN K+2.5
15	VARIABLE	X11+K4320		MAB N OPEN K+1.2
16	VARIABLE	X11+K23400		BRIDGE OPEN K+6.5
17	VARIABLE	FN15*K3600/P4/K10		TT RIV-PL N TRNS 7-8KM
18	VARIABLE	X11+K21240		
19	VARIABLE	N654+N693		
20	VARIABLE	X120-V13		
21	VARIABLE	X121-V13		
22	VARIABLE	X122-V13		
23	VARIABLE	X123-V13		
24	VARIABLE	X124-V14		
25	VARIABLE	X125-V14		
26	VARIABLE	X126-V15		
27	VARIABLE	X127-V4		
28	VARIABLE	X128-V4		

29	VARIABLE	X129-V4					
30	VARIABLE	X130-V5					
31	VARIABLE	X131-V5					
32	VARIABLE	X132-V6					
33	VARIABLE	X104-X103					
1	FUNCTION	RN1	C2	D LD-RIV	4-7KM		
0	40 1.0	70					
2	FUNCTION	RN1	C2	RIV WIDTH	100-175M		
0	100 1.0	175					
3	FUNCTION	RN1	C2	C1 AMPHIB VEL	3-5KPH		
0	30 1.0	50					
4	FUNCTION	RN1	C2	D PL-OBJ	10-12KM		
0	100 1.0	120					
5	FUNCTION	RN1	C2	D LD-DA DA-CSNB	2-3KM		
0	20 1.0	30					
6	FUNCTION	RN1	C2	D DASFB-HASFB	4-6KM		
0	40 1.0	60					
7	FUNCTION	RN1	C2	D HASFB-OBJ	11-13KM		
0	110 1.0	130					
8	FUNCTION	RN1	C2	D RIV-PL N	5.5-6.5KM		
0	55 1.0	65					
9	FUNCTION	RN1	C2	D PL-OBJ N	9-12KM		
0	90 1.0	120					
10	FUNCTION	P6	D4	ASGN U1C2PR7 U2C2PR6 U4C2PR4 U6C2PR5			
1.0	7.0 2.0	6.0 4.0	4.0 6.0 5.0				
11	FUNCTION	P6	D4	ASGN U1C3C4PR3 U2C3C4PR2 U4C3C4PR0 U6C3C4PR1			
1.0	3.0 2.0	2.0 4.0	0.0 6.0 1.0				
12	FUNCTION	RN1	C2	D PL-OBJ U4	17-19KM		
0	17 1.0	19					
13	FUNCTION	P6	D4	ASGN U3C2PR7 U5C2PR6 U4C2PR5 U6PR4			
3.0	7.0 4.0	5.0 5.0	6.0 6.0 4.0				
14	FUNCTION	P6	D4	ASGN U3C3C4PR3 U5C3C4PR2 U4C3C4PR0 U6C3C4 PR1			
3.0	3.0 4.0	0.0 5.0	2.0 6.0 1.0				
15	FUNCTION	RN1	C2	D RIV-PL N	7-8KM		
0	70 1.0	80					
16	FUNCTION	RN1	C2				
0	450 1	900					
17	FUNCTION	P8	D3				
5	163 6	164 7	165				
18	FUNCTION	P8	D3				
11	200 12	201 13	202				
1	TABLE	MP7	820	60	14		
2	TABLE	MP7	820	60	14		
3	TABLE	IA	400	60	10		
4	TABLE	IA	200	60	15		
5	TABLE	IA	100	60	10		
6	TABLE	IA	400	60	10		
7	TABLE	IA	300	60	15		
8	TABLE	IA	100	60	10		
*			TF1-78 AND TF1-77 GENERATORS				
1	ORIGINATE	0	266	2	3	1	
2	ASSIGN	3	K1	ALL	3	6	
3	COMPARE	N2	LE	K109	7		P3 ASLT ECHELN
4	COMPARE	N2	LE	K216	8		C1 VEH 109
5	COMPARE	N2	LE	K233	9		C4 VEH 107
6	ASSIGN	1	K3		10		C2 VEH 17
7	ASSIGN	1	K1		10		C3 VEH 33



8	ASSIGN	1	K4	10			
9	ASSIGN	1	K2	10			
10	SPLIT			11	27		
11	ASSIGN	6	K1	12			U1 TF1-78
12	ENTER	1		13			U1 EN CANB
13	SAVEX	15	C1	140			TM U1 CL CANB
27	ASSIGN	6	K3	28			U3 TF1-77
28	ENTER	1		29			U3 EN CANB
29	SAVEX	17	C1	177			TM U3 CL CANB
* 1-76 GENERATOR							
15	ORIGINATE	0	156	16	3	1	
16	ASSIGN	3	K1	17			P3 ASLT ECHELN
17	ASSIGN	6	K2	18	21		U2 1-76
18	COMPARE	N17	LE K68	22			C1 VEH 68
19	COMPARE	N17	LE K134	23			C4 VEH 66
20	COMPARE	N17	LE K151	24			C2 VEH 17
21	ASSIGN	1	K3	25			C3 VEH 5
22	ASSIGN	1	K1	25			
23	ASSIGN	1	K4	25			
24	ASSIGN	1	K2	25			
25	ENTER	1		26			U2 EN CANB
26	SAVEX	16	C1	140			TM U2 CL CANB
* 1-23 CAV GENERATOR							
30	ORIGINATE	0	212	31	3	1	
31	ASSIGN	3	K1	32			P3 ASLT ECHELN
32	ASSIGN	6	K5	33	35		U5 1-23 CAV
33	COMPARE	N32	LE K117	36			C1 VEH 117
34	COMPARE	N32	LE K186	37			C4 VEH 69
35	ASSIGN	1	K3	38			C3 VEH 26
36	ASSIGN	1	K1	38			
37	ASSIGN	1	K4	38			
38	ENTER	1		39			U5 EN CANB
39	SAVEX	18	C1	177			TM U5 EN CANB
* AAA PLATOON GENERATOR (FOLLOWS TF 1-77)							
40	GENERATE	0	7	41	3	1	
41	COMPARE	N28	E K266 BOTH	42	44		
42	COMPARE	N41	E K1	43			
43	SAVEX	1	C1	44			LD TM AAA PLAT
44	ADVANCE			45	47		
45	COMPARE	N44	LE K5	48			C1 VEH 5
46	COMPARE	N44	LE K6	49			C4 VEH 1
47	ASSIGN	1	K3	50			C3 VEH 1
48	ASSIGN	1	K1	50			
49	ASSIGN	1	K4	50			
50	ASSIGN	6	K7	51			U7 AAA
51	ASSIGN	3	K1	52			P3 ASLT ECHELN
52	ENTER	1		53			U7 EN CANB
53	SAVEX	19	C1	115			TM U7 CL CANB
* BDE TAC CP GENERATOR (FOLLOWS 1-76)							
55	GENERATE	0	8	56	3	1	
56	COMPARE	N25	E K156	60			
60	ASSIGN	1	K1	62			
62	ASSIGN	3	K1	63			P3 ASLT ECHELN
63	ASSIGN	6	K6	64			U6 BDE TAC CP
64	ENTER	1		65			U6 EN CANB
65	SAVEX	20	C1	140			TM U6 CL CANB
* AAA BTRY(-) GENERATOR (FOLLOWS TF 1-78)							

66	GENERATE	0	58		67	3	1	
67	COMPARE	N12	E	K266 BOTH	68	70		
68	COMPARE	N67	E	K1	69			
69	SAVEX	3	C1		70			LD TM AAA(-)
70	ADVANCE			ALL	71	73		
71	COMPARE	N70	LE	K14	74			C1 VEH 14
72	COMPARE	N70	LE	K55	75			C4 VEH 41
73	ASSIGN	1	K3		76			C3 VEH 3
74	ASSIGN	1	K1		76			
75	ASSIGN	1	K4		76			
76	ASSIGN	3	K1		77			P3 ASLT ECHELN
77	ASSIGN	6	K7		78			U7 AAA(-)
78	ENTER	1			79			U7 EN CANB
79	SAVEX	21	C1		126			TM U7 CL CANB
* 1-4ARMOR GENERATOR (FOLLOWS BDE TAC CP)								
80	GENERATE	0	135		81	3	1	
81	COMPARE	N64	E	K8 BOTH	82	84		
82	COMPARE	N81	E	K1	83			
83	SAVEX	5	C1		84			LD TM U4
84	ASSIGN	4	K7	ALL	85	88		P4 VEL 7KPH
85	COMPARE	N84	LE	K49	89			C1 VEH 49
86	COMPARE	N84	LE	K87	90			C4 VEH 38
87	COMPARE	N84	LE	K107	91			C2 VEH 20
88	ASSIGN	1	K3		92			C3 VEH 28
89	ASSIGN	1	K1		92			
90	ASSIGN	1	K4		92			
91	ASSIGN	1	K2		92			
92	ASSIGN	6	K4		93			U4 TF1-4ARMOR
93	ASSIGN	3	K1		94			P3 ASLT ECHELN
94	ENTER	1			95			EN CANB
95	SAVEX	22	C1		625			TM U4 CL CANB
* SOUTHERN ENGINEER GENERATOR (FOLLOWS AAA PLAT)								
96	GENERATE	0	156		97	9	2	
97	COMPARE	N52	E	K7	100			
100	ASSIGN	3	K3		101			P3 ENGR ECHELN
101	ASSIGN	6	K8		102			U8 ENGINEERS
102	ENTER	1			103			EN CANB
103	SAVEX	23	C1	BOTH	104	215		TM U8S CL CANB
104	COMPARE	N103	LE	K11	113			
113	ASSIGN	1	K1		215			11C1VEH ENGR S
* NORTHERN ENGINEER GENERATOR (FOLLOWS AAA BTRY(-))								
105	GENERATE	0	164		106	9	2	
106	COMPARE	N78	E	K58	109			
109	ASSIGN	3	K3		110			P3 FNGR ECHELN
110	ASSIGN	6	K8		111			U8 ENGINEERS
111	ENTER	1			112			EN CANB
112	SAVEX	24	C1	BOTH	114	235		TM U8N CL CANB
114	COMPARE	N112	LE	K11	123			
123	ASSIGN	1	K1		235			11C1VEH ENGR N
* AAA PLAT MOVES FR LD-CROSSING SITES-FIRING POSN								
115	ASSIGN	4	K7		116			P4 VEL 7KPH
116	ASSIGN	5	V1		117			TM=4-7KM/7KPH
117	ADVANCE				118	*5		TT LD-RIVER
118	SAVEX	6	C1		119			TM AAAN CL RIV
119	STORE	14			120			EN FIRE POSN
120	COMPARE	N724	GE	K510	121			
121	SAVEX	91	C1		232			TN AAAN LV

\* AAA BTRY(-) MOVES FR LD-CROSSING SITES-FIRING POSN

126	ASSIGN	4	K7		127			P4 VEL 7KPH
127	ASSIGN	5	V1		128			TM=4-7KM/7KPH
128	ADVANCE				129	*5		TT LD-RIVER
129	SAVEX	7	C1		130			TM AAAS CL RIV
130	STORE	15			131			EN FIRE POSN
131	GATE	LS20			132			
132	SAVEX	92	C1		133			TM AAAS LV
133	LOGIC	I20			59	640		
59	COMPARE	P1	E	K1	122			
122	ADVANCE				PICK	145	147	
61	ASSIGN	8	K2		ALL	743	745	
384	GENERATE	0	58		385		3	1
385	COMPARE	N648	GE	K43	386			
386	LOGIC	I20			800			
640	ADVANCE				BOTH	498	499	
498	COMPARE	N640	LE	K3	61			
499	ASSIGN	8	K1		ALL	740	745	
740	ENTER	43			301			
741	ENTER	44			302			
742	ENTER	45			303			
743	ENTER	46			333			
744	ENTER	47			334			
745	ENTER	48			335			

\* SOUTHERN AMPHIBIOUS VEHICLE FLOW

\*VEHICLES MOVE FROM LD TO CROSSING SITES,CROSS RIVER AND MOVE TO ALIGNMENT AREA  
\*ON FAR BANK.

\*THIS FLOW BEGINS AT CANB-LD AND CARRIES VEH TO THE FAR BANK CAFB

140	ADVANCE				BOTH	141	260	
141	COMPARE	P1	E	K1		142		
142	ASSIGN	4	K7			143		P4 VEL 7KPH
143	ASSIGN	5	V1			144		TM=4-7KM/7KPH
144	ADVANCE				PICK	145	147	*5
145	ASSIGN	8	K5			148		CSNB-CSFB
146	ASSIGN	8	K6			149		CSNB-CSFB
147	ASSIGN	8	K7			150		CSNB-CSFB
148	QUEUE	1				151		CS7NB Q
149	QUEUE	2				152		CS6NB Q
150	QUEUE	3				153		CS5NB Q
151	ENTER	2				154		S C1 EN CS7NB
152	ENTER	3				155		S C1 EN CS6NB
153	ENTER	4				156		S C1 EN CS5NB
154	LEAVE	1				157	8	3
155	LEAVE	1				158	8	3
156	LEAVE	1				159	8	3
157	LEAVE	2				160		
158	LEAVE	3				160		
159	LEAVE	4				160		
160	ASSIGN	2	V2			161		TT RIVER
161	QUEUE	4				162	*2	TM IN RIVER
162	GATE	SNF*8			FN	17		CSNB-CSFB
163	STORE	5				166	10	5
164	STORE	6				166	10	5
165	STORE	7				166	10	5
166	ENTER	16			BOTH	167	169	S5 CS7FB
167	COMPARE	P3	E	K1		168		S6 CS6FB
168	SAVEX	13	C1			169		S7 CS5FB

CAFB

TM SC1 X RIVER

169	ADVANCE				ALL	170	176		SEG BY UNIT
170	COMPARE	P6	E	K1	BOTH	450	500		U1 TF1-78
171	COMPARE	P6	E	K2	BOTH	460	501		U2 1-76
172	COMPARE	P6	E	K6	BOTH	730	740		U6 BDE TAC CP
173	COMPARE	P6	E	K8		219			U8 ENGR
174	COMPARE	P6	E	K7		233			
175	COMPARE	P6	E	K4	BOTH	641	648		U4 1-4ARMOR
176	ADVANCE					799			EXTRA
* NORTHERN AMPHIBIOUS VEHICLE FLOW									
177	ADVANCE				BOTH	178	350		
178	COMPARE	P1	E	K1		179			
179	ASSIGN	4		K7		180			P4 VEL 7KPH
180	ASSIGN	5		V1		181			TM=4-7KM/7KPH
181	ADVANCE				PICK	182	184	*5	TT LD-CS2,3,4
182	ASSIGN	8		K11		185			CSNB-CSFB
183	ASSIGN	8		K12		186			CSNB-CSFB
184	ASSIGN	8		K13		187			CSNB-CSFB
185	QUEUE	5				188			CS4NB Q
186	QUEUE	6				189			CS3NB Q
187	QUEUE	7				190			CS2NB Q
188	ENTER	8				191			S C1 EN CS4NB
189	ENTER	9				192			S C1 EN CS3NB
190	ENTER	10				193			S C1 EN CS2NB
191	LEAVE	1				194	8	3	
192	LEAVE	1				195	8	3	
193	LEAVE	1				196	8	3	
194	LEAVE	8				197			
195	LEAVE	9				197			
196	LEAVE	10				197			
197	ASSIGN	2		V2		198			TT RIVER
198	QUEUE	8				199		*2	TM IN RIVER
199	GATE	SNF*8			FN	18			CSNB-CSFB
200	STORE	11				203	10	5	S11 CS4FB
201	STORE	12				203	10	5	S12 CS3FB
202	STORE	13				203	10	5	S13 CS2FB
203	ENTER	16			BOTH	204	206		CAFB
204	COMPARE	P3	E	K1		205			
205	SAVEX	14		C1		206			
206	ADVANCE				ALL	207	213		TM NC1 X RIVER
207	COMPARE	P6	E	K3	BOTH	550	600		SEG BY UNIT
208	COMPARE	P6	E	K5	BOTH	560	601		U3 TF1-77
209	COMPARE	P6	E	K8		239			U5 1-23CAV
210	COMPARE	P6	E	K6		730			U8 ENGR
211	COMPARE	P6	E	K7		799			
212	COMPARE	P6	E	K4	BOTH	680	687		U7 AAA
213	ADVANCE					725			U4 1-4ARMOR
* ENGINEER UNITS MOVE TO RIVER, RECON NB-FB									
215	ASSIGN	4		K7		216			U11-12ATCHARTY
216	ASSIGN	5		V1		217			P4 VEL 7KPH
217	ADVANCE				BOTH	218	225	*5	TM=4-7KM/7KPH
218	COMPARE	P1	E	K1		145			TT LD-RIVER
219	ADVANCE					220	1200	300	C1 SWIM
220	SAVEX	8		C1		495			RECCE
495	ENTER	16				221			TM RECCE FIN S
221	ENTER	17				224			
224	SAVEX	71		C1		799			EN ENGR PK FBS
225	ADVANCE				BOTH	98	226		TM ENPFBFS FULL

98	COMPARE	N225	E	K1	99			
99	SAVEX	9	C1		226			
226	ADVANCE				227	1200	300	RECCE
227	ENTER	18			230			EN ENGR PK NBS
230	SAVEX	72	C1		799			TM EPNBS FULL
235	ASSIGN	4	K7		236			P4 VEL 7KPH
236	ASSIGN	5	V1		237			TM=4-7KM/7KPH
237	ADVANCE			BOTH	238	245	*5	TT RIVER
238	COMPARE	P1	E	K1	182			C1 SWIM
239	ADVANCE				240	1200	300	RECCE
240	SAVEX	10	C1		496			TM RECCE FIN N
496	ENTER	16			241			
241	ENTER	19			244			EN ENGR PK FBN
244	SAVEX	73	C1		799			TM ENPFBN FULL
245	ADVANCE			BOTH	107	246		
107	COMPARE	N245	E	K1	108			
108	SAVEX	11	C1		246			
246	ADVANCE				247	1200	300	RECCE
247	ENTER	20			250			EN ENGR PK NBN
250	SAVEX	74	C1		799			TM EPNBN FULL
* SOUTHERN C2-4 VEHICLE SECTION								
*NON-AMPHIBIOUS VEHICLES MOVE FROM LD-DA-RIVER ALL C2 AND C3 VEH USE M4T6 OR MAB								
*RHFTS C4 VEH USE LTR								
260	ASSIGN	4	K7		261			P4 VEL 7KPH
261	ASSIGN	5	V3		262			TM=2-3KM/7KPH
262	MARK	7			263			
263	ADVANCE			ALL	264	270	*5	TT LD-OAS 2-3K
264	COMPARE	P6	E	K1	271			
265	COMPARE	P6	E	K2	272			
266	COMPARE	P6	E	K6	273			
267	COMPARE	P6	E	K8	274			
268	COMPARE	P6	E	K7	275			
269	COMPARE	P6	E	K4	276			
270	ADVANCE				277			
271	SAVEX	75	C1		278			U1C2-4CL DASNB
272	SAVEX	76	C1		278			U2C2-4CL DASNB
273	SAVEX	77	C1		278			U6C2-4CL DASNB
274	SAVEX	78	C1		278			U8C2-4CL DASNB
275	SAVEX	79	C1		278			U7C2-4CL DASNB
276	SAVEX	80	C1		278			U4C2-4CL DASNB
277	SAVEX	81	C1		278			U9C2-4CL DASNB
278	TABULATE	1		BOTH	279	311		
279	COMPARE	P1	E	K4	280			
280	ASSIGN	7	FN11		281			
*ABOVE ASSIGNS PRIORITIES U1C4PR3 U2C4PR2 U4C4PR0 U6C4PR1								
281	PRIORITY	*7			478			
478	ASSIGN	8	K1		282			
282	LINK	9	PR1	ALL	283	288		
283	ENTER	43			251			
284	ENTER	44			252			
285	ENTER	45			253			
286	ENTER	46			254			
287	ENTER	47			255			
288	ENTER	48			256			
251	COMPARE	C1	GE	K5443 BOTH	295	296	*5	
252	COMPARE	C1	GE	K5443 BOTH	297	298	*5	
253	COMPARE	C1	GE	K5443 BOTH	299	300	*5	

254	COMPARE	C1	GE	K10843BOTH	327	328	*5
255	COMPARE	C1	GE	K10843BOTH	329	330	*5
256	COMPARE	C1	GE	K6163 BOTH	331	332	*5
257	LEAVE	43			308		
258	LEAVE	44			309		
259	LEAVE	45			405		
703	LEAVE	46			340		
704	LEAVE	47			341		
705	LEAVE	48			342		
317	LINK	13	PR1	ALL	286	288	
479	ASSIGN	8	K2		317		
289	UNLINK	9	K1	283	406		
290	UNLINK	9	K1	284	407		
291	UNLINK	9	K1	285	408		
318	UNLINK	13	K1	286	343	321	
319	UNLINK	13	K1	287	344	322	
320	UNLINK	13	K1	288	346	323	
321	UNLINK	9	K1	286	343		
322	UNLINK	9	K1	287	344		
323	UNLINK	9	K1	288	346		
295	COMPARE	C1	GE	V4	527		
527	TABULATE	3			301		
296	LINK	1	PR1		295		
297	COMPARE	C1	GE	V4	302		
298	LINK	2	PR1		297		
299	COMPARE	C1	GE	V4	303		
300	LINK	3	PR1		299		
327	COMPARE	C1	GE	V5	528		
528	TABULATE	4			333		
328	LINK	4	PR1		327		
329	COMPARE	C1	GE	V5	334		
330	LINK	5	PR1		329		
331	COMPARE	C1	GE	V6	529		
529	TABULATE	5			335		
14	GENERATE		1		439	1	
439	COMPARE	C1	GE	V4	440		
440	UNLINK	1	ALL	301	441		
441	UNLINK	2	ALL	302	442		
442	UNLINK	3	ALL	303	443		
443	COMPARE	C1	GE	V6	445		
445	UNLINK	6	ALL	335	446		
446	COMPARE	C1	GE	V5	447		
447	UNLINK	4	ALL	333	54		
54	UNLINK	5	ALL	334	800		
332	LINK	6	PR1		331		
301	QUEUE	10			304		
302	QUEUE	11			305		
303	QUEUE	12			306		
333	QUEUE	14			337		
334	QUEUE	15			338		
335	QUEUE	16			339		
304	ENTER	72			257		
305	ENTER	73			258		
306	ENTER	74			259		
337	ENTER	75	P8		703		
338	ENTER	76	P8		704		
339	ENTER	77	P8		705		

308	LEAVE	1			289		
309	LEAVE	1			290		
405	LEAVE	1			291		
340	LEAVE	1			318		
341	LEAVE	1			319		
342	LEAVE	1			320		
406	ADVANCE				438	1	FN16
407	ADVANCE				436	1	FN16
408	ADVANCE				437	1	FN16
343	ADVANCE				347	1	FN16
344	ADVANCE				348	1	FN16
346	ADVANCE				349	1	FN16
438	LEAVE	72			639		
639	SAVEX	127	C1		310		LTR 5
436	LEAVE	73			578		
578	SAVEX	128	C1		310		LTR 6
437	LEAVE	74			579		
579	SAVEX	129	C1		310		LTR 7
347	LEAVE	75	P8		586		
586	SAVEX	130	C1		345		M4T6 3
348	LEAVE	76	P8		587		
587	SAVEX	131	C1		345		M4T6 4
349	LEAVE	77	P8		229		
229	SAVEX	132	C1		345		MAB 2
310	ENTER	16			170	176	S16 CAFB
311	ADVANCE			ALL	312	315	
312	COMPARE	P1	E	K2	313		
313	ASSIGN	7	FN10		314		
*ABOVE ASSIGNS PRIORITIES U1C2-PR7 U2C2-PR6 U4C2-PR4 U6C2-PR5							
314	PRIORITY	*7			479		
315	ASSIGN	7	FN11		316		
*ABOVE ASSIGNS PRIORITIES U1C3PR3 U2C3PR2 U4C3PR0 U6C3PR1							
316	PRIORITY	*7			479		
345	ENTER	16		ALL	170	176	S16 CAFB
* NORTHERN C2-4 VEHICLE SECTION							
*THIS SECTION IS THE SAME AS SOUTHERN EXCEPT FOR AN ADDITIONAL LTR							
350	ASSIGN	4	K7		351		
351	ASSIGN	5	V3		352		
352	MARK	7			353		
353	ADVANCE			ALL	354	360	*5
354	COMPARE	P6	E	K3	361		
355	COMPARE	P6	E	K5	362		
356	COMPARE	P6	E	K8	363		
357	COMPARE	P6	E	K6	364		
358	COMPARE	P6	E	K7	365		
359	COMPARE	P6	E	K4	366		
360	ADVANCE				367		
361	SAVEX	82	C1		368		U3C2-4CL DANNB
362	SAVEX	83	C1		368		U5C2-4CL DANNB
363	SAVEX	84	C1		368		U8C2-4CL DANNB
364	SAVEX	85	C1		368		U6C2-4CL DANNB
365	SAVEX	86	C1		368		U7C2-4CL DANNB
366	SAVEX	87	C1		368		U4C2-4CL DANNB
367	SAVEX	88	C1		368		U9C2-4CL DANNB
368	TABULATE	2			369	410	
369	COMPARE	P1	E	K4	370		
370	ASSIGN	7	FN14		371		

## \*ASSIGNS FOLLOWING PRIORITIES U3C4PR3 U5C4PR2 U4C4PR0 U6C4PR1

371	PRIORITY	*7				513		
513	ASSIGN	8	K1			372		
372	LINK	17	PR1		ALL	373	379	
514	ASSIGN	8	K2			416		
416	LINK	18	PR1		ALL	377	379	
373	ENTER	53				706		
374	ENTER	54				717		
375	ENTER	55				718		
376	ENTER	56				719		
377	ENTER	57				720		
378	ENTER	58				791		
379	ENTER	59				792		
706	COMPARE	C1	GE	K5539	BOTH	388	389	*5
717	COMPARE	C1	GE	K5539	BOTH	390	391	*5
718	COMPARE	C1	GE	K5539	BOTH	392	393	*5
719	COMPARE	C1	GE	K5539	BOTH	394	395	*5
720	COMPARE	C1	GE	K10939	BOTH	530	531	*5
791	COMPARE	C1	GE	K10939	BOTH	532	533	*5
792	COMPARE	C1	GE	K6259	BOTH	534	535	*5
793	LEAVE	53				417		
794	LEAVE	54				418		
796	LEAVE	55				419		
797	LEAVE	56				420		
798	LEAVE	57				542		
700	LEAVE	58				543		
214	LEAVE	59				544		
380	UNLINK	17	K1	373		421		
381	UNLINK	17	K1	374		422		
382	UNLINK	17	K1	375		423		
383	UNLINK	17	K1	376		424		
429	UNLINK	18	K1	377		545	432	
430	UNLINK	18	K1	378		546	433	
431	UNLINK	18	K1	379		547	434	
432	UNLINK	17	K1	377		545		
433	UNLINK	17	K1	378		546		
434	UNLINK	17	K1	379		547		
388	COMPARE	C1	GE	V13		712		
712	TABULATE	6				396		
389	LINK	7	PR1			388		
390	COMPARE	C1	GE	V13		397		
391	LINK	8	PR1			390		
392	COMPARE	C1	GE	V13		398		
393	LINK	10	PR1			392		
394	COMPARE	C1	GE	V13		399		
395	LINK	11	PR1			394		
530	COMPARE	C1	GE	V14		713		
713	TABULATE	7				536		
531	LINK	12	PR1			530		
532	COMPARE	C1	GE	V14		537		
533	LINK	14	PR1			532		
534	COMPARE	C1	GE	V15		714		
714	TABULATE	8				538		
124	GENERATE		1			125		1
125	COMPARE	C1	GE	V13		242		
242	UNLINK	7	ALL	396		243		
243	UNLINK	8	ALL	397		248		



248	UNLINK	10	ALL	398	249
249	UNLINK	11	ALL	399	134
134	COMPARE	C1	GE	V15	135
135	UNLINK	15	ALL	538	136
136	COMPARE	C1	GE	V14	137
137	UNLINK	12	ALL	536	138
138	UNLINK	14	ALL	537	800
535	LINK	15	PR1		534
396	QUEUE	18			400
397	QUEUE	19			401
398	QUEUE	20			402
399	QUEUE	21			403
536	QUEUE	23			539
537	QUEUE	24			540
538	QUEUE	25			541
400	ENTER	80			793
401	ENTER	81			794
402	ENTER	82			796
403	ENTER	83			797
539	ENTER	84	P8		798
540	ENTER	85	P8		700
541	ENTER	86	P8		214
417	LEAVE	1			380
418	LEAVE	1			381
419	LEAVE	1			382
420	LEAVE	1			383
542	LEAVE	1			429
543	LEAVE	1			430
544	LEAVE	1			431
421	ADVANCE				425
422	ADVANCE				1
423	ADVANCE				1
424	ADVANCE				1
545	ADVANCE				1
546	ADVANCE				1
547	ADVANCE				1
425	LEAVE	80			789
752	SAVEX	120	C1		752
426	LEAVE	81			409
753	SAVEX	121	C1		753
427	LEAVE	82			409
754	SAVEX	122	C1		754
428	LEAVE	83			409
755	SAVEX	123	C1		755
548	LEAVE	84	P8		409
435	SAVEX	124	C1		435
549	LEAVE	85	P8		444
448	SAVEX	125	C1		444
789	LEAVE	86	P8		444
449	SAVEX	126	C1		444
409	ENTER	16			444
410	ADVANCE			ALL	207
411	COMPARE	P1	E	BOTH	213
412	ASSIGN	7	FN13	K2	414
*ASSIGNS FOLLOWING PRIORITIES U3C2PR7 U5C2PR6 U4C2PR5 U6C2PR4					
413	PRIORITY	*7			514
414	ASSIGN	7	FN14		415

1 FN16  
 1 FN16  
 1 FN16  
 1 FN16  
 1 FN16  
 1 FN16  
 1 FN16  
 LTR 1  
 LTR 2  
 LTR 3  
 LTR 4  
 M4T6 1  
 M4T6 2  
 MAB 1  
 S16 CAFB

## \*ASSIGNS FOLLOWING PRIORITIES U3C3PR3 U5C3PR2 U4C3PR0 U6C3PR1

415	PRIORITY	*7			514			
444	ENTER	16			207	213		S16 CAFB
* SOUTHERN C1 VEH MOVT FROM RIVER-PL-OBJ								
450	COMPARE	P1	E	K1	451			U1
451	SAVEX	25	C1		452			TM U1C1CL CAFB
452	ENTER	29			453			U1 ALIGN AREA
453	GATE	LS1			454			
454	LOGIC	I1			455			
455	LEAVE	29			470			
456	GENERATE	0	109		457	3	1	
457	COMPARE	N452	GE	K109	458			
458	LOGIC	I1			800			
460	COMPARE	P1	E	K1	461			U2
461	SAVEX	26	C1		462			TM U2C1CL CAFB
462	ENTER	30			463			U2 ALIGN AREA
463	GATE	LS2			464			
464	LOGIC	I2			465			
465	LEAVE	30			470			
466	GENERATE	0	68		467	3	1	
467	COMPARE	N462	GE	K68	468			
468	LOGIC	I2			800			
470	ASSIGN	2	V1		471			
471	ADVANCE				472		*2	TT FB-PL 4-6KM
472	LEAVE	16			473			LV CAFB
473	ENTER	31			474	476	1	U1U2U6 AR PL
474	COMPARE	P6	E	K1	475			
475	SAVEX	29	C1		477			TM U1C1 CL PL
476	SAVEX	30	C1		477			TM U2C1 CL PL
477	LEAVE	31			480			
480	ASSIGN	2	V7		481			TT PL-OBJ S
481	ADVANCE				482		*2	
482	ENTER	32			483		1	S32 U1U2 OBJ
483	LEAVE	32			484	486		
484	COMPARE	P6	E	K1	489	491		
489	COMPARE	P1	E	K1	490			
490	SAVEX	31	C1		799			TM U1C1 CL OBJ
491	SAVEX	33	C1		799			TM U1C2-4 CL
485	COMPARE	P6	E	K2	492	494		
492	COMPARE	P1	E	K1	493			
493	SAVEX	32	C1		799			TM U2C1 CL OBJ
494	SAVEX	34	C1		799			TM U2C2-4 CL
486	COMPARE	P6	E	K6	497			
497	SAVEX	98	C1		799			TM U6C1 CL OBJ
* SOUTHERN C2-4 VEH MOVT FROM RIVER-DA-HA-OBJ								
500	SAVEX	27	C1		502			TMU1C2-4CLCAFB
501	SAVEX	35	C1		502			TMU2C2-4CLCAFB
502	ADVANCE				503		*5	TT RIVER-DASFB
503	ENTER	25			504	508		S25 DASFB
504	COMPARE	P6	E	K1	505			
505	SAVEX	36	C1		506			TMU1C2-4CLDASF
506	ENTER	26			507		1	U1AREA DASFB
507	LEAVE	26			511			
508	SAVEX	37	C1		509			TMU2C2-4CLDASF
509	ENTER	27			510		1	U2AREA DASFB
510	LEAVE	27			511			
511	LEAVE	25			325			

325	LEAVE	16				512			
512	ASSIGN	5	V8			515			
515	ADVANCE					516	*5		TT DA-HA 4-6KM
516	ENTER	68			BOTH	517	521		S68 HASFB
517	COMPARE	P6	E	K1		518			
518	SAVEX	38	C1			519			TMU1C2-4CLHASF
519	ENTER	66				520	1		U1AREA HASFB
520	LEAVE	66				522			
521	SAVEX	39	C1			523	1		TMU2C2-4CLHASF
522	ENTER	67				524			U2AREA HASFB
523	LEAVE	67				525			
524	LEAVE	68				526			TT HASFB-0BJ
525	ASSIGN	5	V9			482	*5		D=11-13KM
526	ADVANCE								
* SOUTHERN AAA BTRY(-) MOVT SECTION RIVER TO									
* ALL VEHICLES FROM RIVER TO PL									
233	ASSIGN	2	V10			751			
751	SAVEX	101	C1			234			
234	ADVANCE					487	*2		
487	LEAVE	16				488			
488	SAVEX	102	C1			799			TM U7S CL PL
* NORTHERN C1 VEH MOVT FROM RIVER-PL-0BJ									
550	COMPARE	P1	E	K1		551			
551	SAVEX	40	C1			552			TM U3C1CL CAFB
552	ENTER	33				553			U3 ALIGN
553	GATE	LS3				554			
554	LOGIC	I3				555			
555	LEAVE	33				570			
556	GENERATE	0	109			557	3	1	
557	COMPARE	N552	GE	K109		558			
558	LOGIC	I3				800			
560	COMPARE	P1	E	K1		561			
561	SAVEX	41	C1			562			TMU5C1 CL CAFB
562	ENTER	34				563			U5 ALIGN
563	GATE	LS4				564			
564	LOGIC	I4				565			
565	LEAVE	34				570			LV ALIGN
566	GENERATE	0	117			567	3	1	
567	COMPARE	N562	GE	K117		568			
568	LOGIC	I4				800			
570	ASSIGN	2	V10			571			TT RIVER-PL N
571	ADVANCE					572	*2		D=5.5-6.5KM
572	LEAVE	16				573			LV CAFB
573	ENTER	35			BOTH	574	576	1	U3U5 AR PL
574	COMPARE	P6	E	K3		575			
575	SAVEX	42	C1			577			TM U3 C1 CL PL
576	SAVEX	43	C1			577			TM U5 C1 CL PL
577	LEAVE	35				580			
580	ASSIGN	2	V11			581			TT PL-0BJ U3U5
581	ADVANCE					582	*2		D=9-12KM
582	ENTER	36				583	1		S36 U3U5 0BJ
583	LEAVE	36			BOTH	584	585		
584	COMPARE	P6	E	K3	BOTH	588	590		
588	COMPARE	P1	E	K1		589			
589	SAVEX	44	C1			799			TM U3C1 CL 0BJ
590	SAVEX	45	C1			799			TMU3C2-4CL 0BJ
585	COMPARE	P6	E	K5	BOTH	591	593		

591	COMPARE	P1	E	K1	592			
592	SAVEX	46	C1		799			TM USC1 CL OBJ
593	SAVEX	47	C1		799			TMUSC2-4CL OBJ
*					NORTHERN C2-4 VEH	MOVT	FROM RIVER-DA-HA-OBJ	
600	SAVEX	48	C1		602			TMU3C2-4CLCAFB
601	SAVEX	49	C1		602			TMU5C2-4CLCAFB
602	ADVANCE				603		*5	TT RIVER-DANFB
603	ENTER	37			604	608		S37 DANFB
604	COMPARE	P6	E	K3	605			
605	SAVEX	50	C1		606			TMU3C2-4CLDANF
606	ENTER	38			607		1	U3 AREA DANFB
607	LEAVE	38			611			
608	SAVEX	51	C1		609			TMU5C2-4CLDANF
609	ENTER	39			610		1	U5 AREA DANFB
610	LEAVE	39			611			
611	LEAVE	37			326			
326	LEAVE	16			612			
612	ASSIGN	5	V8		613			TT DANFB-HANFB
613	ADVANCE				614		*5	O=4-6KM
614	ENTER	40			615	619		S40 HANFB
615	COMPARE	P6	E	K3	616			
616	SAVEX	52	C1		617			TMU3C2-4CLHANF
617	ENTER	41			618		1	U3 AREA HANFB
618	LEAVE	41			622			
619	SAVEX	53	C1		620			TMU5C2-4CLHANF
620	ENTER	42			621		1	U5 AREA HANFB
621	LEAVE	42			622			
622	LEAVE	40			623			LV HANFB
623	ASSIGN	5	V9		624			TT HANFB-OBJ
624	ADVANCE				582		*5	
*					TF1-4ARMOR	MOVT	FROM RIVER TO OBJ	
625	LOGIC	I5			BOTH	626	667	
626	GATE	LS5			627			
627	ASSIGN	5	V1		628	630		
628	COMPARE	P1	E	K2	631			
629	COMPARE	P1	E	K1	631			
630	ADVANCE				260			
631	ADVANCE				632		*5	TT RIVER-FSPNB
632	ENTER	49			633			S49 FSPSNB
633	SAVEX	57	C1		634			TMU4S CL FSPNB
634	GATE	LS6			635			U4C1-260TOCAFB
635	LOGIC	16			636			U1-2CL ALIGN
636	LEAVE	49			637			LV FSPNB
637	SAVEX	58	C1		638	313		TM U4 CL FSPS
638	COMPARE	P1	E	K1	PICK	145	147	GOTOM4T6MAB CS
641	COMPARE	P1	E	K1	642			
642	SAVEX	59	C1		643			TMU4SC1CLALIGN
643	ENTER	50			644			S50 U4S ALIGN
644	GATE	LS7			645			
645	LOGIC	17			646			
646	LEAVE	50			647			
647	ASSIGN	5	V3		650			O=2-3KM
648	ASSIGN	5	V3		649			
649	SAVEX	60	C1		650			TMU4SC2-4CLCAF
650	ADVANCE				651		*5	TT TO AA 2-3KM
651	ENTER	51			652	654		S51 U4AA
652	COMPARE	P1	E	K1	BOTH	653		

653	SAVEX	61	C1		694				TM U4C1 CL AAS
654	SAVEX	62	C1		694				TM U4C2-4 CL
655	GENERATE	0	25		656	3	1		
656	COMPARE	N643	GE	K25	657				
657	LOGIC	I7			800				
659	GENERATE	0	35		660	3	1		
660	COMPARE	N633	GE	K35	665				
665	LOGIC	I6			800				
667	ASSIGN	5	V1		668	670			D=4-7 KM
668	COMPARE	P1	E	K2	671				
669	COMPARE	P1	E	K1	671				
670	ADVANCE				350				
671	ADVANCE				672		*5		TT RIVER-FSPN
672	ENTER	70			673				S70 FSPN
673	SAVEX	63	C1		674				TMU4C1-2CLFSPN
674	GATE	LS10			675				
675	LOGIC	I10			676				
676	LEAVE	70			677				
677	SAVEX	64	C1		678	679			TM U4C1-2LVFSP
678	COMPARE	P1	E	K1	182	184			C1 SWIM
679	ADVANCE				412				TO M4T6 MAB N
680	COMPARE	P1	E	K1	681				
681	SAVEX	65	C1		682				TMU4C1CLALIGNN
682	ENTER	71			683				S71 ALIGN N U4
683	GATE	LS13			684				
684	LOGIC	I13			685				
685	LEAVE	71			686				
686	ASSIGN	5	V3		689				2-3KM
687	ASSIGN	5	V3		688				TT TO AA N
688	SAVEX	66	C1		689				TMU4C2-4CLCAFB
689	ADVANCE				690		*5		TT TO AA N
690	ENTER	51			691	693			S51 AA
691	COMPARE	P1	E	K1	692				
692	SAVEX	67	C1		694				TMU4C1 CL AAN
693	SAVEX	68	C1		694				TMU4C2-4 CL AA
694	GATE	LS12			711				
711	LOGIC	I12			404				
404	LEAVE	51			336				
336	LEAVE	16			696				
696	SAVEX	69	C1		697				TM U4 LV RESAA
697	ASSIGN	5	V12		698				TT AA-0BJ
698	ADVANCE				699		*5		D=17-19KM
699	SAVEX	70	C1		799				TM U4 CL OBJ
701	GENERATE	0	34		702	3	1		
702	COMPARE	N673	GE	K34	707				
707	LOGIC	I10			800				
709	GENERATE	0	135		710	3	1		
710	COMPARE	V19	GE	K86	715				
715	LOGIC	I12			800				
222	GENERATE	0	24		223	3	1		
223	COMPARE	N682	GE	K24	228				
228	LOGIC	I13			800				
* TRAINS MOVT SECTION									
594	GENERATE	0	306		595	7	1		
595	COMPARE	C1	GE	V16	596				
596	ASSIGN	6	K9		597				U9 TRNS
597	ASSIGN	4	K10		598				P4 VEL 10KPH

598	ENTER	1			599				S1 CANB
599	ASSIGN	5	V10		231				TT LD-BR 6KM
231	ADVANCE				232		*5		
232	LEAVE	1			721				
721	SAVEX	89	C1		722				TM TRNS LVCANB
722	STORE	63			723		58		S63 BRIDGE
723	SAVEX	104	C1		724				TM LAST VEH
724	ENTER	16			725				S16 CAFB
725	ASSIGN	5	V17		726				TT BR-PL 7-8KM
726	ADVANCE				727		*5		
727	LEAVE	16			795	728			
795	COMPARE	P6	NE	K9	57				
57	ADVANCE				58	771			
58	COMPARE	P6	E	K7	729				
728	SAVEX	90	C1		799				TM TRNS LV PL
729	SAVEX	105	C1		799				TM U7NLVPL
*					BDE TAC CP MOVT SECTION U6				
730	COMPARE	P1	E	K1	731				
731	SAVEX	100	C1		732				TM U6C1CL CAFB
732	ENTER	60			733				S60 U6 ALIGN
733	GATE	LS11			734				
734	LOGIC	I11			735				
735	LEAVE	60			470				
736	GENERATE	0	8		737		3	1	
737	COMPARE	N732	GE	K8	738				
738	LOGIC	I11			800				
*					ATCH ARTY MOVT SECTION U11 U12				
756	GENERATE	0	102		757		7	1	
757	COMPARE	C1	GE	V18	758				
758	PRIORITY	7			759	761			U11 U12 PR7
759	COMPARE	N758	LE	K72	760				
760	ASSIGN	1	K4		762				72 C4
761	ASSIGN	1	K3		762				30 C3
762	ASSIGN	3	K2		763				FS ECHELON
763	SPLIT				764	778			
764	ASSIGN	6	K11		765				U11 1-651ARTY
765	ENTER	1			790				S1 CANB
790	ASSIGN	4	K10		766				
766	ASSIGN	5	V10		768				TT TO BR
767	COMPARE	C1	GE	V16	787	769			BR OPEN
768	ADVANCE				767		*5		
787	COMPARE	P6	E	K11	788				
788	SAVEX	94	C1		770				TM U11 LV CANB
769	SAVEX	93	C1		770				TM U12 LV CANB
770	LEAVE	1			664	722			
664	COMPARE	N770	E	K1	695				
695	SAVEX	103	C1		722				TM FIRST VEH
771	ENTER	64			772	774	1		
772	COMPARE	P6	E	K11	773				
773	SAVEX	96	C1		775				TM U11 CL FPF8
774	SAVEX	97	C1		775				TM U12 CL FPF8
775	COMPARE	N771	GE	K204	776				
776	LEAVE	64			777				
777	SAVEX	99	C1		799				U11 U12 TERM
778	ASSIGN	6	K12		779				U12 1-652 ARTY
779	ENTER	65			780				U12 FP VIC LD
780	GATE	LS15			781				

781	LOGIC	I15		782			
782	LEAVE	65		765			
783	GENERATE	0	102	784	7	1	
784	COMPARE	N771	NE K0	785			
785	LOGIC	I15		800			
*			VITAL STATISTICS SECTION				
292	GENERATE	0	1	459	1		
459	COMPARE	N488	E K58	293			TM LTR 1 USED
293	SAVEX	106	V20	294			TM LTR 2 USED
294	SAVEX	107	V21	661			TM LTR 3 USED
661	SAVEX	108	V22	662			TM LTR 4 USED
662	SAVEX	109	V23	663			TM M4T6 1 USED
663	SAVEX	110	V24	746			TM M4T6 2 USED
746	SAVEX	111	V25	747			TM MAB 1 USED
747	SAVEX	112	V26	748			TM LTR 5 USED
748	SAVEX	113	V27	749			TM LTR 6 USED
749	SAVEX	114	V28	750			TM LTR 7 USED
750	SAVEX	115	V29	324			TM M4T6 3 USED
324	SAVEX	116	V30	139			TM M4T6 4 USED
139	SAVEX	117	V30	387			TM MAB 2 USED
387	SAVEX	118	V32	307			TM BRIDGE USED
307	SAVEX	119	V33	800			
799	TERMINATE	R					
800	TERMINATE						
	START	1938	43200				
CLOCK TIME	REL	43035		ABS	43035		

**APPENDIX D****BASE MODEL REPRESENTATIVE GPSS II FLOW DIAGRAM**



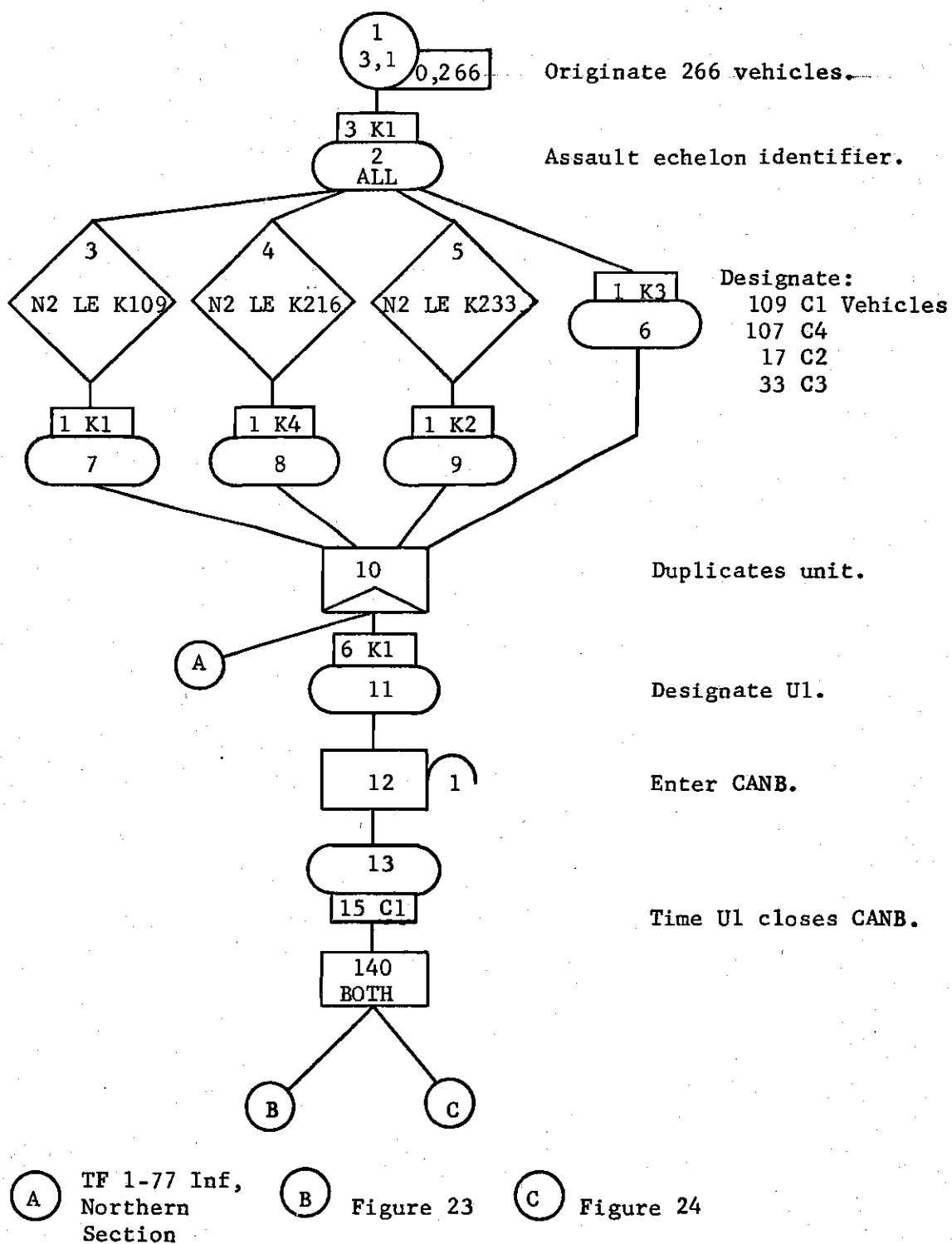


Figure 22. TF 1-78 Infantry Generator

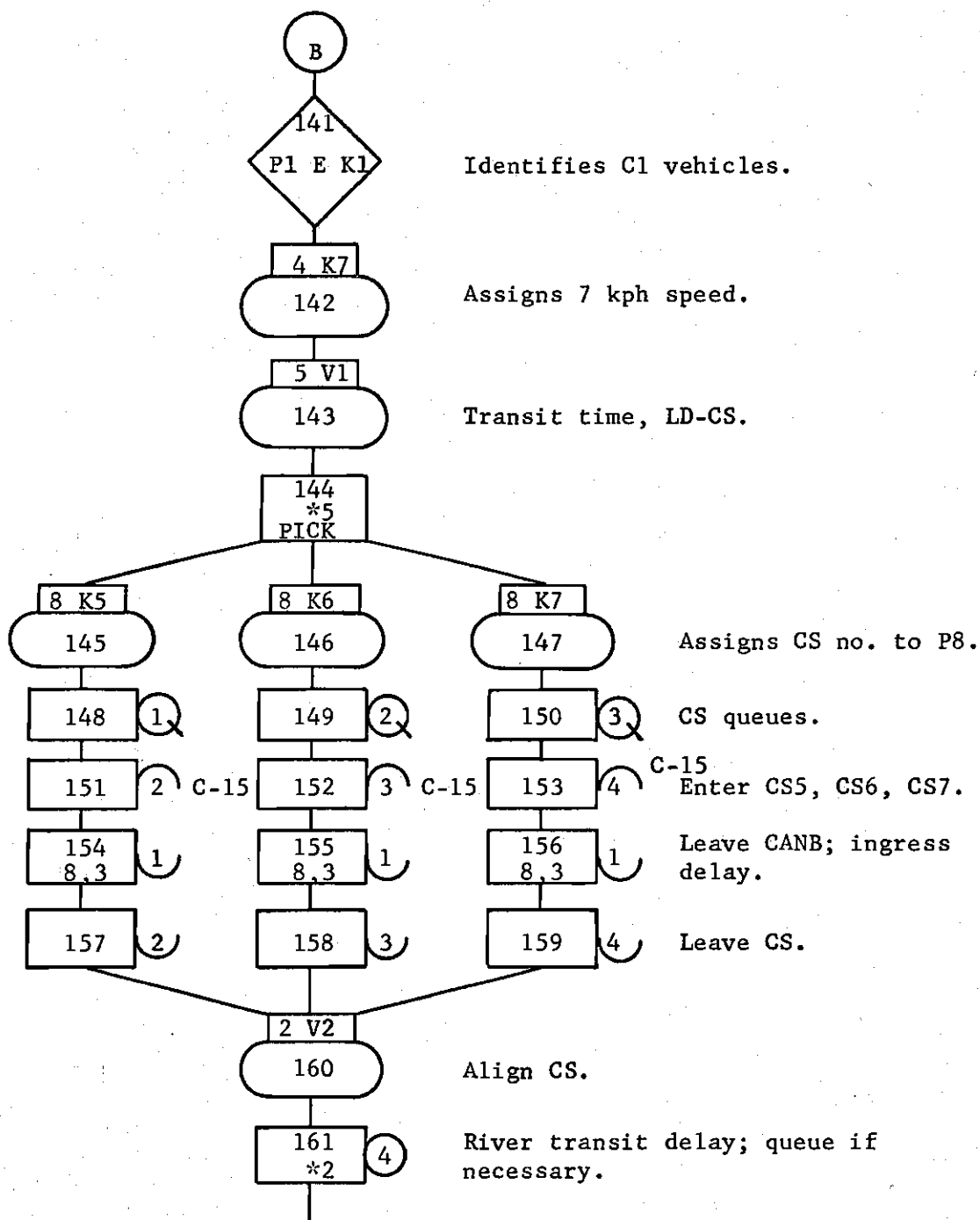


Figure 23. GPSS II Southern Amphibious Vehicle Flow, CANB

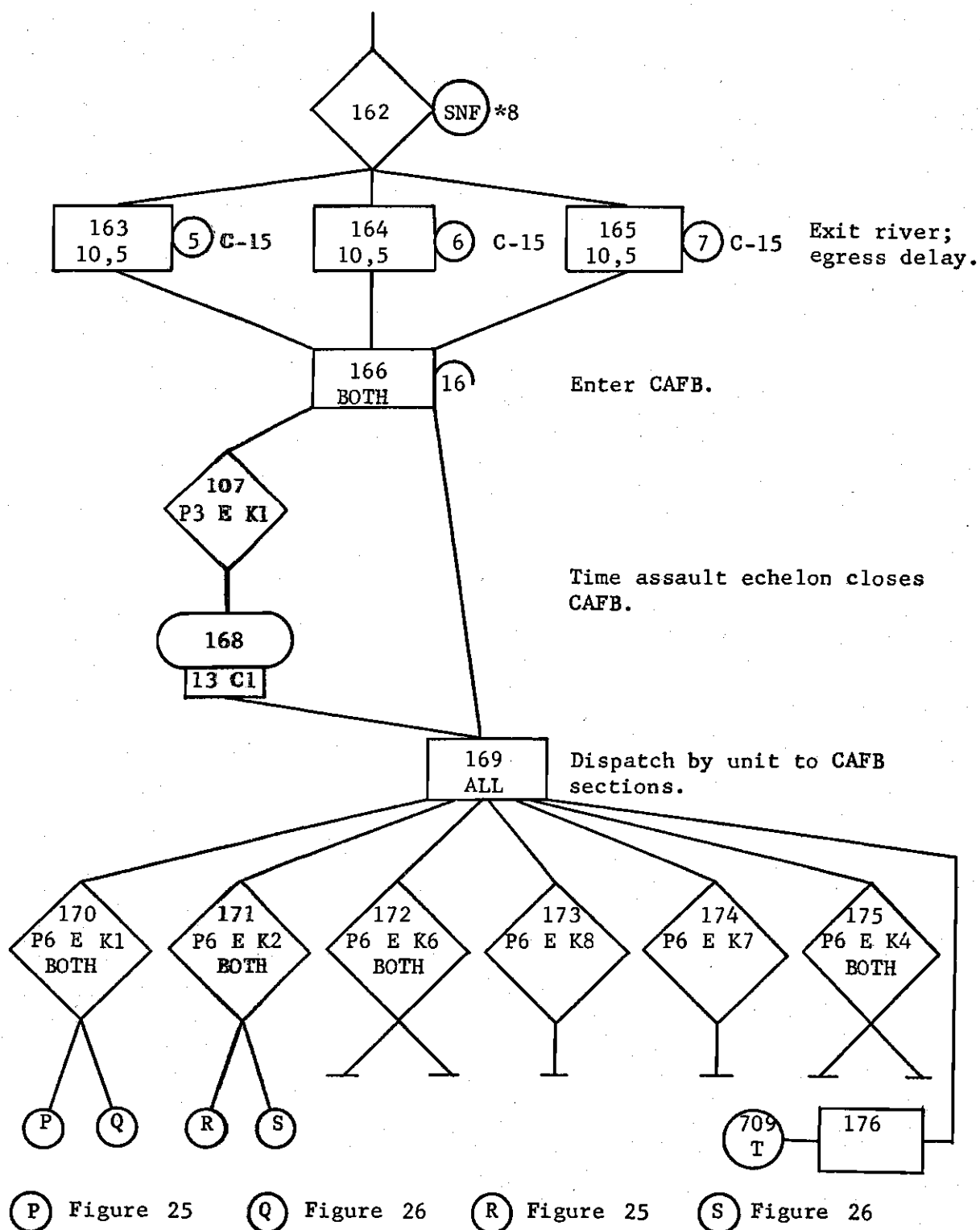
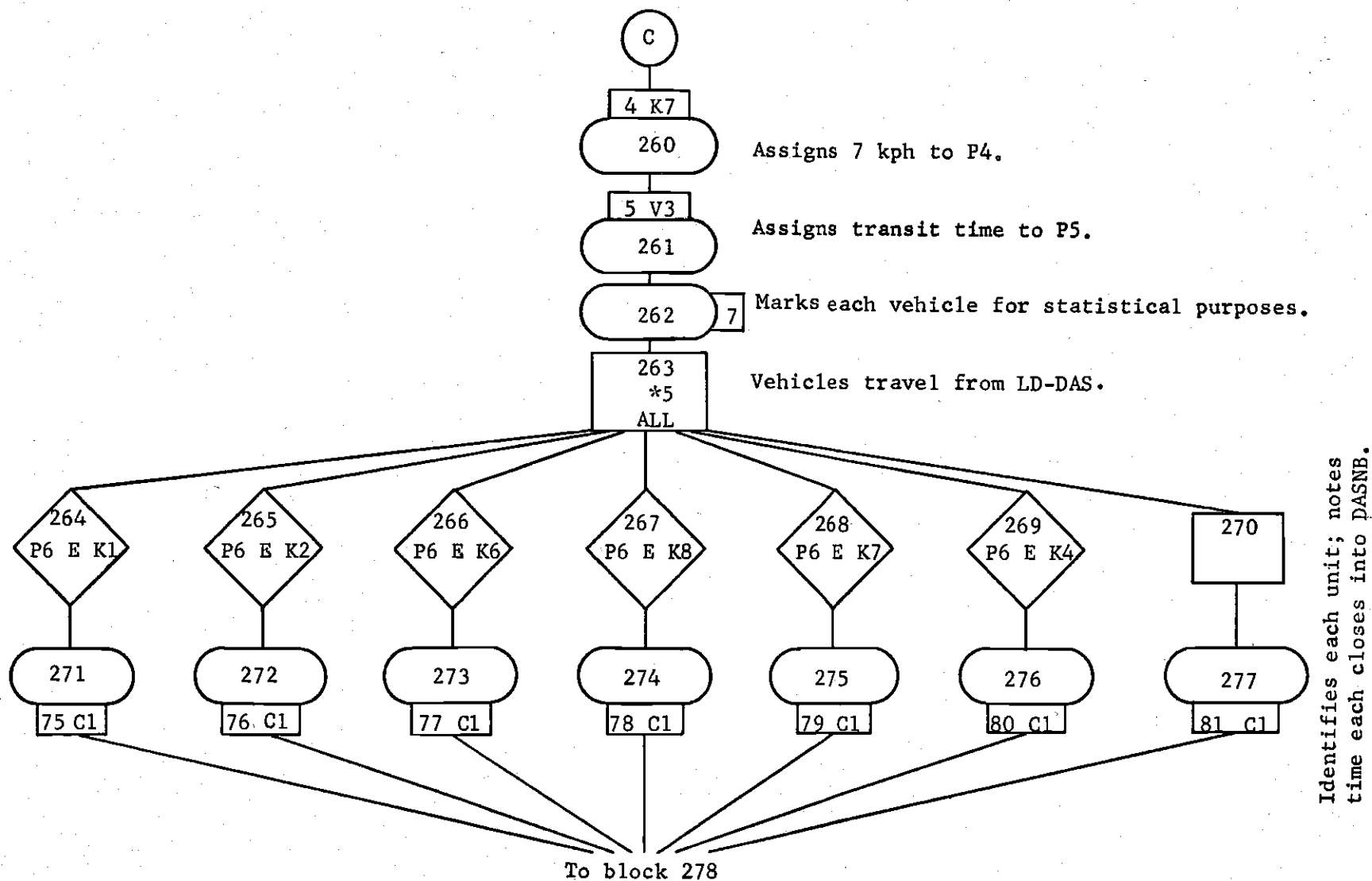


Figure 23. Concluded



Identifies each unit; notes  
time each closes into DASNB.

Figure 24. GPSS II Southern Nonamphibious Vehicle Flow, CANB

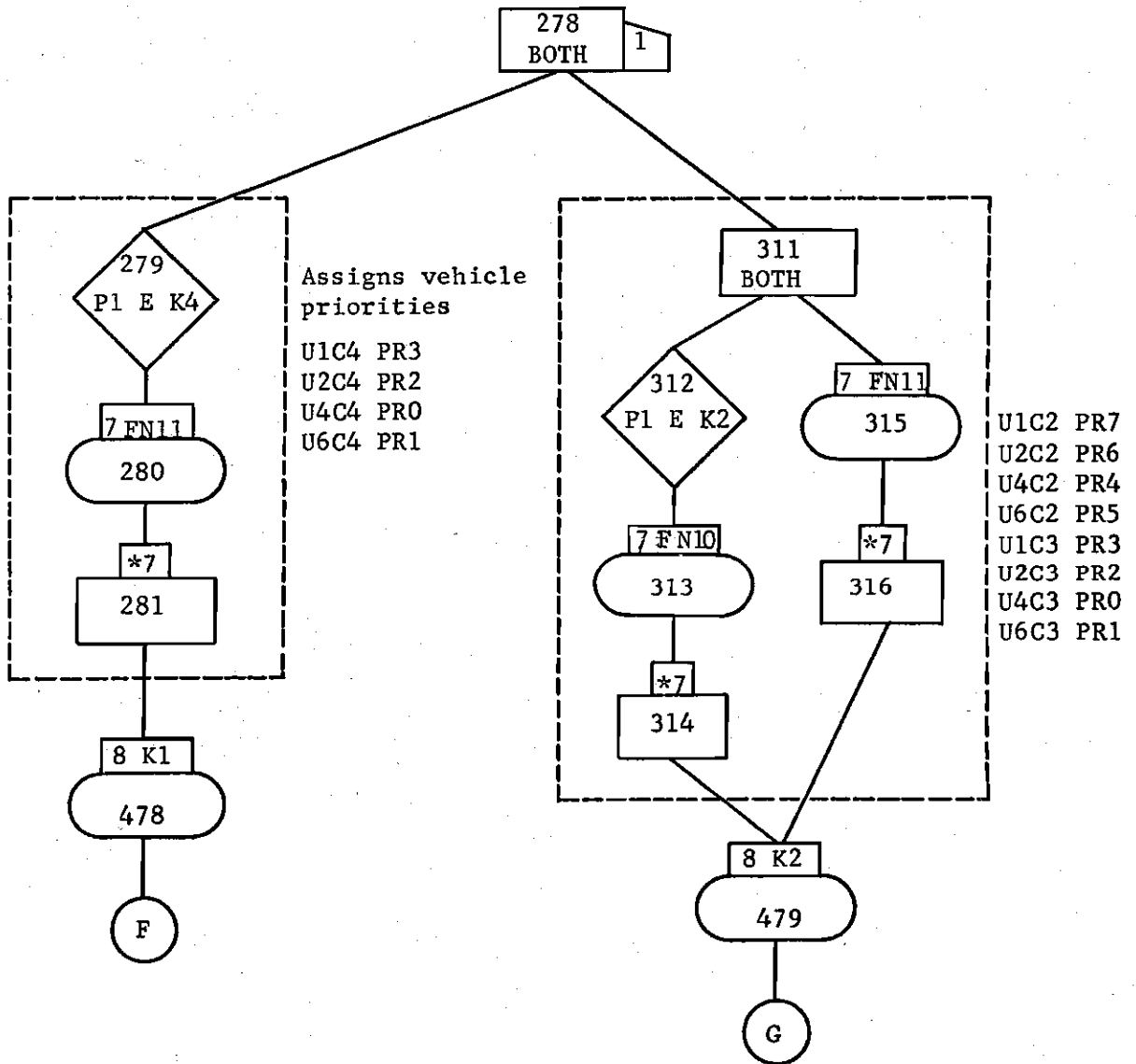


Figure 24. Continued

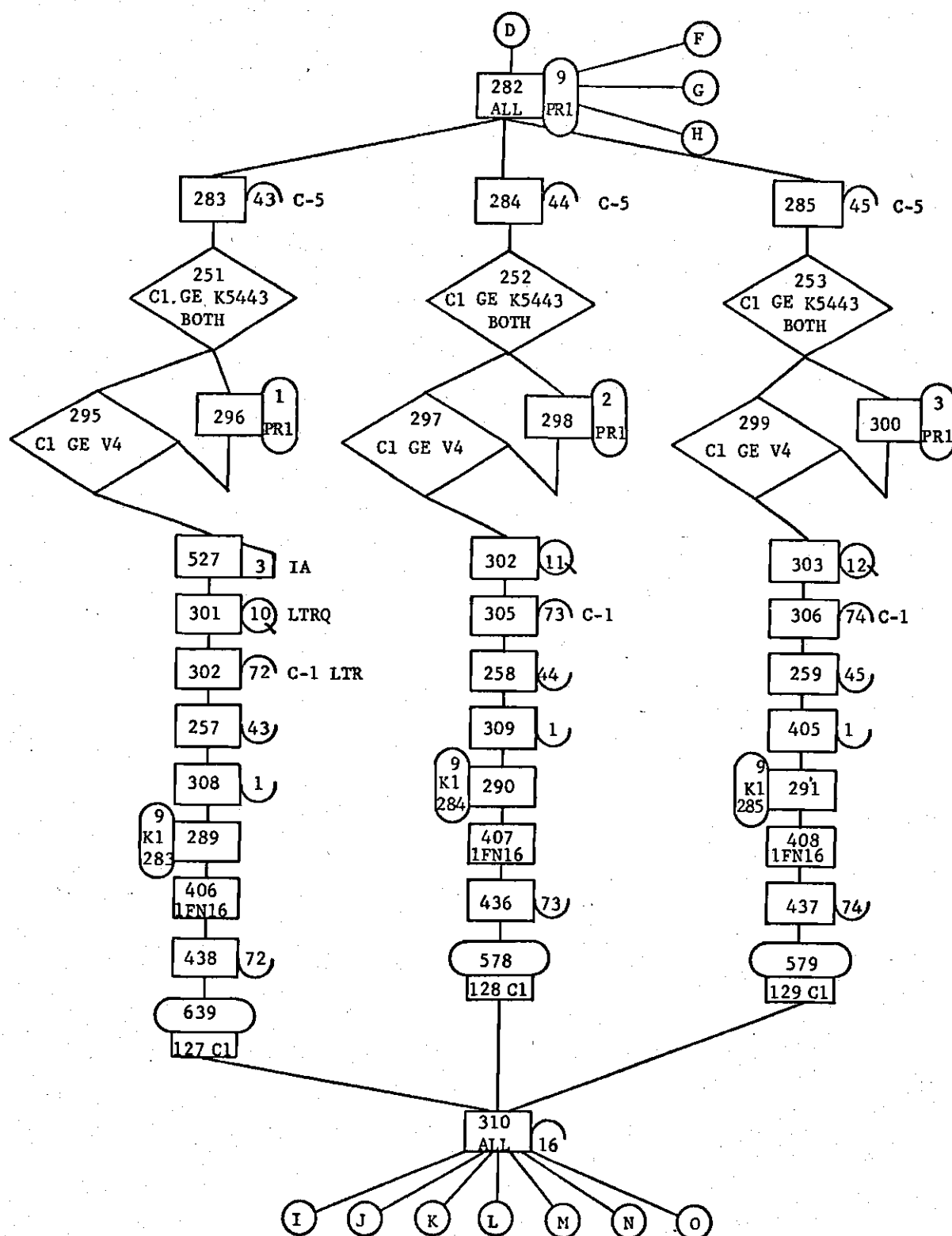


Figure 24. Continued

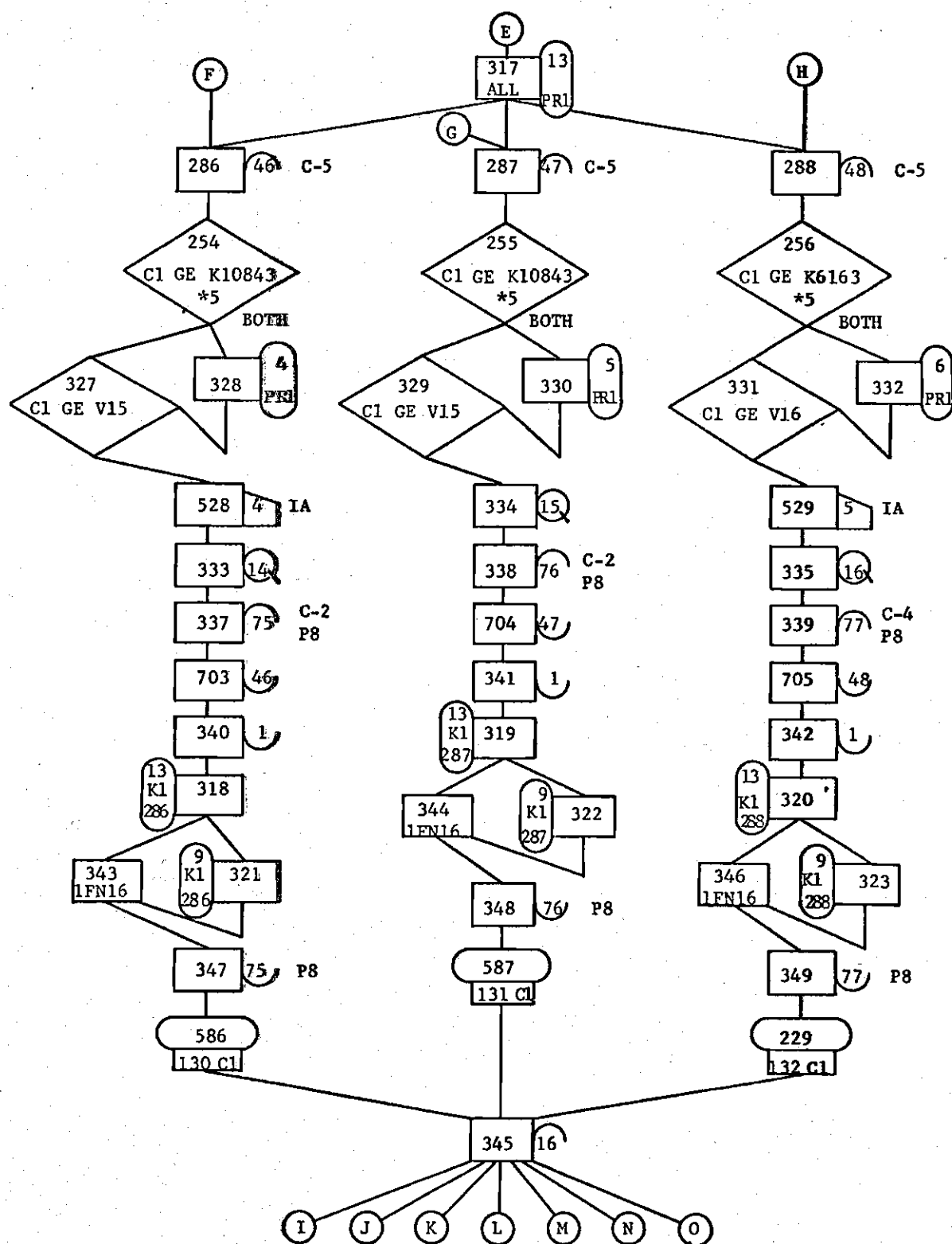


Figure 24. Concluded

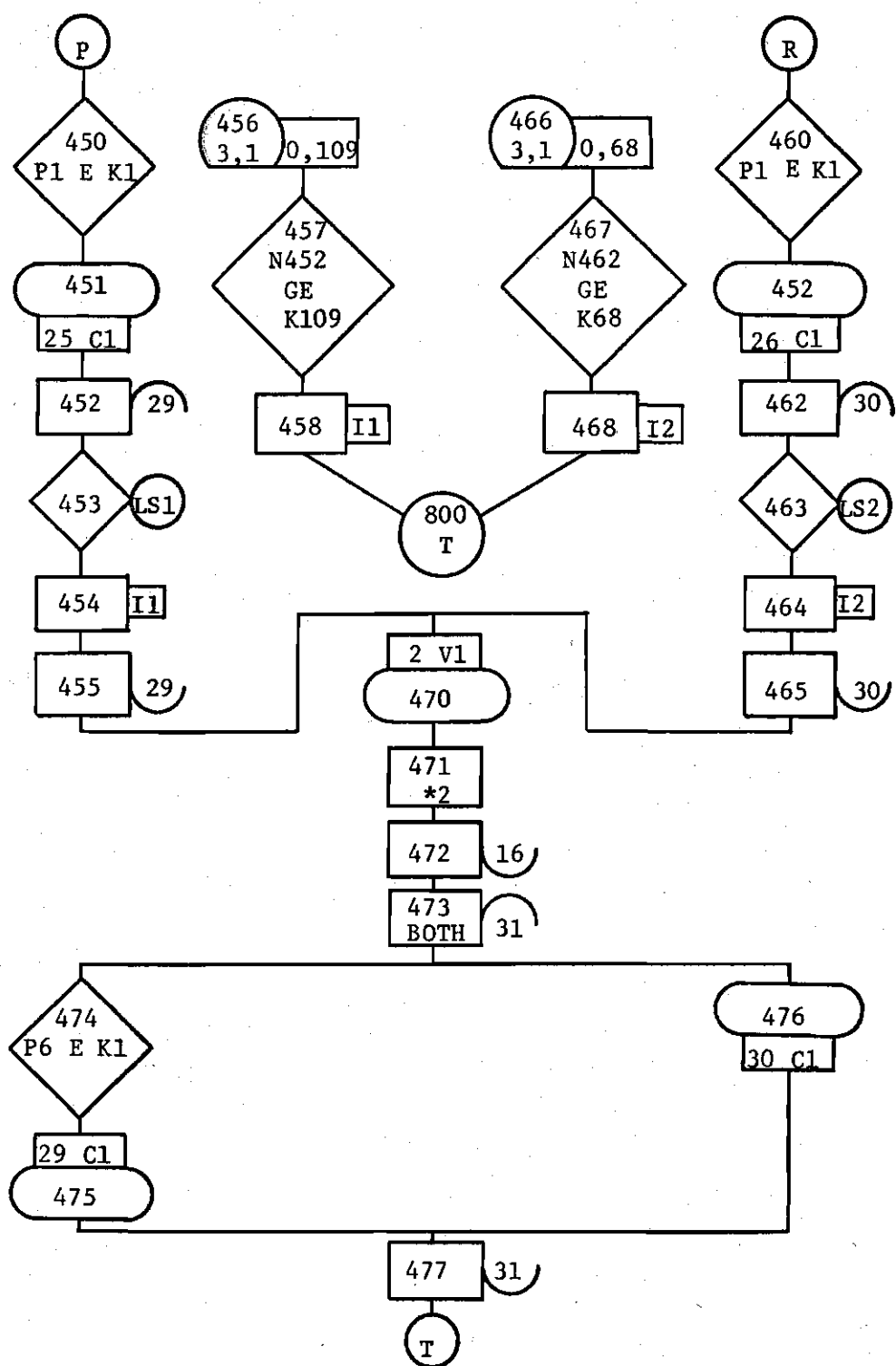


Figure 25. GPSS II Southern Amphibious Vehicle Flow, CAFB



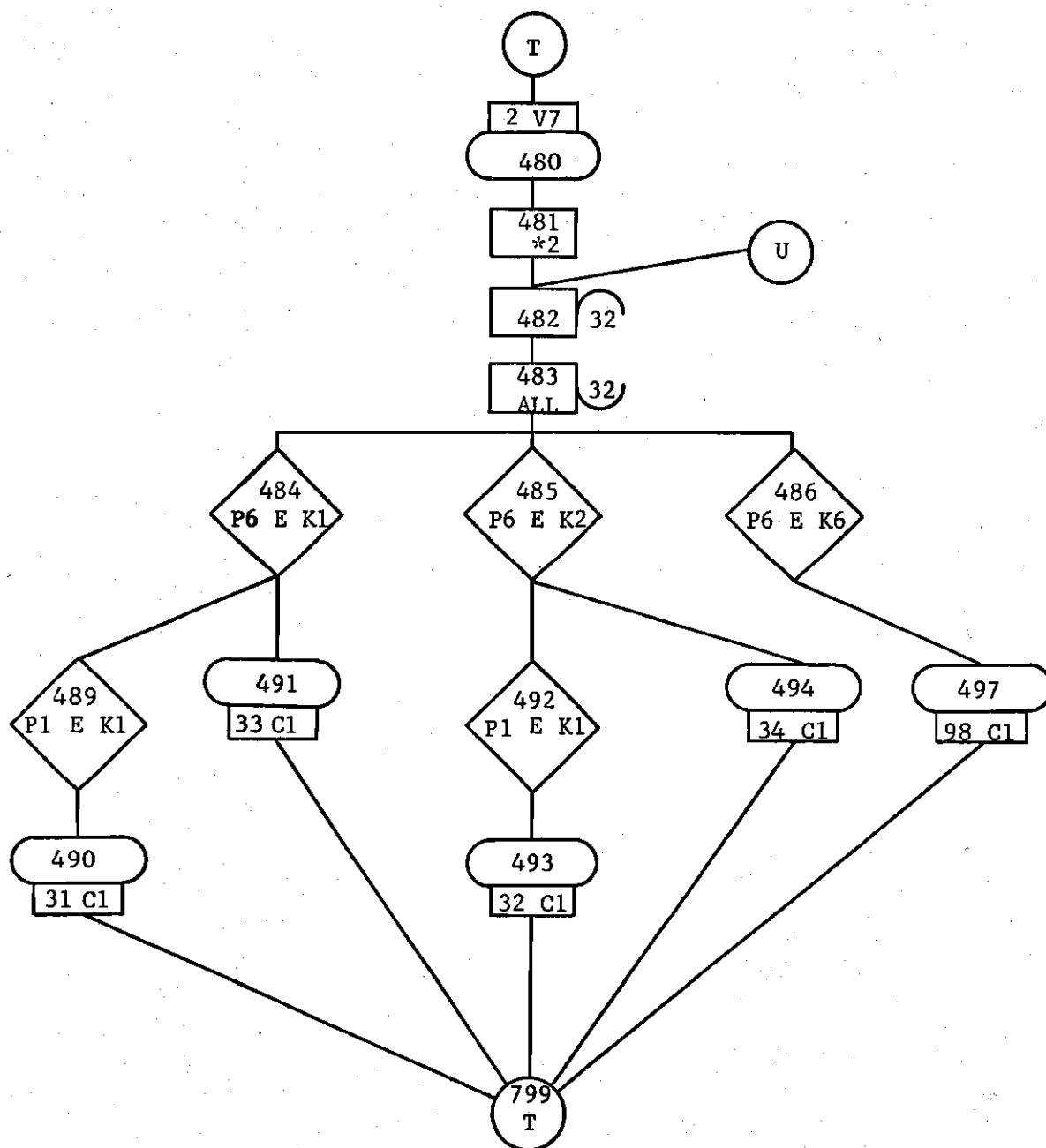


Figure 25. Concluded

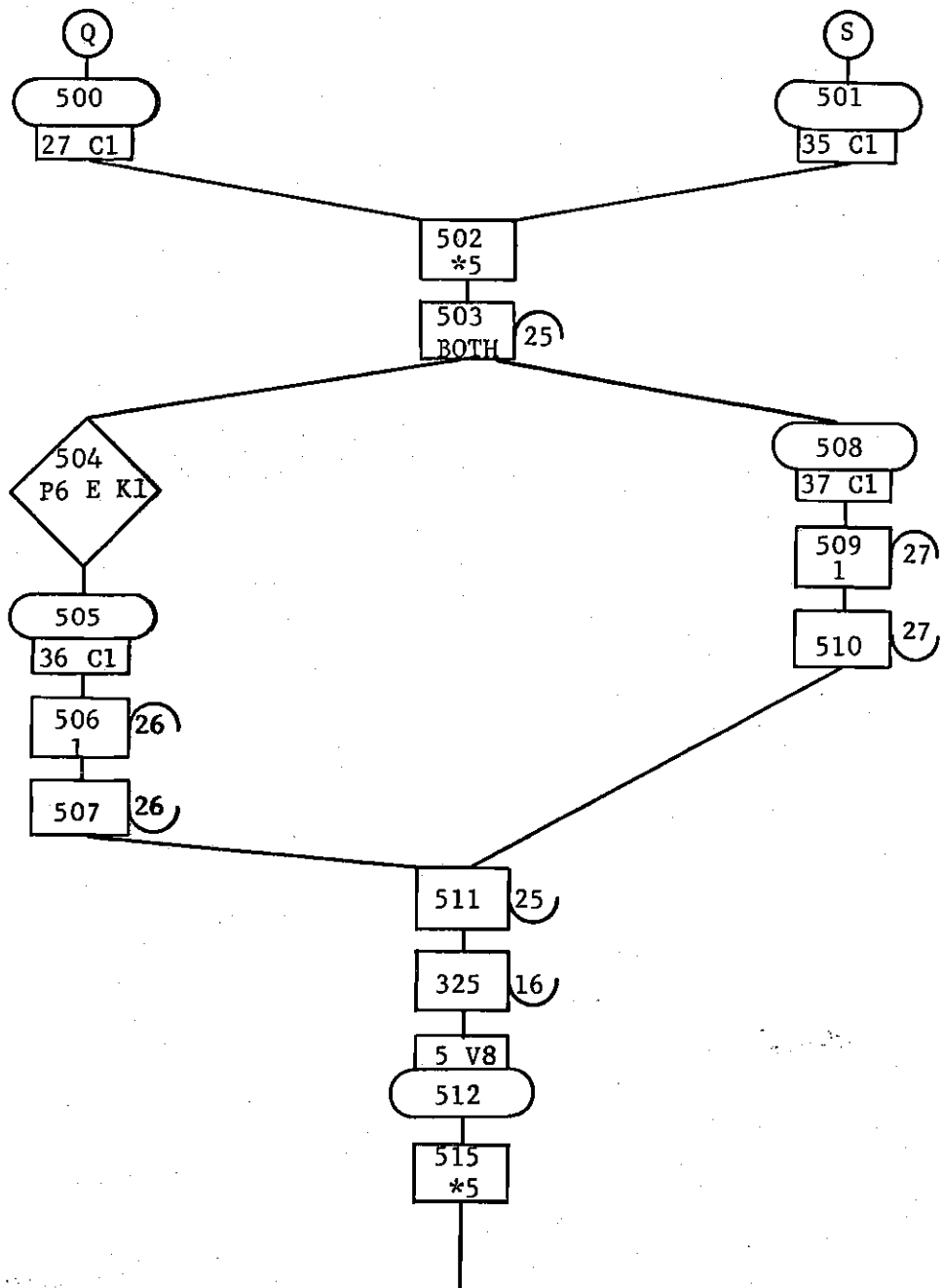


Figure 26. GPSS II Southern Nonamphibious Vehicle Flow, CAFB

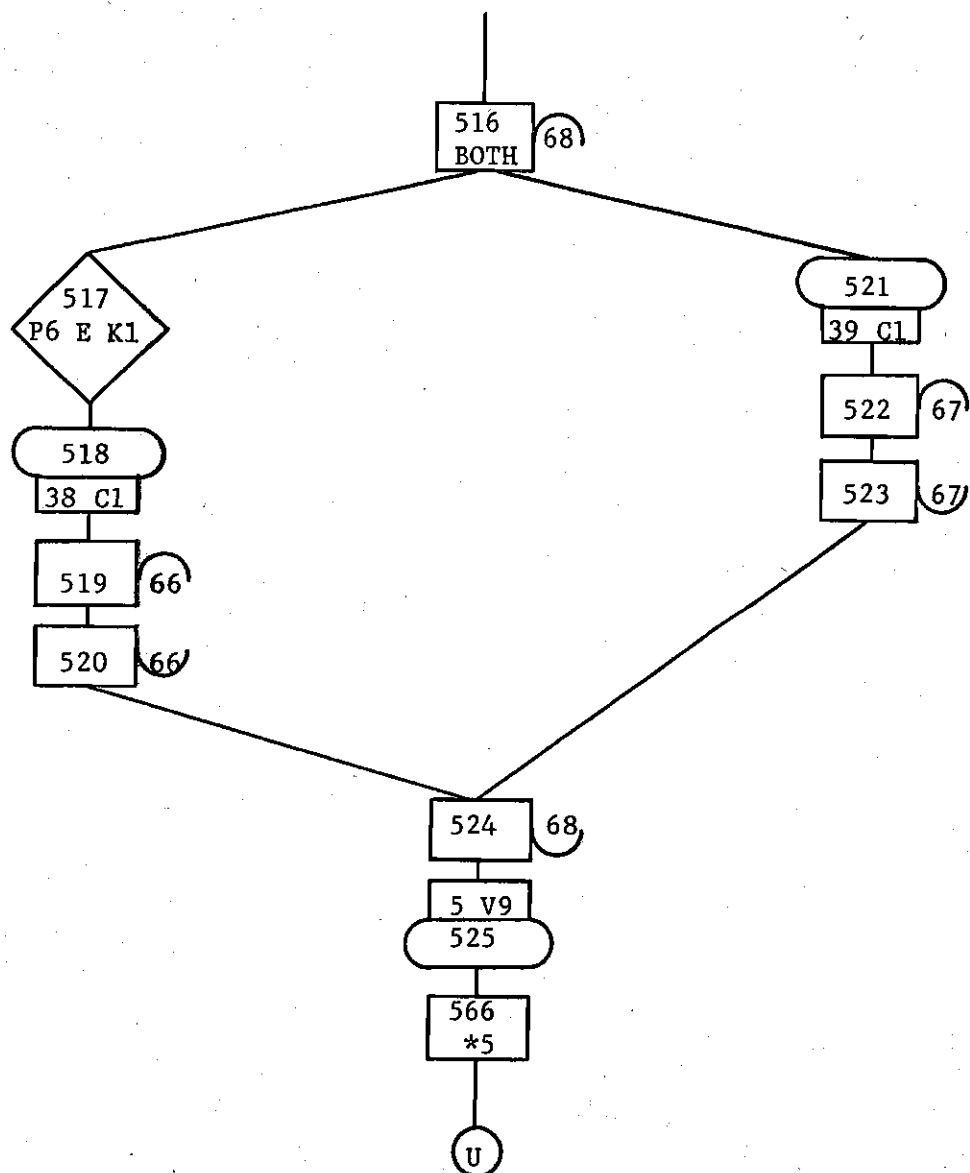


Figure 26. Concluded

## APPENDIX E

## GPSS II SIMULATION LANGUAGE

General Purpose Systems Simulator II is a special purpose simulation language which requires little or no previous programming experience to use (24). The language is ideally suited for simulating queueing flow problems. Transactions, representing units of traffic, are created and flow through the block diagram, which represents the system being simulated. The model of the system is constructed through the use of a flow chart which traces the movement of transactions from one block of the system to another. The blocks describe some specific step or response of the system.

Transactions are initiated by GENERATE or ORIGINATE blocks. These blocks enable one to initiate a specific number of transactions, to select the time the first transaction enters the system, to designate transaction interarrival times, and to assign transaction priorities.

The routing from a block is depicted by one or more straight lines drawn from the block to its successors. A block specifies the next block to which a transaction is to be sent upon completion of the designated action time at the block. Various selection modes are available that provide considerable flexibility in this routing.

Traffic movement--the movement of transactions through the block diagram--is controlled by a program clock. Each event occurs at a designated time. The program keeps a "current events" and "future events" list

and moves transactions through the system in the correct time sequence. An event which is scheduled to occur at a specific time is processed until a delay or all events scheduled at that time have been completed. The master clock is incremented to the next scheduled event and the process continues until there are no more events to process.

While moving through a system, transactions are operated on or influenced by the equipment in the system. This equipment is represented by blocks, facilities, and storages.

Table 15. GPSS II System Representations

Type of System	Transaction	Facility	Storage
River Crossing Operation	Vehicle	Single Vehicle Load Raft	Multiple Vehicle Load Raft

Facilities may be used by one transaction; storages may be used by any preset number of transactions. The HOLD, SEIZE, and RELEASE blocks handle single transactions and are called unit processing elements. A raft may be represented by a HOLD block. One transaction (vehicle) enters the block if not occupied and is delayed for a time which simulates the raft's occupancy. The SEIZE and RELEASE block's use is similar to that of the HOLD block.

The STORE, ENTER, and LEAVE blocks are the batch processing elements analogous to the unit processing element blocks. A STORE block with a capacity of four could represent a large raft capable of carrying four

vehicles. Transactions (vehicles) enter the STORE block until the capacity is reached and are delayed for a time which simulates the raft's occupancy.

Transactions refused entry to a block form queues. The queues are simulated by the QUEUE block which maintains statistics on the average queue delay, number of entries, and other pertinent information. These statistics are printed in a special section of the computer printout at the end of the simulation run.

TERMINATE blocks remove transactions from the system. As a transaction enters this block, the total number of transactions in the system is decremented by one.

Various statistics are constantly maintained by the program and, like the queue statistics, are printed out at the end of the run. Some of these statistics are storage utilization data, facility utilization data, number of transactions in the system, and the average length of time a transaction spends in the system. Detailed information on the UNIVAC 1108 GPSS II system can be found in (12).

**APPENDIX F****REPRESENTATIVE MILITARY SYMBOLS**



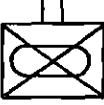
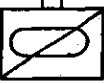
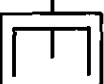


	1-77	Task force, 1st Battalion, 77th Infantry (Mechanized)
	1-4	Task force, 1st Battalion, 4th Armor
	1-76(-)	1st Battalion, 76th Infantry (Mechanized) (The (-) indicate one or more companies have been detached from the battalion.)
	1-23	1st Squadron, 23rd Armored Cavalry
A 	52	A Company, 52nd Engineer Battalion
1 	52	1st Brigade, 52nd Mechanized Division
	1-40	1st Battalion, 40th Artillery

Figure 27. Representative Military Symbols



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